



PREDICTOR/ESTIMATOR COMPUTATIONS UNDER A CONSTRAINED MULTIVARIATE LINEAR MODEL AND SOME RELATED REDUCED MODELS

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Abstract. This study deals with basic prediction/estimation issues involving a constrained multivariate linear model (CMLM) and some related reduced models. By reparameterizing these models, the authors create unconstrained multivariate linear models (UMLMs). After that, the authors use some quadratic matrix optimization methods to derive analytical formulas for computing the best linear unbiased predictors/estimators (BLUPs/BLUEs) of all unknown parameter matrices. This provides a broad perspective on BLUPs.

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1. INTRODUCTION

As follows, we introduce the notations that will be used throughout this study. We will write $\Gamma \in \mathbb{R}_{k,t}$ if Γ is a $k \times t$ real matrix, $\Gamma \in \mathbb{R}_k^s$ if $\Gamma \in \mathbb{R}_{k,k}$ and is symmetric, and $\Gamma \in \mathbb{R}_k^{\geq}$ if $\Gamma \in \mathbb{R}_k^s$ and is positive semi-definite. We will use Γ' , $\mathcal{C}(\Gamma)$, and $r(\Gamma)$ as symbols to present the transpose, the column space, and the rank of $\Gamma \in \mathbb{R}_{k,t}$, respectively. $\Gamma^\perp = \mathbf{I}_k - \Gamma\Gamma^+$ and $\mathbf{F}_\Gamma = \mathbf{I}_t - \Gamma^+\Gamma$ stand for orthogonal projectors, where $\mathbf{I}_k \in \mathbb{R}_k^s$ and $\mathbf{I}_t \in \mathbb{R}_t^s$ are the identity matrices and Γ^+ is the Moore–Penrose generalized inverse of $\Gamma \in \mathbb{R}_{k,t}$. The symbol $i_+(\Gamma)$ represents positive inertia of $\Gamma \in \mathbb{R}_k^s$. The vectorization operation (vec operation) of a matrix $\Gamma = [\gamma_1, \dots, \gamma_t]$ is defined to be $\vec{\Gamma} = [\gamma_1', \dots, \gamma_t']'$, where $\gamma_1, \dots, \gamma_t$ are the columns of $\Gamma \in \mathbb{R}_{k,t}$. A well-known property on the vec operation of a triple matrix product is $\vec{\Gamma_1 \Lambda \Gamma_2} = (\Gamma_2' \otimes \Gamma_1) \vec{\Lambda}$ for matrices Λ , Γ_1 , and Γ_2 .

One of the most frequently used essential statistical tools, both in theory and in practice, is linear models (LMs). The multivariate LM (MLM) is a generalization of the univariate LM, which normally means that a response variable on a given set of regressors is regressed to several response variables on regressors. There may be

certain restrictions on unknown parameters that are often added to model assumptions in statistical theory and its applications. Such restrictions arise in some cases, such as linear hypothesis testing on parameters. In such cases, MLM becomes a constrained MLM (CMLM).

In the present study, we consider a CMLM, formulated by

$$\mathcal{M} : \mathbf{Y} = \mathbf{X}\Theta + \Psi = \mathbf{X}_1\Theta_1 + \mathbf{X}_2\Theta_2 + \Psi, \mathbf{C}\Theta = \mathbf{C}_1\Theta_1 + \mathbf{C}_2\Theta_2 = \mathbf{D}, \quad (1.1)$$

where $\mathbf{Y} \in \mathbb{R}_{n,m}$ is a matrix of observable dependent variables, $\mathbf{X} = [\mathbf{X}_1, \mathbf{X}_2] \in \mathbb{R}_{n,p}$ with $\mathbf{X}_i \in \mathbb{R}_{n,p_i}$, $\mathbf{C} = [\mathbf{C}_1, \mathbf{C}_2] \in \mathbb{R}_{s,p}$ with $\mathbf{C}_i \in \mathbb{R}_{s,p_i}$, and $\mathbf{D} \in \mathbb{R}_{s,m}$ are known matrices of arbitrary ranks, $\Theta = [\Theta'_1, \Theta'_2] \in \mathbb{R}_{p,m}$ with $\Theta_i \in \mathbb{R}_{p_i,m}$ is a matrix of fixed but unknown parameters, $i = 1, 2$, $p_1 + p_2 = p$, $\Psi \in \mathbb{R}_{n,m}$ is a matrix of randomly distributed error terms with mean matrix $E(\Psi) = \mathbf{0}$ and dispersion matrix $D(\vec{\Psi}) = \sigma^2(\Sigma_2 \otimes \Sigma_1)$, where $\Sigma_1 = (\sigma_{1ij}) \in \mathbb{R}_n^{\times}$, $\Sigma_2 = (\sigma_{2ij}) \in \mathbb{R}_m^{\times}$, and σ^2 is an unknown positive number. Further, $\Sigma_2 \otimes \Sigma_1$ means that $\vec{\Psi}$ has a Kronecker product structured covariance matrix.

A CMLM in partitioned form is usually considered for statistical inferences of partial parameters in regression analysis. Model transformations are a common occurrence, and we utilize them to extrapolate and infer the model's parameter space. One of the simplest transformations is a linear transformation, which is achieved by premultiplying both sides of (1.1) by two matrices \mathbf{X}_1^\perp and \mathbf{X}_2^\perp to yield the following pair of transformed CMLMs:

$$\begin{aligned} \mathcal{M}_1 : \mathbf{X}_2^\perp \mathbf{Y} &= \mathbf{X}_2^\perp \mathbf{X}_1 \Theta_1 + \mathbf{X}_2^\perp \Psi, \mathbf{C}_1 \Theta_1 = \mathbf{D}, \\ E(\mathbf{X}_2^\perp \Psi) &= \mathbf{0}, D(\mathbf{X}_2^\perp \Psi) = \sigma^2(\Sigma_2 \otimes \mathbf{X}_2^\perp \Sigma_1 \mathbf{X}_2^\perp) \end{aligned} \quad (1.2)$$

and

$$\begin{aligned} \mathcal{M}_2 : \mathbf{X}_1^\perp \mathbf{Y} &= \mathbf{X}_1^\perp \mathbf{X}_2 \Theta_2 + \mathbf{X}_1^\perp \Psi, \mathbf{C}_2 \Theta_2 = \mathbf{D}, \\ E(\mathbf{X}_1^\perp \Psi) &= \mathbf{0}, D(\mathbf{X}_1^\perp \Psi) = \sigma^2(\Sigma_2 \otimes \mathbf{X}_1^\perp \Sigma_1 \mathbf{X}_1^\perp), \end{aligned} \quad (1.3)$$

which are frequently referred to as correctly-reduced versions of \mathcal{M} in (1.1); for the related expositions, see, [14]. Each of the model equations in \mathcal{M}_1 and \mathcal{M}_2 is not equal to the whole model equation in \mathcal{M} due to the two linear transformations $\mathbf{X}_1^\perp \mathbf{Y}$ and $\mathbf{X}_2^\perp \mathbf{Y}$ are unique. It is advantageous to formulate \mathcal{M}_1 and \mathcal{M}_2 since they do not contain the partial parameter matrices Θ_1 and Θ_2 found in \mathcal{M} . As a result, using \mathcal{M}_1 and \mathcal{M}_2 , we may estimate Θ_1 and Θ_2 in \mathcal{M} separately.

In many cases, we are forced to use these derived models in the hopes that the inference outcomes obtained from \mathcal{M}_1 and \mathcal{M}_2 are equal to those that would correspond to \mathcal{M} . The linear sufficiency problem, initially stated by [2] and taken into consideration in the statistical literature, is the search for relationships between estimators under original models and their reduced models.

