



NEW OSCILLATION CRITERIA FOR SECOND-ORDER DELAY DYNAMIC EQUATIONS WITH A SUB-LINEAR NEGATIVE NEUTRAL TERM ON TIME SCALES

AHMED MOHAMED HASSAN AND SAMY AFFAN

Received 11 April, 2022

Abstract. In this paper, some sufficient conditions for the oscillation of all solutions of second order dynamic equations with a negative sub-linear neutral term are established. The obtained results provide a unified platform that adequately covers both discrete and continuous equations. Furthermore, it covers a wide range of equations by utilizing different time scales. Illustrative examples are provided.

2010 *Mathematics Subject Classification:* 34N05; 39A10; 34C10

Keywords: second order, nonlinear dynamic equations, oscillation, Riccati transformation

1. INTRODUCTION

The main focus of this paper is to provide new oscillation criteria for the second-order half-linear dynamic equation of the form

$$\left[r(t) (z^\Delta(t))^\gamma \right]^\Delta + q(t) f(x(\delta(t))) = 0, \quad (1.1)$$

where $z(t) := x(t) - p(t)x^\alpha(\tau(t))$. Under the following assumptions

- (H1) $\alpha, \gamma \in \mathbb{Q}_{\text{odd}}^+$, where $\mathbb{Q}_{\text{odd}}^+ := \{a/b : a, b \in \mathbb{Z}^+ \text{ are odd}\}$, $\alpha \in (0, 1]$;
- (H2) $r \in C_{rd}([t_0, \infty)_{\mathbb{T}}, (0, \infty))$, $p, q \in C_{rd}([t_0, \infty)_{\mathbb{T}}, \mathbb{R})$, $0 \leq p(t) \leq p_0 < 1$, $q(t) \geq 0$ and $q(t)$ is not identically zero for large t ;
- (H3) $\tau, \delta \in C_{rd}([t_0, \infty)_{\mathbb{T}}, \mathbb{T})$, $\delta^\Delta \geq 0$, $\tau(t) \leq t$, $\delta(t) \leq t$, $\lim_{t \rightarrow \infty} \tau(t) = \lim_{t \rightarrow \infty} \delta(t) = \infty$ and $h(t) = \tau^{-1}(\delta(t))$;
- (H4) $f \in C(\mathbb{R}, \mathbb{R})$, $uf(u) > 0$ for all $u \neq 0$, and there exists a positive constant k such that $f(u)/u^\beta \geq k$, β is a ratio of odd positive integers where $\beta \leq \gamma$.

Furthermore, for sufficiently large t_1 , we assume

$$R(v, u) = \int_u^v \frac{1}{r^{1/\gamma}(s)} \Delta s, \quad v \geq u \geq t_0.$$

and assume that

$$R(t_0, t) \rightarrow \infty \quad \text{as } t \rightarrow \infty. \quad (1.2)$$

Also, we define

$$Q(t) = \int_t^\infty kq(s)\Delta s, \quad t \geq t_0.$$

By a solution of (1.1), we mean a function $x \in C_{rd}[T_x, \infty)_{\mathbb{T}}$, $T_x \in [t_0, \infty)_{\mathbb{T}}$ which has the property $r(z^\Delta)^\alpha \in C_{rd}^1[T_x, \infty)_{\mathbb{T}}$ and satisfies (1.1) on $[T_x, \infty)_{\mathbb{T}}$. We consider only those solutions x of (1.1) which satisfy $\sup\{|x(t)| : t \in [T_x, \infty)_{\mathbb{T}}\} > 0$ for all $T \in [T_x, \infty)_{\mathbb{T}}$. A solution of (1.1) is called oscillatory if it is neither eventually positive nor eventually negative; otherwise, it is termed nonoscillatory.

Differential, difference equations, and dynamic equations on time scales have an enormous potential for applications in biology, engineering, economics, physics, neural networks, social sciences, etc. In particular, half-linear equations have numerous applications in the analyses of p -Laplace equations, Emden-Fowler equations, non-Newtonian fluid theory, porous medium problems, chemotaxis models, and so forth; see, e.g., [6, 11, 19, 25]. We also refer the reader to the papers [1, 2, 4–11, 13–18, 20–24, 28–34] for the oscillation and asymptotic behavior of different classes of half-linear equations.

In previous years, many papers studied the oscillatory behavior for different classes of dynamic equations on time scale. Many studies have been devoted to the oscillatory behavior of solutions to different classes of equations with nonnegative neutral coefficients; see, e.g., [2, 4, 31, 32] and the references cited therein. However, for equations with nonpositive neutral coefficients, there are relatively fewer results in the literature; see [5, 7, 17, 18, 28–30, 34]. for the oscillation and asymptotic behavior of different classes of half-linear equations.

For instance, Zhang *et al.*[33] investigated oscillatory behavior of solutions to a class of second-order nonlinear neutral delay dynamic equations with nonpositive neutral coefficients of the form

$$\left[r(t) (z^\Delta(t))^\gamma \right]^\Delta + q(t)f(x(\delta(t))) = 0, \quad t \in [t_0, \infty)_{\mathbb{T}}$$

where $\gamma \geq 1$ is a ratio of odd integers and $z(t) = x(t) - p(t)x(\tau(t))$ with $\int_{t_0}^\infty r^{-\frac{1}{\alpha}}(s)\Delta s = \infty$, and presented new oscillation criteria for

$$\left[r(t) (z'(t))^\alpha \right]' + q(t)f(x(\delta(t))) = 0, \quad t \geq t_0$$

under the assumption

$$\int_{t_0}^\infty r^{-\frac{1}{\alpha}}(s)ds < \infty.$$

For $\mathbb{T} = \mathbb{Z}$, in [14] Grace and Graef presented some new oscillation criteria for second order nonlinear difference equations with a nonlinear nonpositive neutral term of the form

$$\Delta \left(a(t) (\Delta(x(t) - p(t)x^\alpha(t-k)))^\gamma \right) + q(t)x^\beta(t+1-m) = 0$$

where α, β and γ are ratios of positive odd integers with $\gamma \geq \beta$ and $0 < \alpha \leq 1$.

In [26], Lin studied $\Delta(x_n - p_n x_{n-\tau}^\alpha) + q_n x_{n-\sigma}^\beta = 0, n \geq n_0$ where α and β are quotients of odd positive integers with $0 < \alpha < 1$

More precisely, to the best of our knowledge, no paper on the oscillation of second-order dynamic equations on a time scale appears on (1.1). Our aim is not only present some oscillation criteria for solutions of equation (1.1) but also present sufficient conditions which ensure that all solutions of (1.1) are oscillatory.

2. AUXILIARY RESULTS

Lemma 1 ([9, Theorem 1.93]). *Assume that $v: \mathbb{T} \rightarrow \mathbb{R}$ is strictly increasing and $\check{\mathbb{T}} := v(\mathbb{T})$ is a time scale. Let $y: \check{\mathbb{T}} \rightarrow \mathbb{R}$. If $v^\Delta(t)$ and $y^{\check{\Delta}}(v(t))$ exist for $t \in \mathbb{T}^k$, then*

$$(y(v(t)))^\Delta = y^{\check{\Delta}}(v(t))v^\Delta(t).$$

Lemma 2. *Let conditions (H1)-(H4) and (1.2) hold. Assume that $x(t)$ is a positive solution of (1.1). Then we have the following two cases:*

(I) $z(t) > 0, z^\Delta(t) > 0, (r(t)(z^\Delta(t))^\gamma)^\Delta \leq 0,$

(II) $z(t) < 0, z^\Delta(t) > 0, (r(t)(z^\Delta(t))^\gamma)^\Delta \leq 0,$

for $t \in [t_1, \infty)_{\mathbb{T}}$, where $t_1 \in [t_0, \infty)_{\mathbb{T}}$, is sufficiently large.