We can take the following matrix into consideration in order to develop some results on predictors of all unknown matrices under \mathcal{M} .

$$\begin{aligned}\Phi &= \mathbf{H}\Theta + \mathbf{J}\Psi = \mathbf{H}_1\Theta_1 + \mathbf{H}_2\Theta_2 + \mathbf{J}\Psi, \text{ or,} \\ \vec{\Phi} &= (\mathbf{I}_m \otimes \mathbf{H}) \vec{\Theta} + (\mathbf{I}_m \otimes \mathbf{J}) \vec{\Psi} \\ &= (\mathbf{I}_m \otimes \mathbf{H}_1) \vec{\Theta}_1 + (\mathbf{I}_m \otimes \mathbf{H}_2) \vec{\Theta}_2 + (\mathbf{I}_m \otimes \mathbf{J}) \vec{\Psi},\end{aligned}\tag{1.4}$$

in accordance with the partition considered in (1.1) for given matrices $\mathbf{H} = [\mathbf{H}_1, \mathbf{H}_2] \in \mathbb{R}_{k,p}$ with $\mathbf{H}_i \in \mathbb{R}_{k,p_i}$, $\Theta = [\Theta_1, \Theta_2] \in \mathbb{R}_{p,m}$ with $\Theta_i \in \mathbb{R}_{p_i,m}$, $i = 1, 2$, $p_1 + p_2 = p$, and $\mathbf{J} \in \mathbb{R}_{k,n}$.

For statistical inference under the CMLM and its two reduced models, in addition to (1.4), we are also able to create the next three matrices linked to the constrained reduced models \mathcal{M}_i , $i = 1, 2$, respectively.

$$\begin{aligned}\Phi_1 &= \mathbf{H}_1\Theta_1 + \mathbf{J}\Psi = [\mathbf{H}_1, \mathbf{0}] \Theta + \mathbf{J}\Psi, \text{ or,} \\ \vec{\Phi}_1 &= (\mathbf{I}_m \otimes \mathbf{H}_1) \vec{\Theta}_1 + (\mathbf{I}_m \otimes \mathbf{J}) \vec{\Psi},\end{aligned}\tag{1.5}$$

and

$$\begin{aligned}\Phi_2 &= \mathbf{H}_2\Theta_2 + \mathbf{J}\Psi = [\mathbf{0}, \mathbf{H}_2] \Theta + \mathbf{J}\Psi, \text{ or,} \\ \vec{\Phi}_2 &= (\mathbf{I}_m \otimes \mathbf{H}_2) \vec{\Theta}_2 + (\mathbf{I}_m \otimes \mathbf{J}) \vec{\Psi}.\end{aligned}\tag{1.6}$$

Then, we obtain

$$\begin{aligned}E(\Phi) &= \mathbf{H}\Theta, D(\vec{\Phi}) = \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \Sigma_1)(\mathbf{I}_m \otimes \mathbf{J})', \\ \text{cov}(\vec{\Phi}, \vec{Y}) &= \text{cov}(\vec{\Phi}_1, \vec{Y}) = \text{cov}(\vec{\Phi}_2, \vec{Y}) = \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \Sigma_1),\end{aligned}\tag{1.7}$$

$$\begin{aligned}E(\Phi_1) &= \mathbf{H}_1\Theta_1, D(\vec{\Phi}_1) = \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \Sigma_1)(\mathbf{I}_m \otimes \mathbf{J})', \\ \text{cov}(\vec{\Phi}_1, \vec{X}_1^\perp \vec{Y}) &= \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \mathbf{X}_1^\perp \Sigma_1 \mathbf{X}_1^\perp), \\ \text{cov}(\vec{\Phi}_1, \vec{X}_2^\perp \vec{Y}) &= \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \mathbf{X}_2^\perp \Sigma_1 \mathbf{X}_2^\perp),\end{aligned}\tag{1.8}$$

and

$$\begin{aligned}E(\Phi_2) &= \mathbf{H}_2\Theta_2, D(\vec{\Phi}_2) = \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \Sigma_1)(\mathbf{I}_m \otimes \mathbf{J})', \\ \text{cov}(\vec{\Phi}_2, \vec{X}_1^\perp \vec{Y}) &= \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \mathbf{X}_1^\perp \Sigma_1 \mathbf{X}_1^\perp), \\ \text{cov}(\vec{\Phi}_2, \vec{X}_2^\perp \vec{Y}) &= \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \mathbf{X}_2^\perp \Sigma_1 \mathbf{X}_2^\perp).\end{aligned}\tag{1.9}$$

Note that the linear restriction equations $\mathbf{C}\Theta = \mathbf{D}$ and $\mathbf{C}_i\Theta_i = \mathbf{D}$ in \mathcal{M} and \mathcal{M}_i , $i = 1, 2$ are consistent, respectively. The general solutions of these matrix equations can be written as $\Theta = \mathbf{C}^+\mathbf{D} + \mathbf{F}_C\Omega$ and $\Theta_i = \mathbf{C}_i^+\mathbf{D} + \mathbf{F}_{C_i}\Omega_i$, respectively, where $\Omega \in \mathbb{R}_{p,m}$ and $\Omega_i \in \mathbb{R}_{p_i,m}$ are reparameterized but arbitrary matrices. Substituting these solutions

into the model equations in \mathcal{M} and \mathcal{M}_i , $i = 1, 2$, yields the following reparameterized MLMs:

$$\mathcal{R} : \Upsilon = \mathbf{X}\mathbf{F}_C\Omega + \Psi, \quad (1.10)$$

$$\mathcal{R}_1 : \mathbf{X}_2^\perp \Upsilon_1 = \mathbf{X}_2^\perp \mathbf{X}_1 \mathbf{F}_{C_1} \Omega_1 + \mathbf{X}_2^\perp \Psi, \quad (1.11)$$

$$\mathcal{R}_2 : \mathbf{X}_1^\perp \Upsilon_2 = \mathbf{X}_1^\perp \mathbf{X}_2 \mathbf{F}_{C_2} \Omega_2 + \mathbf{X}_1^\perp \Psi, \quad (1.12)$$

where $\Upsilon = \mathbf{Y} - \mathbf{X}\mathbf{C}^+\mathbf{D}$ and $\Upsilon_i = \mathbf{Y} - \mathbf{X}_i\mathbf{C}_i^+\mathbf{D}$, $i = 1, 2$, thus, predictions under \mathcal{M} and \mathcal{M}_i can be derived from \mathcal{R} and \mathcal{R}_i , $i = 1, 2$, respectively. Correspondingly, Φ in (1.4) and Φ_i in (1.5)-(1.6) become the following reparameterized matrices:

$$\begin{aligned} \Delta &= \mathbf{H}\mathbf{F}_C\Omega + \mathbf{J}\Psi = \mathbf{H}_1\mathbf{F}_{C_1}\Omega_1 + \mathbf{H}_2\mathbf{F}_{C_2}\Omega_2 + \mathbf{J}\Psi, \text{ or,} \\ \vec{\Delta} &= (\mathbf{I}_m \otimes \mathbf{H}\mathbf{F}_C) \vec{\Omega} + (\mathbf{I}_m \otimes \mathbf{J}) \vec{\Psi}, \end{aligned} \quad (1.13)$$

$$\begin{aligned} &= (\mathbf{I}_m \otimes \mathbf{H}_1\mathbf{F}_{C_1}) \vec{\Omega}_1 + (\mathbf{I}_m \otimes \mathbf{H}_2\mathbf{F}_{C_2}) \vec{\Omega}_2 + (\mathbf{I}_m \otimes \mathbf{J}) \vec{\Psi}, \\ \Delta_1 &= \mathbf{H}_1\mathbf{F}_{C_1}\Omega_1 + \mathbf{J}\Psi = [\mathbf{H}_1\mathbf{F}_{C_1}, \quad \mathbf{0}] \Omega + \mathbf{J}\Psi, \text{ or,} \\ \vec{\Delta}_1 &= (\mathbf{I}_m \otimes \mathbf{H}_1\mathbf{F}_{C_1}) \vec{\Omega}_1 + (\mathbf{I}_m \otimes \mathbf{J}) \vec{\Psi}, \end{aligned} \quad (1.14)$$