Proof. Suppose that there exists a $t_1 \geq t_0$ such that $x(t) > 0, x(\tau(t)) > 0,$ and $x(\sigma(t)) > 0$ for $t \geq t_1$. From (1.1) it follows that

$$[r(t)(z^\Delta(t))^\gamma]^\Delta \leq -kq(t)x^\beta(\delta(t)) < 0.$$

Hence, $[r(t)(z^\Delta(t))^\gamma]$ is nonincreasing and of one sign. That is, there exists $t_2 \geq t_1$ such that $z^\Delta(t) > 0$ or $z^\Delta(t) < 0$ for $t \geq t_2$. We claim that $z^\Delta(t) > 0$ for $t \geq t_2$. For this, we assume that $z^\Delta(t) < 0$ for $t \geq t_2$. Then,

$$r(t)(z^\Delta(t))^\gamma \leq -C < 0, \quad \text{for } t \geq t_2,$$

where $C = -r(t_2)(z^\Delta(t_2))^\gamma$. Thus, we conclude that

$$z(t) \leq z(t_2) - c^{1/\gamma} \int_{t_2}^t r^{-1/\gamma}(s)\Delta s.$$

By virtue of condition (1.2), $\lim_{t \rightarrow \infty} z(t) = -\infty$. Now, we consider two cases.

Case 1: If x is unbounded, then there exists a sequence $\{t_k\}$ such that $\lim_{k \rightarrow \infty} t_k = \infty$ and $\lim_{k \rightarrow \infty} x(t_k) = \infty,$ where $x(t_k) = \max \{x(s); t_0 \leq s \leq t_k\},$ since

$$\lim_{t \rightarrow \infty} \tau(t) = \infty, \quad \tau(t_k) > t_0$$

for all sufficiently large k . By $\tau(t) \leq t$

$$x(\tau(t_k)) = \max \{x(s); t_0 \leq s \leq \tau(t_k)\} \leq \max \{x(s); t_0 \leq s \leq t_k\} = x(t_k).$$

Therefore, for all large $k,$

$$z(t_k) = x(t_k) - p(t_k)x^\alpha(\tau(t_k)) \geq x(t_k) - p(t_k)x^\alpha(t_k)$$

$$\geq \left(1 - \frac{p(t_k)}{x^{1-\alpha}(t_k)}\right) x(t_k) > 0$$

which contradicts the fact that $\lim_{t \rightarrow \infty} z(t) = -\infty$.

Case 2: If $x(t)$ is bounded, then $z(t)$ is also bounded, which contradicts $\lim_{t \rightarrow \infty} z(t) = -\infty$. This completes the proof. \square

3. MAIN RESULTS

For simplicity, we consider

$$K(t) = \begin{cases} 1, & \gamma = \beta; \\ MR^{\frac{\beta-\gamma}{\gamma}}(t, t_2); & \gamma > \beta, \end{cases} \quad \text{for some } M > 0.$$

$$Q(t) = \int_t^\infty q(s) \Delta s \quad \text{and} \quad \psi(t) = r^{1/\gamma}(t)R(T, t), \quad \text{for } T \geq t_0.$$

Theorem 1. Assume that conditions (H1)-(H4) and (1.2) hold. If there exists a positive nondecreasing continuously differentiable function $\varphi(t)$, such that

$$\limsup_{t \rightarrow \infty} [\varphi(t)Q(t)] \tag{3.1}$$

$$+ \int_{t_2}^t \left(kq(s)\varphi(s) - \frac{\gamma^\gamma}{\beta^\gamma(\gamma+1)^{\gamma+1}} \frac{r(\delta(s))(\varphi^\Delta(s))^{\gamma+1}}{(\delta^\Delta(s))^\gamma \varphi^\gamma(s) K^\gamma(\delta(\sigma(s)))} \right) \Delta s = \infty,$$

$$\limsup_{t \rightarrow \infty} \left[k \int_{h(t)}^t q(s) R^{\beta/\alpha}(h(s), h(t)) \Delta s \right] > 1, \quad \text{for } \beta = \alpha\gamma, \tag{3.2}$$

and

$$\limsup_{t \rightarrow \infty} \int_{h(t)}^t q(s) R^{\beta/\alpha}(h(s), h(t)) \Delta s = \infty, \quad \text{for } \beta < \alpha\gamma, \tag{3.3}$$

then every solution of (1.1) is oscillatory.

Proof. Assume that x is a nonoscillatory solution of (1.1) such that $x(t) > 0$, $x(\tau(t)) > 0$ and $x(\delta(t)) > 0$, for $t \in [t_1, \infty)_{\mathbb{T}}$. From Lemma 2, $z(t)$ satisfies either (I) or (II) for $t \in [t_1, \infty)_{\mathbb{T}}$.

Case 1 : Suppose that $z(t)$ satisfies Lemma 2 (I). From the definition of $z(t)$,

$$x(t) = z(t) + p(t)x^\alpha(\tau(t)) \geq z(t),$$

in view of (1.1), we get

$$[r(t)(z^\Delta(t))^\alpha]^\Delta \leq -kq(t)z^\beta(\delta(t)) < 0. \tag{3.4}$$

Integrating (3.4) from t to u , letting $u \rightarrow \infty$, and using the increasing fact of $z(t)$, we get

$$r(t)(z^\Delta(t))^\gamma \geq z^\beta(\delta(t)) \int_t^\infty kq(s) \Delta s =: Q(t)z^\beta(\delta(t)). \tag{3.5}$$

Define

$$\omega(t) = \varphi(t) \frac{r(t)(z^\Delta(t))^\gamma}{z^\beta(\delta(t))}.$$

It is clear that $\omega(t) > 0$ and

$$\begin{aligned} \omega^\Delta(t) &= [r(t)(z^\Delta(t))^\gamma]^\Delta \frac{\varphi(t)}{z^\beta(\delta(t))} + r(\sigma(t))(z^\Delta(\sigma(t)))^\gamma \left(\frac{\varphi(t)}{z^\beta(\delta(t))} \right)^\Delta \\ &\leq -kq(t)\varphi(t) + \varphi^\Delta(t) \frac{r(\sigma(t))(z^\Delta(\sigma(t)))^\gamma}{z^\beta(\delta(\sigma(t)))} \\ &\quad - \beta\varphi(t) \frac{r(\sigma(t))(z^\Delta(\sigma(t)))^\gamma z^\Delta(\delta(t))\delta^\Delta(t)}{z^{\beta+1}(\delta(t))}. \end{aligned}$$

Since $z^\Delta(t) > 0$, $\delta^\Delta(t) \geq 0$ and from the definition of $\omega(t)$, we obtain

$$\begin{aligned} \omega^\Delta(t) &\leq -kq(t)\varphi(t) + \frac{\varphi^\Delta(t)}{\varphi(\sigma(t))} \omega(\sigma(t)) \\ &\quad - \beta\delta^\Delta(t)\varphi(t) \frac{r(\sigma(t))(z^\Delta(\sigma(t)))^\gamma}{z^\beta(\delta(\sigma(t)))} \frac{z^\Delta(\delta(t))}{z(\delta(\sigma(t)))} \\ &\leq -kq(t)\varphi(t) + \frac{\varphi^\Delta(t)}{\varphi(\sigma(t))} \omega(\sigma(t)) \\ &\quad - \beta\delta^\Delta(t) \frac{\varphi(t)z^\Delta(\delta(t))}{\varphi(\sigma(t))z(\delta(\sigma(t)))} \omega(\sigma(t)). \end{aligned} \tag{3.6}$$

From the definition of $\omega(t)$ and since $[r(t)(z^\Delta)^\gamma]$ is nonincreasing, then we have

$$z^\Delta(\delta(t)) \geq \frac{z^{\frac{\beta}{\gamma}}(\delta(\sigma(t)))}{r^{\frac{1}{\gamma}}(\delta(t))\varphi^{\frac{1}{\gamma}}(\sigma(t))} \omega^{\frac{1}{\gamma}}(\sigma(t)).$$