and

$$\begin{aligned} \Delta_2 &= \mathbf{H}_2\mathbf{F}_{C_2}\Omega_2 + \mathbf{J}\Psi = [\mathbf{0}, \quad \mathbf{H}_2\mathbf{F}_{C_2}] \Omega + \mathbf{J}\Psi, \text{ or,} \\ \vec{\Delta}_2 &= (\mathbf{I}_m \otimes \mathbf{H}_2\mathbf{F}_{C_2}) \vec{\Omega}_2 + (\mathbf{I}_m \otimes \mathbf{J}) \vec{\Psi}, \end{aligned} \quad (1.15)$$

where $\Delta = \Phi - \mathbf{H}\mathbf{C}^+\mathbf{D}$ and $\Delta_i = \Phi_i - \mathbf{H}_i\mathbf{C}_i^+\mathbf{D}$, $i = 1, 2$. Then, we obtain

$$\begin{aligned} E(\Delta) &= \mathbf{H}\mathbf{F}_C\Omega, \quad D(\vec{\Delta}) = \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \Sigma_1)(\mathbf{I}_m \otimes \mathbf{J})', \\ \text{cov}(\vec{\Delta}, \vec{\Upsilon}) &= \text{cov}(\vec{\Delta}_1, \vec{\Upsilon}) = \text{cov}(\vec{\Delta}_2, \vec{\Upsilon}) = \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \Sigma_1). \end{aligned} \quad (1.16)$$

$$\begin{aligned} E(\Delta_1) &= \mathbf{H}_1\mathbf{F}_{C_1}\Omega_1, \quad D(\vec{\Delta}_1) = \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \Sigma_1)(\mathbf{I}_m \otimes \mathbf{J})', \\ \text{cov}(\vec{\Delta}_1, \vec{\mathbf{X}}_2^\perp \Upsilon_1) &= \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \mathbf{X}_2^\perp \Sigma_1 \mathbf{X}_2^\perp), \\ \text{cov}(\vec{\Delta}_1, \vec{\mathbf{X}}_1^\perp \Upsilon_2) &= \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \mathbf{X}_1^\perp \Sigma_1 \mathbf{X}_1^\perp). \end{aligned} \quad (1.17)$$

$$\begin{aligned} E(\Delta_2) &= \mathbf{H}_2\mathbf{F}_{C_2}\Omega_2, \quad D(\vec{\Delta}_2) = \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \Sigma_1)(\mathbf{I}_m \otimes \mathbf{J})', \\ \text{cov}(\vec{\Delta}_2, \vec{\mathbf{X}}_2^\perp \Upsilon_1) &= \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \mathbf{X}_2^\perp \Sigma_1 \mathbf{X}_2^\perp), \\ \text{cov}(\vec{\Delta}_2, \vec{\mathbf{X}}_1^\perp \Upsilon_2) &= \sigma^2(\mathbf{I}_m \otimes \mathbf{J})(\Sigma_2 \otimes \mathbf{X}_1^\perp \Sigma_1 \mathbf{X}_1^\perp). \end{aligned} \quad (1.18)$$

In the present study, we consider the CMLM in (1.1) and some related reduced models in (1.2) and (1.3) with general assumptions. After reparameterizing these models given as \mathcal{R} and \mathcal{R}_i , $i = 1, 2$ in (1.10)-(1.12), we derive analytic formulas for computing the best linear unbiased predictor/estimator (BLUP/BLUE).

In the statistical literature, LMs with exact restrictions on unknown parameters have been studied under various model assumptions, see e.g., [3, 5, 8–10, 12, 13, 18, 20, 23, 25]. We may refer to the studies [6, 7, 11, 19, 24], among others, in which both an CMLM and unconstrained MLM (UMLM) on unknown parameters has been considered from different perspectives.

2. PRELIMINARY

For the models that are taken into consideration in the work, consistency is given the first definition; see [17]. In the second definition, predictability is given; see [1]. The last definition is related to the BLUP and the BLUE.

Definition 1. The model \mathcal{R} is consistent $\iff Y \in \mathcal{C}[\mathbf{X}\mathbf{F}_C, \Sigma_2 \otimes \Sigma_1]$ holds with probability (wp) 1.

For reduced models \mathcal{R}_i , $i = 1, 2$, it is possible to make the following consistency assumptions in accordance with Definition 1.

- (1) \mathcal{R}_1 is consistent $\iff \mathbf{X}_2^\perp \mathbf{Y}_1 \in \mathcal{C}[\mathbf{X}_2^\perp \mathbf{X}_1 \mathbf{F}_{C_1}, \Sigma_2 \otimes \mathbf{X}_2^\perp \Sigma_1 \mathbf{X}_2^\perp]$ holds wp 1.
- (2) \mathcal{R}_2 is consistent $\iff \mathbf{X}_1^\perp \mathbf{Y}_2 \in \mathcal{C}[\mathbf{X}_1^\perp \mathbf{X}_2 \mathbf{F}_{C_2}, \Sigma_2 \otimes \mathbf{X}_1^\perp \Sigma_1 \mathbf{X}_1^\perp]$ holds wp 1.

We note that \mathcal{R}_i are consistent under the assumption of consistency of \mathcal{R} , $i = 1, 2$.

Definition 2. The predictability requirement of matrix Δ under \mathcal{R} is described as holding the inclusion $\mathcal{C}((\mathbf{H}\mathbf{F}_C)') \subseteq \mathcal{C}((\mathbf{X}\mathbf{F}_C)')$. This requirement also corresponds to the estimability of $\mathbf{H}\mathbf{F}_C\Omega$ under \mathcal{R} . Further, the matrix Ψ is always predictable under \mathcal{R} .

For models \mathcal{R} and \mathcal{R}_i , $i = 1, 2$, the following predictability/estimability requirements of Δ_i and its special cases are given in accordance with Definition 2. Let $\hat{\mathbf{H}}_1 = [\mathbf{H}_1 \mathbf{F}_{C_1}, \mathbf{0}]$ and $\hat{\mathbf{H}}_2 = [\mathbf{0}, \mathbf{H}_2 \mathbf{F}_{C_2}]$. Then

- (1) Δ_1 is predictable by \mathbf{Y} in $\mathcal{R} \iff \mathcal{C}(\hat{\mathbf{H}}_1') \subseteq \mathcal{C}((\mathbf{X}\mathbf{F}_C)')$.
- (2) Δ_2 is predictable by \mathbf{Y} in $\mathcal{R} \iff \mathcal{C}(\hat{\mathbf{H}}_2') \subseteq \mathcal{C}((\mathbf{X}\mathbf{F}_C)')$.
- (3) Δ_1 is predictable by $\mathbf{X}_2^\perp \mathbf{Y}_1$ in $\mathcal{R}_1 \iff \mathcal{C}((\mathbf{H}_1 \mathbf{F}_{C_1})') \subseteq \mathcal{C}((\mathbf{X}_2^\perp \mathbf{X}_1 \mathbf{F}_{C_1})')$.
- (4) Δ_2 is predictable by $\mathbf{X}_1^\perp \mathbf{Y}_2$ in $\mathcal{R}_2 \iff \mathcal{C}((\mathbf{H}_2 \mathbf{F}_{C_2})') \subseteq \mathcal{C}((\mathbf{X}_1^\perp \mathbf{X}_2 \mathbf{F}_{C_2})')$.