This with (3.6) leads to

$$\begin{aligned} \omega^\Delta(t) &\leq -kq(t)\varphi(t) + \frac{\varphi^\Delta(t)}{\varphi(\sigma(t))} \omega(\sigma(t)) \\ &\quad - \beta\delta^\Delta(t) \frac{\varphi(t)}{\varphi^{\frac{\gamma+1}{\gamma}}(\sigma(t))r^{\frac{1}{\gamma}}(\delta(t))} \omega^{\frac{\gamma+1}{\gamma}}(\sigma(t))z^{\frac{\beta-\gamma}{\gamma}}(\delta(\sigma(t))). \end{aligned} \tag{3.7}$$

It is clear that $z^{\frac{\beta-\gamma}{\gamma}}(\delta(\sigma(t))) = 1$ for $\beta = \gamma$ and (3.7) takes the form

$$\begin{aligned} \omega^\Delta(t) &\leq -kq(t)\varphi(t) + \frac{\varphi^\Delta(t)}{\varphi(\sigma(t))} \omega(\sigma(t)) \\ &\quad - \beta\delta^\Delta(t) \frac{\varphi(t)}{\varphi^{\frac{\gamma+1}{\gamma}}(\sigma(t))r^{\frac{1}{\gamma}}(\delta(t))} \omega^{\frac{\gamma+1}{\gamma}}(\sigma(t)). \end{aligned} \tag{3.8}$$

On the other hand for $\beta < \gamma$. Since $[r(t)(z^\Delta(t))^\gamma]^\Delta \leq 0$, then there exists a constant $C > 0$ such that $r(t)(z^\Delta(t))^\gamma \leq r(t_2)(z^\Delta(t_2))^\gamma < C$ for some $t \geq t_2$, which leads to

$$z^\Delta(t) \leq C^{\frac{1}{\gamma}} r^{-\frac{1}{\gamma}}(t). \quad (3.9)$$

Integrating (3.9) from t to t_2 , we get

$$\begin{aligned} z(t) &\leq z(t_2) + C^{\frac{1}{\gamma}} R(t_2, t) \\ &\leq C^{1/\gamma} R(t_2, t). \end{aligned}$$

This leads to,

$$z^{\frac{\beta-\gamma}{\gamma}}(\delta(\sigma(t))) > MR^{\frac{\beta-\gamma}{\gamma}}(\delta(\sigma(t)), t_2), \quad \beta < \gamma \text{ for some } M > 0. \quad (3.10)$$

Combining (3.8) and (3.10), we get

$$\begin{aligned} \omega^\Delta(t) &\leq -kq(t)\varphi(t) + \frac{\varphi^\Delta(t)}{\varphi(\sigma(t))}\omega(\sigma(t)) \\ &\quad - \beta M \delta^\Delta(t)\varphi(t) \frac{R^{\frac{\beta-\gamma}{\gamma}}(\delta(\sigma(t)), t_2)}{\varphi^{\frac{\gamma+1}{\gamma}}(\sigma(t))r^{\frac{1}{\gamma}}(\delta(t))} \omega^{\frac{\gamma+1}{\gamma}}(\sigma(t)) \\ &\leq -kq(t)\varphi(t) + \frac{\varphi^\Delta(t)}{\varphi(\sigma(t))}\omega(\sigma(t)) \\ &\quad - \beta \delta^\Delta(t)\varphi(t) \frac{K(\delta(\sigma(t)))}{\varphi^{\frac{\gamma+1}{\gamma}}(\sigma(t))r^{\frac{1}{\gamma}}(\delta(t))} \omega^{\frac{\gamma+1}{\gamma}}(\sigma(t)). \end{aligned} \quad (3.11)$$