We note that if Δ_i is predictable under \mathcal{R}_i , $i = 1, 2$, then it is predictable under \mathcal{R} .

Definition 3. If a matrix $\mathbf{K} \in \mathbb{R}_{k,n}$ and $\mathbf{K}_1 \in \mathbb{R}_{k,m}$, or $\hat{\mathbf{K}} \in \mathbb{R}_{km,nm}$ and $\hat{\mathbf{K}}_1 \in \mathbb{R}_{km,1}$ exists with

$$\begin{aligned} D(\overrightarrow{\mathbf{K}\mathbf{Y} + \mathbf{K}_1 - \Phi}) &= \min \text{ s.t. } E(\mathbf{K}\mathbf{Y} + \mathbf{K}_1 - \Phi) = \mathbf{0}, \text{ or,} \\ D(\overrightarrow{\hat{\mathbf{K}}\hat{\mathbf{Y}} + \hat{\mathbf{K}}_1 - \hat{\Phi}}) &= \min \text{ s.t. } E(\hat{\mathbf{K}}\hat{\mathbf{Y}} + \hat{\mathbf{K}}_1 - \hat{\Phi}) = \mathbf{0} \end{aligned} \quad (2.1)$$

in the Löwner partial ordering (LPO), the linear statistic $\mathbf{K}\mathbf{Y} + \mathbf{K}_1$ is said to be the BLUP of Φ and is represented by $\mathbf{K}\mathbf{Y} + \mathbf{K}_1 = \text{BLUP}_{\mathcal{M}}(\mathbf{H}\Theta + \mathbf{J}\Psi)$. If $\mathbf{J} = \mathbf{0}$ in Φ ,

$\mathbf{KY} + \mathbf{K}_1$ is the well-known the BLUE of $\mathbf{H}\Theta$, represented by $\text{BLUE}_{\mathcal{M}}(\mathbf{H}\Theta)$, under \mathcal{M} .

Suppose that Δ or $\vec{\Delta}$ in (1.13) is predictable under \mathcal{R} . \mathbf{KY} is defined to be the BLUP of Δ if there exists \mathbf{KY} such that

$$D(\overrightarrow{\mathbf{KY} - \Delta}) = \min \text{ s.t. } E(\mathbf{KY} - \Delta) = \mathbf{0} \quad (2.2)$$

holds in the LPO, and is represented by

$$\mathbf{KY} = \text{BLUP}_{\mathcal{R}}(\Delta) = \text{BLUP}_{\mathcal{R}}(\mathbf{H}\mathbf{F}_c\Omega + \mathbf{J}\Psi).$$

If $\mathbf{J} = \mathbf{0}$ in Δ , \mathbf{KY} corresponds the BLUE of $\mathbf{H}\mathbf{F}_c\Omega$, represented by $\text{BLUE}_{\mathcal{R}}(\mathbf{H}\mathbf{F}_c\Omega)$. Further, if $\mathbf{H} = \mathbf{0}$ and $\mathbf{J} = \mathbf{I}_n$ in Δ , \mathbf{KY} corresponds the BLUP of Ψ , i.e., $\text{BLUP}_{\mathcal{R}}(\Psi)$, under \mathcal{R} .

The following results are given in accordance with Definition 3. Let Δ_1 or $\vec{\Delta}_1$ be predictable under \mathcal{R} and \mathcal{R}_i , $i = 1, 2$. Then

- (1) $\text{BLUP}_{\mathcal{R}}(\Delta_1) = \mathbf{K}_1\Upsilon \iff D(\overrightarrow{\mathbf{K}_1\Upsilon - \Delta_1}) = \min \text{ s.t. } E(\mathbf{K}_1\Upsilon - \Delta_1) = \mathbf{0}.$
- (2) $\text{BLUP}_{\mathcal{R}}(\Delta_2) = \mathbf{K}_2\Upsilon \iff D(\overrightarrow{\mathbf{K}_2\Upsilon - \Delta_2}) = \min \text{ s.t. } E(\mathbf{K}_2\Upsilon - \Delta_2) = \mathbf{0}.$
- (3) $\text{BLUP}_{\mathcal{R}_1}(\Delta_1) = \mathbf{G}_1\mathbf{X}_2^\perp\Upsilon_1$
 $\iff D(\overrightarrow{\mathbf{G}_1\mathbf{X}_2^\perp\Upsilon_1 - \Delta_1}) = \min \text{ s.t. } E(\mathbf{G}_1\mathbf{X}_2^\perp\Upsilon_1 - \Delta_1) = \mathbf{0}.$
- (4) $\text{BLUP}_{\mathcal{R}_2}(\Delta_2) = \mathbf{G}_2\mathbf{X}_1^\perp\Upsilon_2$
 $\iff D(\overrightarrow{\mathbf{G}_2\mathbf{X}_1^\perp\Upsilon_2 - \Delta_2}) = \min \text{ s.t. } E(\mathbf{G}_2\mathbf{X}_1^\perp\Upsilon_2 - \Delta_2) = \mathbf{0}.$

Finally, we give the following two lemmas, which are required in the sections that follow. For the first lemma; see, [15], and for the last one; see, [20].

Lemma 1. *The linear matrix equation $\mathbf{H}\mathbf{X} = \mathbf{D}$ is consistent $\Leftrightarrow \mathbf{r}[\mathbf{H}, \mathbf{D}] = \mathbf{r}(\mathbf{H})$, or equivalently, $\mathbf{H}\mathbf{H}^+\mathbf{D} = \mathbf{D}$. Then, the general solution of this equation can be written as $\mathbf{X} = \mathbf{H}^+\mathbf{D} + (\mathbf{I} - \mathbf{H}^+\mathbf{H})\mathbf{V}$, where \mathbf{V} is an arbitrary matrix.*

Lemma 2. *Let $\mathbf{B} \in \mathbb{R}_{m,p}$, $\mathbf{A} \in \mathbb{R}_{n,p}$ be given matrices, and let $\mathbf{Q} \in \mathbb{R}_n^{\succ}$. Suppose that there exists $\mathbf{X}_0 \in \mathbb{R}_{m,n}$ such that $\mathbf{X}_0\mathbf{B} = \mathbf{A}$. Then the maximal positive inertia of $\mathbf{X}_0\mathbf{Q}\mathbf{X}_0' - \mathbf{X}\mathbf{Q}\mathbf{X}'$ subject to all solutions of $\mathbf{X}\mathbf{B} = \mathbf{A}$ is*

$$\max_{\mathbf{X}\mathbf{B}=\mathbf{A}} i_+(\mathbf{X}_0\mathbf{Q}\mathbf{X}_0' - \mathbf{X}\mathbf{Q}\mathbf{X}') = \mathbf{r} \begin{bmatrix} \mathbf{X}_0\mathbf{Q} \\ \mathbf{B}' \end{bmatrix} - \mathbf{r}(\mathbf{B}) = \mathbf{r}(\mathbf{X}_0\mathbf{Q}\mathbf{B}^\perp).$$

Hence a solution \mathbf{X}_0 of $\mathbf{X}_0\mathbf{B} = \mathbf{A}$ exists such that $\mathbf{X}_0\mathbf{Q}\mathbf{X}_0' \preccurlyeq \mathbf{X}\mathbf{Q}\mathbf{X}'$ holds for all solutions of $\mathbf{X}\mathbf{B} = \mathbf{A} \Leftrightarrow$ both the equations $\mathbf{X}_0\mathbf{B} = \mathbf{A}$ and $\mathbf{X}_0\mathbf{Q}\mathbf{B}^\perp = \mathbf{0}$ are satisfied by \mathbf{X} .