Applying the inequality

$$B\omega - A\omega^{\frac{\gamma+1}{\gamma}} \leq \frac{\gamma^\gamma}{(\gamma+1)^{\gamma+1}} \frac{B^{\gamma+1}}{A^\gamma},$$

with $B = \frac{\varphi^\Delta(t)}{\varphi(\sigma(t))}$, $A = \beta \delta^\Delta(t)\varphi(t) \frac{K(\delta(\sigma(t)))}{\varphi^{\frac{\gamma+1}{\gamma}}(\sigma(t))r^{\frac{1}{\gamma}}(\delta(t))}$, we get

$$\omega^\Delta(t) \leq -kq(t)\varphi(t) + \frac{\gamma^\gamma \beta^{-\gamma}}{(\gamma+1)^{\gamma+1}} \frac{r(\delta(t))(\varphi^\Delta(t))^{\gamma+1}}{(\delta^\Delta(t))^\gamma \varphi^\gamma(t) K^\gamma(\delta(\sigma(t)))}. \quad (3.12)$$

Integrating (3.12) from t_2 to t

$$\begin{aligned} \omega(t) &\leq \omega(t_2) - \int_{t_2}^t \left(kq(s)\varphi(s) \right. \\ &\quad \left. - \frac{\gamma^\gamma}{\beta^\alpha (\gamma+1)^{\gamma+1}} \frac{r(\delta(s))(\varphi^\Delta(s))^{\gamma+1}}{(\delta^\Delta(s))^\gamma \varphi^\gamma(s) K^\gamma(\delta(\sigma(s)))} \right) \Delta s. \end{aligned} \quad (3.13)$$

From the definition of $\omega(t)$ and (3.5) we have

$$\omega(t) \geq \varphi(t) \frac{Q(t)z^\beta(\delta(t))}{z^\beta(\delta(t))} \geq \varphi(t)Q(t). \tag{3.14}$$

From (3.13) and taking (3.14) into account

$$\varphi(t)Q(t) + \int_{t_2}^t \left(kq(s)\varphi(s) - \frac{\alpha^\alpha}{\beta^\alpha(\alpha+1)^{\alpha+1}} \frac{r(\delta(s))(\varphi^\Delta(s))^{\alpha+1}}{(\delta^\Delta(s))^\alpha \varphi^\alpha(s) K^\alpha(\delta(\sigma(s)))} \right) \Delta s \leq \omega(t_2),$$

which contradicts (3.1).

Case 2 : Suppose that $z(t)$ satisfies Lemma 2 (II). Putting $y = -z > 0$, then $y^\Delta < 0$, and (1.1) takes the form

$$[r(t)(y^\Delta(t))^\gamma]^\Delta \geq kq(t)x^\beta(\delta(t)) \geq 0. \tag{3.15}$$

Since

$$\begin{aligned} y(t) &= -z(t) = p(t)x^\alpha(\tau(t)) - x(t) \\ &\leq p(t)x^\alpha(\tau(t)), \end{aligned}$$

by virtue of $0 \leq p(t) \leq p_0 < 1$, we have

$$y^{1/\alpha}(h(t)) \leq x(\delta(t)). \tag{3.16}$$

Now, inequalities (3.15) and (3.16) lead to

$$[r(t)(y^\Delta(t))^\gamma]^\Delta \geq kq(t)y^{\beta/\alpha}(h(t)). \tag{3.17}$$

Also for $t_2 \leq u \leq v$, we can write

$$y(u) - y(v) = \int_u^v \frac{1}{r^{1/\gamma}(s)} (-r(s)(y^\Delta(s))^\gamma)^{1/\gamma} \Delta s,$$

$$y(u) \geq R(v, u) (-r(v)(y^\Delta(v))^\gamma)^{1/\gamma}.$$

Setting $u = h(t)$ and $v = h(s)$, we get

$$y(h(s)) \geq R(h(s), h(t)) (-r(h(t))(y^\Delta(h(t)))^\gamma)^{1/\gamma}. \tag{3.18}$$