3. BLUPS/BLUES UNDER A CMLM WITH SOME RELATED REDUCED MODELS

The following theorems, respectively, are collections of the basic findings on BLUP of Δ and Δ_i in (1.10)-(1.12) and its sub-cases. These theorems use a method described in [4]. For different approaches; see, e.g., [16, 22].

Theorem 1. Suppose that Δ is predictable under \mathcal{R} in (1.11). For Δ under \mathcal{R} , let $\mathbf{K}\Upsilon$ and $\mathbf{L}\Upsilon$ be unbiased linear predictors. Then the maximal positive inertia of $D(\overrightarrow{\mathbf{K}\Upsilon - \Delta}) - D(\overrightarrow{\mathbf{L}\Upsilon - \Delta})$ subject to $\mathbf{L}\mathbf{X}\mathbf{F}_C = \mathbf{H}\mathbf{F}_C$ is

$$\max_{E(\mathbf{L}\Upsilon - \Delta) = \mathbf{0}} i_+(D(\overrightarrow{\mathbf{K}\Upsilon - \Delta}) - D(\overrightarrow{\mathbf{L}\Upsilon - \Delta})) = r \left(\begin{bmatrix} \mathbf{K}, & -\mathbf{I}_k \end{bmatrix} \begin{bmatrix} \mathbf{I}_n \\ \mathbf{J} \end{bmatrix} \text{cov}(\Upsilon) \begin{bmatrix} \mathbf{I}_n \\ \mathbf{J} \end{bmatrix}' \begin{bmatrix} \mathbf{X}\mathbf{F}_C \\ \mathbf{H}\mathbf{F}_C \end{bmatrix}^\perp \right). \quad (3.1)$$

Hence,

$$\begin{aligned} D(\overrightarrow{\mathbf{K}\Upsilon - \Delta}) &= \min \text{ s.t. } E(\mathbf{K}\Upsilon - \Delta) = \mathbf{0} \Leftrightarrow \mathbf{K}\Upsilon = \text{BLUP}_{\mathcal{R}}(\Delta) \\ &\Leftrightarrow \mathbf{K} \begin{bmatrix} \mathbf{X}\mathbf{F}_C, & \Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp \end{bmatrix} = \begin{bmatrix} \mathbf{H}\mathbf{F}_C, & \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp \end{bmatrix}. \end{aligned} \quad (3.2)$$

(3.2) is consistent and the BLUP of Δ under \mathcal{R} can be written as follows by considering the general solution of this equation:

$$\mathbf{K}\Upsilon = \text{BLUP}_{\mathcal{R}}(\Delta) \Leftrightarrow \mathbf{K} \begin{bmatrix} \mathbf{X}\mathbf{F}_C, & \Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp \end{bmatrix} = \begin{bmatrix} \mathbf{H}\mathbf{F}_C, & \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp \end{bmatrix}$$

and the general solution of this consistent equation can be written as

$$\begin{aligned} \text{BLUP}_{\mathcal{R}}(\Delta) &= \mathbf{K}\Upsilon = \left(\begin{bmatrix} \mathbf{H}\mathbf{F}_C, & \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp \end{bmatrix} \mathbf{W}_r^+ + \mathbf{U}_r \mathbf{W}_r^\perp \right) \Upsilon, \\ \overrightarrow{\text{BLUP}_{\mathcal{R}}(\Delta)} &= (\mathbf{I}_m \otimes \mathbf{K}) \vec{\Upsilon} \\ &= \left(\mathbf{I}_m \otimes \left(\begin{bmatrix} \mathbf{H}\mathbf{F}_C, & \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp \end{bmatrix} \mathbf{W}_r^+ + \mathbf{U}_r \mathbf{W}_r^\perp \right) \right) \vec{\Upsilon}, \end{aligned} \quad (3.3)$$

where $\mathbf{U}_r \in \mathbb{R}_{k,n}$ is an arbitrary matrix and $\mathbf{W}_r = \begin{bmatrix} \mathbf{X}\mathbf{F}_C, & \Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp \end{bmatrix}$. In particular,

$$\begin{aligned} \text{BLUE}_{\mathcal{R}}(\mathbf{H}\mathbf{F}_C\Omega) &= \mathbf{K}\Upsilon = \left(\begin{bmatrix} \mathbf{H}\mathbf{F}_C, & \mathbf{0} \end{bmatrix} \mathbf{W}_r^+ + \mathbf{U}_r \mathbf{W}_r^\perp \right) \Upsilon, \\ \overrightarrow{\text{BLUE}_{\mathcal{R}}(\mathbf{H}\mathbf{F}_C\Omega)} &= (\mathbf{I}_m \otimes \mathbf{K}) \vec{\Upsilon} \\ &= \left(\mathbf{I}_m \otimes \left(\begin{bmatrix} \mathbf{H}\mathbf{F}_C, & \mathbf{0} \end{bmatrix} \mathbf{W}_r^+ + \mathbf{U}_r \mathbf{W}_r^\perp \right) \right) \vec{\Upsilon}, \end{aligned} \quad (3.4)$$

and

$$\begin{aligned} \text{BLUP}_{\mathcal{R}}(\Psi) &= \mathbf{K}\Upsilon = \left(\begin{bmatrix} \mathbf{0}, & \Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp \end{bmatrix} \mathbf{W}_r^+ + \mathbf{U}_r \mathbf{W}_r^\perp \right) \Upsilon, \\ \overrightarrow{\text{BLUP}_{\mathcal{R}}(\Psi)} &= (\mathbf{I}_m \otimes \mathbf{K}) \vec{\Upsilon} \\ &= \left(\mathbf{I}_m \otimes \left(\begin{bmatrix} \mathbf{0}, & \Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp \end{bmatrix} \mathbf{W}_r^+ + \mathbf{U}_r \mathbf{W}_r^\perp \right) \right) \vec{\Upsilon}. \end{aligned} \quad (3.5)$$

Further, the matrix \mathbf{W}_r satisfies

$$r(\mathbf{W}_r) = r \begin{bmatrix} \mathbf{X}\mathbf{F}_C, & \Sigma_1 \end{bmatrix} \text{ and } \mathcal{C}(\mathbf{W}_r) = \mathcal{C} \begin{bmatrix} \mathbf{X}\mathbf{F}_C, & \Sigma_1 \end{bmatrix}. \quad (3.6)$$

Also, the following equalities hold.

$$\begin{aligned} D[\overrightarrow{\text{BLUP}_{\mathcal{R}}(\Delta)}] &= \sigma^2 \Sigma_2 \otimes \begin{bmatrix} \mathbf{H}\mathbf{F}_C, & \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp \end{bmatrix} \mathbf{W}_r^+ \Sigma_1 \\ &\quad \times \left(\begin{bmatrix} \mathbf{H}\mathbf{F}_C, & \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp \end{bmatrix} \mathbf{W}_r^+ \right)', \end{aligned}$$

$$\begin{aligned}
\text{cov}\{\overrightarrow{\text{BLUP}_{\mathcal{R}}(\Delta)}, \overrightarrow{\Delta}\} &= \sigma^2 \Sigma_2 \otimes [\mathbf{H}\mathbf{F}_C, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ \Sigma_1 \mathbf{J}', \\
\mathbf{D}[\overrightarrow{\Delta} - \overrightarrow{\text{BLUP}_{\mathcal{R}}(\Delta)}] &= \sigma^2 \Sigma_2 \otimes ([\mathbf{H}\mathbf{F}_C, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ - \mathbf{J}) \\
&\quad \times \Sigma_1 ([\mathbf{H}\mathbf{F}_C, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ - \mathbf{J})'.
\end{aligned} \tag{3.7}$$