Integrating (3.17) from $h(t)$ to t , in view of (3.18), we get

$$-r(h(t))(y^\Delta(h(t)))^\gamma \geq k[-r(h(t))(y^\Delta(h(t)))^\gamma]^{\beta/\alpha\gamma} \int_{h(t)}^t q(s)R^{\beta/\alpha}(h(s), h(t))\Delta s,$$

which leads to

$$[Y(t)]^{1-\frac{\beta}{\alpha\gamma}} \geq k \int_{h(t)}^t q(s)R^{\beta/\alpha}(h(s), h(t))\Delta s,$$

where $Y(t) = -r(h(t))(y^\Delta(h(t)))^\gamma$. Therefore, we have

$$1 \geq k \int_{h(t)}^t q(s)R^{\beta/\alpha}(h(s), h(t))\Delta s, \quad \text{for } \beta = \alpha\gamma,$$

which contradicts (3.2). Also, for $\beta < \gamma$, by (3.15) together with the fact that $Y^\Delta(t) \leq 0$ and $Y(t)$ is bounded, we get a contradiction with (3.3). This completes the proof. \square

Remark 1. Note that Theorem 1 holds when $Q(t) < \infty$ and the addition term $\varphi(t)Q(t)$ in condition (3.1) may improve some of the well-known results in the literature.

Corollary 1. Let conditions (H1)-(H4) be satisfied and (1.2) hold. If $Q(t) < \infty$, then condition (3.1) replaced by

$$\limsup_{t \rightarrow \infty} \int_{t_2}^t \left(kq(s)\varphi(s) - \frac{\gamma^\gamma}{\beta^\gamma(\gamma+1)^{\gamma+1}} \frac{r(\delta(s))(\varphi^\Delta(s))^{\gamma+1}}{(\delta^\Delta(s))^\gamma \varphi^\gamma(s) K^\gamma(\delta(\sigma(s)))} \right) \Delta s = \infty, \quad (3.19)$$

and conclusion of Theorem 1 remains intact.

Corollary 2. Let conditions (H1)-(H4) be satisfied and (1.2) hold. With $\varphi^\Delta(t) \leq 0$, then condition (3.1) replaced by

$$\limsup_{t \rightarrow \infty} \left[\varphi(t)Q(t) + \int_{t_2}^t kq(s)\varphi(s)\Delta s \right] = \infty,$$

and conclusion of Theorem 1 remains intact.

To add variety, we present a different approach of the condition (3.1) in the following.

Theorem 2. Assume that conditions (H1)-(H4) and (1.2) hold. If

$$\limsup_{t \rightarrow \infty} \left[\varphi(t)Q(t) + \int_{t_2}^t (kq(s)\varphi(s) - \frac{1}{4\beta} \frac{r^{1/\gamma}(\delta(s))(\varphi^\Delta(s))^2}{\delta^\Delta(s)Q^{\frac{1-\gamma}{\gamma}}(\sigma(s))\varphi(s)K(\delta(\sigma(s)))}) \Delta s \right] = \infty, \quad (3.20)$$

and (3.2) or (3.3), then every solution of (1.1) is oscillatory.

Proof. Assume that $x(t)$ is a nonoscillatory solution of (1.1) such that $x(t) > 0$, $x(\tau(t)) > 0$ and $x(\delta(t)) > 0$, for $t \in [t_1, \infty)_{\mathbb{T}}$. From Lemma 2, $z(t)$ satisfies either (I) or (II) for $t \in [t_1, \infty)_{\mathbb{T}}$.

Case 1: First, we suppose that $z(t)$ satisfies (I). Since $\omega(t) = \varphi(t) \frac{r(t)(z^\Delta(t))^\gamma}{z^\beta(\delta(t))}$, then

by (3.14), we conclude that

$$\left(\frac{\omega(\sigma(t))}{\varphi(\sigma(t))} \right)^{\frac{1-\gamma}{\gamma}} \geq Q^{\frac{1-\gamma}{\gamma}}(\sigma(t)). \quad (3.21)$$

Now, inequalities (3.11) and (3.21) imply

$$\begin{aligned} \omega^\Delta(t) &\leq -kq(t)\varphi(t) + \frac{\varphi^\Delta(t)}{\varphi(\sigma(t))}\omega(\sigma(t)) \\ &\quad - \beta\delta^\Delta(t)Q^{\frac{1-\gamma}{\gamma}}(\sigma(t))\frac{\varphi(t)K(\delta(\sigma(t)))}{\varphi^2(\sigma(t))r^{\frac{1}{\gamma}}(\delta(t))}\omega^2(\sigma(t)). \end{aligned}$$