Proof of Theorem 1. Suppose that $\mathbf{K}\Upsilon$ and $\mathbf{L}\Upsilon$ are two unbiased linear predictors for Δ in \mathcal{R} . Then, the expected value and covariance matrix of $\mathbf{K}\Upsilon - \Delta$ are written as

$$\mathbf{E}(\mathbf{K}\Upsilon - \Delta) = \mathbf{0} \Leftrightarrow \mathbf{K}\mathbf{X}\mathbf{F}_C = \mathbf{H}\mathbf{F}_C \Leftrightarrow [\mathbf{K}, -\mathbf{I}_k] \begin{bmatrix} \mathbf{X}\mathbf{F}_C \\ \mathbf{H}\mathbf{F}_C \end{bmatrix} = \mathbf{0} \tag{3.8}$$

and

$$\begin{aligned}
\mathbf{D}(\overrightarrow{\mathbf{K}\Upsilon - \Delta}) &= (\mathbf{I}_m \otimes (\mathbf{K} - \mathbf{J})) \text{cov}(\Psi) (\mathbf{I}_m \otimes (\mathbf{K} - \mathbf{J}))' \\
&= \sigma^2 (\mathbf{I}_m \otimes (\mathbf{K} - \mathbf{J})) (\Sigma_2 \otimes \Sigma_1) (\mathbf{I}_m \otimes (\mathbf{K} - \mathbf{J}))' \\
&= \sigma^2 \Sigma_2 \otimes (\mathbf{K} - \mathbf{J}) \Sigma_1 (\mathbf{K} - \mathbf{J})' \\
&= \sigma^2 \Sigma_2 \otimes [\mathbf{K}, -\mathbf{I}_k] \begin{bmatrix} \mathbf{I}_n \\ \mathbf{J} \end{bmatrix} \Sigma_1 \begin{bmatrix} \mathbf{I}_n \\ \mathbf{J} \end{bmatrix}' [\mathbf{K}, -\mathbf{I}_k]' := \Sigma_2 \otimes f(\mathbf{K}),
\end{aligned} \tag{3.9}$$

where

$$f(\mathbf{K}) = [\mathbf{K}, -\mathbf{I}_k] \begin{bmatrix} \mathbf{I}_n \\ \mathbf{J} \end{bmatrix} \Sigma_1 \begin{bmatrix} \mathbf{I}_n \\ \mathbf{J} \end{bmatrix}' [\mathbf{K}, -\mathbf{I}_k]'.$$

By using \mathbf{L} in place of \mathbf{K} , the equivalent formulas as in (3.8) and (3.9) may also be given for the other unbiased linear predictor $\mathbf{L}\Upsilon$ for Δ under \mathcal{R} . In order to obtain solution \mathbf{K} of the consistent linear matrix equation $\mathbf{K}\mathbf{X}\mathbf{F}_C = \mathbf{H}\mathbf{F}_C$, the matrix minimization problem described in Definition 3 for finding the BLUP of Δ under \mathcal{R} can be expressed such that

$$\Sigma_2 \otimes f(\mathbf{K}) \preceq \Sigma_2 \otimes f(\mathbf{L}) \text{ s.t. } \mathbf{L}\mathbf{X}\mathbf{F}_C = \mathbf{H}\mathbf{F}_C \tag{3.10}$$

or equivalently,

$$f(\mathbf{K}) \preceq f(\mathbf{L}) \text{ s.t. } \mathbf{L}\mathbf{X}\mathbf{F}_C = \mathbf{H}\mathbf{F}_C$$

because Σ_2 is a non-null matrix. According to Lemma 2, (3.10) is a typical constrained quadratic matrix-valued function optimization problem in the LPO. Lemma 2 gives us the basic formula for the BLUP of Δ in (3.2), and Lemma 1 gives us the expression for the BLUP of Δ under \mathcal{R} in (3.3). Setting $\mathbf{J} = \mathbf{0}$, and $\mathbf{H} = \mathbf{0}$ and $\mathbf{J} = \mathbf{I}_n$ at (3.3) yields (3.4) and (3.5), respectively. The expressions in (3.6) are well-known results; see also [21, Lemma 2.1(a)]. From (1.17) and (3.3),

$$\begin{aligned}
\mathbf{D}[\overrightarrow{\text{BLUP}_{\mathcal{R}}(\Delta)}] &= (\mathbf{I}_m \otimes \mathbf{K}) \text{cov}(\Psi) (\mathbf{I}_m \otimes \mathbf{K})' = \sigma^2 (\mathbf{I}_m \otimes \mathbf{K}) (\Sigma_2 \otimes \Sigma_1) (\mathbf{I}_m \otimes \mathbf{K})' \\
&= \sigma^2 \Sigma_2 \otimes \mathbf{K} \Sigma_1 \mathbf{K}' \\
&= \sigma^2 \Sigma_2 \otimes ([\mathbf{H}\mathbf{F}_C, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ + \mathbf{U}_r \mathbf{W}_r^\perp)
\end{aligned}$$

$$\begin{aligned}
& \times \Sigma_1 \left([\mathbf{H}\mathbf{F}_C, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ + \mathbf{U}_r \mathbf{W}_r^\perp \right)' \\
& = \sigma^2 \Sigma_2 \otimes [\mathbf{H}\mathbf{F}_C, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ \\
& \quad \times \Sigma_1 \left([\mathbf{H}\mathbf{F}_C, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ \right)', \\
\text{cov}\{\overrightarrow{\text{BLUP}_{\mathcal{R}}(\Delta)}, \overrightarrow{\Delta}\} & = (\mathbf{I}_m \otimes \mathbf{K}) \text{cov}(\Psi) (\mathbf{I}_m \otimes \mathbf{J})' \\
& = \sigma^2 (\mathbf{I}_m \otimes \mathbf{K}) (\Sigma_2 \otimes \Sigma_1) (\mathbf{I}_m \otimes \mathbf{J})' = \sigma^2 \Sigma_2 \otimes \mathbf{K} \Sigma_1 \mathbf{J}' \\
& = \sigma^2 \Sigma_2 \otimes [\mathbf{H}\mathbf{F}_C, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ \Sigma_1 \mathbf{J}', \\
D[\overrightarrow{\Delta} - \overrightarrow{\text{BLUP}_{\mathcal{R}}(\Delta)}] & = \sigma^2 \Sigma_2 \otimes \left([\mathbf{H}\mathbf{F}_C, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ + \mathbf{U}_r \mathbf{W}_r^\perp - \mathbf{J} \right) \\
& \quad \times \Sigma_1 \left([\mathbf{H}\mathbf{F}_C, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ + \mathbf{U}_r \mathbf{W}_r^\perp - \mathbf{J} \right)' \\
& = \sigma^2 \Sigma_2 \otimes ([\mathbf{H}\mathbf{F}_C, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ - \mathbf{J}) \\
& \quad \times \Sigma_1 ([\mathbf{H}\mathbf{F}_C, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ - \mathbf{J})'.
\end{aligned}$$

Thus establishing equalities in (3.7). \square

Theorem 2. Suppose that Δ_i is predictable under \mathcal{R}_i , $i = 1, 2$ in (1.11)-(1.12) (also predictable under \mathcal{R} in (1.10)). Thus, the results that follow are provided.

- (1) $\overrightarrow{\text{BLUP}_{\mathcal{R}}(\Delta_1)} = (\mathbf{I}_m \otimes ([\hat{\mathbf{H}}_1, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ + \mathbf{P}_1 \mathbf{W}_r^\perp)) \overrightarrow{\mathbf{Y}}$, where $\hat{\mathbf{H}}_1 = [\mathbf{H}_1 \mathbf{F}_{C_1}, \mathbf{0}]$, $\mathbf{W}_r = [\mathbf{X}\mathbf{F}_C, \Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp]$ and $\mathbf{P}_1 \in \mathbb{R}_{s,n}$ is an arbitrary matrix. Then,

$$\begin{aligned}
D[\overrightarrow{\text{BLUP}_{\mathcal{R}}(\Delta_1)}] & = \sigma^2 \Sigma_2 \otimes [\hat{\mathbf{H}}_1, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ \Sigma_1 \\
& \quad \times ([\hat{\mathbf{H}}_1, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+)' , \tag{3.11}
\end{aligned}$$

$$\begin{aligned}
D[\overrightarrow{\Delta_1} - \overrightarrow{\text{BLUP}_{\mathcal{R}}(\Delta_1)}] & = \sigma^2 \Sigma_2 \otimes ([\hat{\mathbf{H}}_1, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ - \mathbf{J}) \\
& \quad \times \Sigma_1 ([\hat{\mathbf{H}}_1, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ - \mathbf{J})' . \tag{3.12}
\end{aligned}$$

- (2) $\overrightarrow{\text{BLUP}_{\mathcal{R}}(\Delta_2)} = (\mathbf{I}_m \otimes ([\hat{\mathbf{H}}_2, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ + \mathbf{P}_2 \mathbf{W}_r^\perp)) \overrightarrow{\mathbf{Y}}$, where $\hat{\mathbf{H}}_2 = [\mathbf{0}, \mathbf{H}_2 \mathbf{F}_{C_2}]$, $\mathbf{W}_r = [\mathbf{X}\mathbf{F}_C, \Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp]$ and $\mathbf{P}_2 \in \mathbb{R}_{s,n}$ is an arbitrary matrix. Then,

$$\begin{aligned}
D[\overrightarrow{\text{BLUP}_{\mathcal{R}}(\Delta_2)}] & = \sigma^2 \Sigma_2 \otimes [\hat{\mathbf{H}}_2, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ \Sigma_1 \\
& \quad \times ([\hat{\mathbf{H}}_2, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+)' , \tag{3.13}
\end{aligned}$$

$$\begin{aligned}
D[\overrightarrow{\Delta_2} - \overrightarrow{\text{BLUP}_{\mathcal{R}}(\Delta_2)}] & = \sigma^2 \Sigma_2 \otimes ([\hat{\mathbf{H}}_2, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ - \mathbf{J}) \\
& \quad \times \Sigma_1 ([\hat{\mathbf{H}}_2, \mathbf{J}\Sigma_1(\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ - \mathbf{J})' . \tag{3.14}
\end{aligned}$$

- (3) $\overrightarrow{\text{BLUP}_{\mathcal{R}_1}(\Delta_1)} = (\mathbf{I}_m \otimes (\mathbf{M}_1 \mathbf{W}_{r_1}^+ + \mathbf{U}_1 \mathbf{W}_{r_1}^\perp)) \overrightarrow{\mathbf{Y}}_1$,
where $\mathbf{U}_1 \in \mathbb{R}_{s,n}$ is arbitrary matrix, $\mathbf{M}_1 = [\mathbf{H}_1 \mathbf{F}_{C_1}, \mathbf{J}\Sigma_1 \mathbf{X}_2^\perp (\mathbf{X}_2^\perp \mathbf{X}_1 \mathbf{F}_{C_1})^\perp]$

and $\mathbf{W}_{r_1} = [\mathbf{X}_2^\perp \mathbf{X}_1 \mathbf{F}_{C_1}, \quad \mathbf{X}_2^\perp \Sigma_1 \mathbf{X}_2^\perp (\mathbf{X}_2^\perp \mathbf{X}_1 \mathbf{F}_{C_1})^\perp]^\top$. Then,

$$D[\overrightarrow{\text{BLUP}_{\mathcal{R}_1}(\Delta_1)}] = \sigma^2 \Sigma_2 \otimes \mathbf{M}_1 \mathbf{W}_{r_1}^+ \mathbf{X}_2^\perp \Sigma_1 \mathbf{X}_2^\perp (\mathbf{M}_1 \mathbf{W}_{r_1}^+)', \quad (3.15)$$

$$D[\overrightarrow{\Delta_1} - \overrightarrow{\text{BLUP}_{\mathcal{R}_1}(\Delta_1)}] = \sigma^2 \Sigma_2 \otimes (\mathbf{M}_1 \mathbf{W}_{r_1}^+ \mathbf{X}_2^\perp - \mathbf{J}) \Sigma_1 (\mathbf{M}_1 \mathbf{W}_{r_1}^+ \mathbf{X}_2^\perp - \mathbf{J})'. \quad (3.16)$$

$$(4) \overrightarrow{\text{BLUP}_{\mathcal{R}_2}(\Delta_2)} = (\mathbf{I}_m \otimes (\mathbf{M}_2 \mathbf{W}_{r_2}^+ + \mathbf{U}_2 \mathbf{W}_{r_2}^\perp)) \overrightarrow{\Upsilon_2},$$

where $\mathbf{U}_2 \in \mathbb{R}_{s,n}$ is arbitrary matrix, $\mathbf{M}_2 = [\mathbf{H}_2 \mathbf{F}_{C_2}, \quad \mathbf{J} \Sigma_1 \mathbf{X}_1^\perp (\mathbf{X}_1^\perp \mathbf{X}_2 \mathbf{F}_{C_2})^\perp]$ and $\mathbf{W}_{r_2} = [\mathbf{X}_1^\perp \mathbf{X}_2 \mathbf{F}_{C_2}, \quad \mathbf{X}_1^\perp \Sigma_1 \mathbf{X}_1^\perp (\mathbf{X}_1^\perp \mathbf{X}_2 \mathbf{F}_{C_2})^\perp]^\top$. Then,

$$D[\overrightarrow{\text{BLUP}_{\mathcal{R}_2}(\Delta_2)}] = \sigma^2 \Sigma_2 \otimes \mathbf{M}_2 \mathbf{W}_{r_2}^+ \mathbf{X}_1^\perp \Sigma_1 \mathbf{X}_1^\perp (\mathbf{M}_2 \mathbf{W}_{r_2}^+)', \quad (3.17)$$

$$D[\overrightarrow{\Delta_2} - \overrightarrow{\text{BLUP}_{\mathcal{R}_2}(\Delta_2)}] = \sigma^2 \Sigma_2 \otimes (\mathbf{M}_2 \mathbf{W}_{r_2}^+ \mathbf{X}_1^\perp - \mathbf{J}) \Sigma_1 (\mathbf{M}_2 \mathbf{W}_{r_2}^+ \mathbf{X}_1^\perp - \mathbf{J})'. \quad (3.18)$$

Proof of Theorem 2. For BLUP of Δ_i under \mathcal{R}_i , the fundamental equations can be proved similarly to Theorem 1. \square

The basic conclusions are reached by changing (3.3) in Theorem 1 into (3.9), accordingly.

Corollary 1. \mathcal{M} and \mathcal{R} be as given (1.1) and (1.11), respectively. Let Φ and Δ be as given in (1.4) and (1.13), respectively, and suppose that Δ is predictable under \mathcal{R} . Then

$$\begin{aligned} \text{BLUP}_{\mathcal{M}}(\Phi) &= \mathbf{H}\mathbf{C}^+ \mathbf{D} + \text{BLUP}_{\mathcal{R}}(\Delta) \\ &= \mathbf{H}\mathbf{C}^+ \mathbf{D} + \left([\mathbf{H}\mathbf{F}_C, \quad \mathbf{J} \Sigma_1 (\mathbf{X}\mathbf{F}_C)^\perp] \mathbf{W}_r^+ + \mathbf{U}_r \mathbf{W}_r^\perp \right) \\ &\quad \times (\mathbf{Y} - \mathbf{X}\mathbf{C}^+ \mathbf{D}) \end{aligned}$$

where $\mathbf{U}_r \in \mathbb{R}_{k,n}$ is arbitrary matrix, and $\mathbf{W}_r = [\mathbf{X}\mathbf{F}_C, \quad \Sigma_1 (\mathbf{X}\mathbf{F}_C)^\perp]^\top$. In particular,

$$\begin{aligned} \text{BLUP}_{\mathcal{M}}(\mathbf{H}\Theta) &= \mathbf{H}\mathbf{C}^+ \mathbf{D} + \text{BLUP}_{\mathcal{R}}(\mathbf{H}\mathbf{F}_C \Omega) \\ &= \mathbf{H}\mathbf{C}^+ \mathbf{D} + \left([\mathbf{H}\mathbf{F}_C, \quad \mathbf{0}] \mathbf{W}_r^+ + \mathbf{U}_r \mathbf{W}_r^\perp \right) (\mathbf{Y} - \mathbf{X}\mathbf{C}^+ \mathbf{D}). \end{aligned}$$

Corollary 2. \mathcal{M}_i and \mathcal{R}_i be as given (1.2)-(1.3) and (1.11)-(1.12), respectively. Let Φ_i and Δ_i be as given in (1.5)-(1.6) and (1.14)-(1.15), respectively, and suppose that Δ_i , $i = 1, 2$ is predictable under \mathcal{R}_i . Then

$$\begin{aligned} \text{BLUP}_{\mathcal{M}_1}(\Phi_1) &= \mathbf{H}_1 \mathbf{C}_1^+ \mathbf{D} + \text{BLUP}_{\mathcal{R}_1}(\Delta_1) \\ &= \mathbf{H}_1 \mathbf{C}_1^+ \mathbf{D} + \left(\mathbf{M}_1 \mathbf{W}_{r_1}^+ + \mathbf{U}_1 \mathbf{W}_{r_1}^\perp \right) (\mathbf{Y} - \mathbf{X}_1 \mathbf{C}_1^+ \mathbf{D}) \end{aligned}$$

where $\mathbf{U}_1 \in \mathbb{R}_{k,n}$ is arbitrary matrix, $\mathbf{M}_1 = [\mathbf{H}_1 \mathbf{F}_{C_1}, \quad \mathbf{J} \Sigma_1 \mathbf{X}_2^\perp (\mathbf{X}_2^\perp \mathbf{X}_1 \mathbf{F}_{C_1})^\perp]$ and $\mathbf{W}_{r_1} = [\mathbf{X}_2^\perp \mathbf{X}_1 \mathbf{F}_{C_1}, \quad \mathbf{X}_2^\perp \Sigma_1 \mathbf{X}_2^\perp (\mathbf{X}_2^\perp \mathbf{X}_1 \mathbf{F}_{C_1})^\perp]^\top$. In particular,

$$\text{BLUP}_{\mathcal{M}_1}(\mathbf{H}_1 \Theta_1) = \mathbf{H}_1 \mathbf{C}_1^+ \mathbf{D} + \text{BLUP}_{\mathcal{R}_1}(\mathbf{H}_1 \mathbf{F}_{C_1} \Omega_1)$$

$$= \mathbf{H}_1 \mathbf{C}_1^+ \mathbf{D} + \left([\mathbf{H}_1 \mathbf{F}_{C_1}, \quad \mathbf{0}] \mathbf{W}_{r_1}^+ + \mathbf{U}_1 \mathbf{W}_{r_1}^\perp \right) (\mathbf{Y} - \mathbf{X}_1 \mathbf{C}_1^+ \mathbf{D})$$

and

$$\begin{aligned} \text{BLUP}_{\mathcal{M}_2}(\Phi_2) &= \mathbf{H}_2 \mathbf{C}_2^+ \mathbf{D} + \text{BLUP}_{\mathcal{R}_2}(\Delta_2) \\ &= \mathbf{H}_2 \mathbf{C}_2^+ \mathbf{D} + \left(\mathbf{M}_2 \mathbf{W}_{r_2}^+ + \mathbf{U}_2 \mathbf{W}_{r_2}^\perp \right) (\mathbf{Y} - \mathbf{X}_2 \mathbf{C}_2^+ \mathbf{D}) \end{aligned}$$

where $\mathbf{U}_2 \in \mathbb{R}_{k,n}$ is arbitrary matrix, $\mathbf{M}_2 = [\mathbf{H}_2 \mathbf{F}_{C_2}, \quad \mathbf{J} \Sigma_1 \mathbf{X}_1^\perp (\mathbf{X}_1^\perp \mathbf{X}_2 \mathbf{F}_{C_2})^\perp]$ and

$$\mathbf{W}_{r_2} = [\mathbf{X}_1^\perp \mathbf{X}_2 \mathbf{F}_{C_2}, \quad \mathbf{X}_1^\perp \Sigma_1 \mathbf{X}_1^\perp (\mathbf{X}_1^\perp \mathbf{X}_2 \mathbf{F}_{C_2})^\perp].$$

In particular,

$$\begin{aligned} \text{BLUP}_{\mathcal{M}_2}(\mathbf{H}_2 \Theta_2) &= \mathbf{H}_2 \mathbf{C}_2^+ \mathbf{D} + \text{BLUP}_{\mathcal{R}_2}(\mathbf{H}_2 \mathbf{F}_{C_2} \Omega_2) \\ &= \mathbf{H}_2 \mathbf{C}_2^+ \mathbf{D} + \left([\mathbf{H}_2 \mathbf{F}_{C_2}, \quad \mathbf{0}] \mathbf{W}_{r_2}^+ + \mathbf{U}_2 \mathbf{W}_{r_2}^\perp \right) (\mathbf{Y} - \mathbf{X}_2 \mathbf{C}_2^+ \mathbf{D}). \end{aligned}$$

4. SUMMARY COMMENTS

This study presents a general approach to CMLMs and some related reduced models. We use the approach of reparameterization of CMLMs subject to exact linear restrictions. Another popular approach to handling a CMLM is to construct a new combined model by merging two given parts of the CMLM, i.e., the model part and the restriction part, into a combined form. According to this approach, the explicitly constrained model \mathcal{M} and some related reduced models \mathcal{M}_i , $i = 1, 2$ are converted into the following implicitly CMLM and some related reduced models:

$$\widehat{\mathcal{M}}: \begin{bmatrix} \mathbf{Y} \\ \mathbf{D} \end{bmatrix} = \begin{bmatrix} \mathbf{X} \\ \mathbf{C} \end{bmatrix} \Theta + \begin{bmatrix} \Psi \\ \mathbf{0} \end{bmatrix} \quad \text{with} \quad \mathbf{D} \begin{bmatrix} \mathbf{Y} \\ \mathbf{D} \end{bmatrix} = \sigma^2 \begin{bmatrix} \Sigma_2 \otimes \Sigma_1 & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix}, \quad (4.1)$$

$$\widehat{\mathcal{M}}_i: \begin{bmatrix} \mathbf{X}_j^\perp \mathbf{Y} \\ \mathbf{D} \end{bmatrix} = \begin{bmatrix} \mathbf{X}_j^\perp \mathbf{X}_i \\ \mathbf{C}_i \end{bmatrix} \Theta_i + \begin{bmatrix} \mathbf{X}_j^\perp \Psi \\ \mathbf{0} \end{bmatrix} \quad \text{with} \quad \mathbf{D} \begin{bmatrix} \mathbf{X}_j^\perp \mathbf{Y} \\ \mathbf{D} \end{bmatrix} = \sigma^2 \begin{bmatrix} \Sigma_2 \otimes \mathbf{X}_j^\perp \Sigma_1 \mathbf{X}_j^\perp & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix}, \quad (4.2)$$

$i, j = 1, 2$ and $i \neq j$. Then, by taking into account the model $\widehat{\mathcal{M}}$ and $\widehat{\mathcal{M}}_i$, $i = 1, 2$ in (4.1) and (4.2), respectively, equivalent results for the BLUP of Φ may be established.

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