Apply the inequality

$$B\omega - A\omega^{\frac{\gamma+1}{\alpha}} \leq \frac{\gamma^\gamma}{(\gamma+1)^{\gamma+1}} \frac{B^{\gamma+1}}{A^\gamma}, \quad \text{where } \gamma = 1,$$

with $B = \frac{\varphi^\Delta(t)}{\varphi(\sigma(t))}$, $A = \beta\delta^\Delta(t)Q^{\frac{1-\gamma}{\gamma}}(\sigma(t))\frac{\varphi(t)K(\delta(\sigma(t)))}{\varphi^2(\sigma(t))r^{\frac{1}{\gamma}}(\delta(t))}$, we get

$$\omega^\Delta(t) \leq -kq(t)\varphi(t) + \frac{1}{4\beta} \frac{r^{1/\gamma}(\delta(t))(\varphi^\Delta(t))^2}{\delta^\Delta(t)Q^{\frac{1-\gamma}{\gamma}}(\sigma(t))\varphi(t)K(\delta(\sigma(t)))}. \tag{3.22}$$

Integrating (3.22) from t_2 to t

$$\omega(t) \leq \omega(t_2) - \int_{t_2}^t \left(kq(s)\varphi(s) - \frac{1}{4\beta} \frac{r^{1/\gamma}(\delta(s))(\varphi^\Delta(s))^2}{\delta^\Delta(s)Q^{\frac{1-\gamma}{\gamma}}(\sigma(s))\varphi(s)K(\delta(\sigma(s)))} \right) \Delta s, \tag{3.23}$$

In view of (3.14), inequality (3.23) takes the form

$$k\varphi(t)Q(t) + \int_{t_2}^t \left(kq(s)\varphi(s) - \frac{1}{4\beta} \frac{r^{1/\gamma}(\delta(s))(\varphi^\Delta(s))^2}{\delta^\Delta(s)Q^{\frac{1-\gamma}{\gamma}}(\sigma(s))\varphi(s)K(\delta(\sigma(s)))} \right) \Delta s \leq \omega(t_2),$$

which contradicts (3.20).

Case 2: Suppose that $z(t)$ satisfies Lemma 2 (II). The proof can be performed a similar manner as in the proof of Theorem 1. This completes the proof. □

4. APPLICATIONS AND EXAMPLES

This section introduces some special cases for Eq. (1.1). For the non-neutral equation, i.e., Eq. (1.1) with $p(t) \equiv 0$, and $q(t)$ is either positive or negative for all large t , Eq. (1.1) is reduced to the equation

$$\left[r(t) \left((x(t))^\Delta \right)^\gamma \right]^\Delta \pm q(t)f(x(\delta(t))) = 0. \tag{E±}$$

From Theorem 1 we conclude the following results.

Corollary 3. Assume that conditions (H1)-(H4) and (1.2) hold. If there exists a positive function $\phi(t)$ with $\phi^\Delta(t) \geq 0$ such that condition (3.1) holds, then Eq. (E+) is oscillatory.

Proof. The proof is omitted because it is included in the proof of Theorem 1-Case (1). \square

It's noted that, results in [3] and the references cited therein are related to Corollary 3 for $\mathbb{T} = \mathbb{R}$. Also the results can be extended to the difference equations when $\mathbb{T} = \mathbb{Z}$, see [12, 27].

Corollary 4. *Assume that conditions (H1)-(H4) and (1.2) hold. If there exists a positive function $\phi(t)$ with $\phi^\Delta(t) \geq 0$ such that condition (3.2) or (3.3) holds, then Eq. (E-) is oscillatory.*

Proof. The proof is omitted because it is included in the proof of Theorem 1-Case (2). \square

In the following, we investigate another special case

Theorem 3. *Let $\alpha = 1$, conditions (H1)-(H4), and (1.2) hold. Assume that condition (3.2) and*

$$\limsup_{t \rightarrow \infty} R^\beta(t_0, \delta(t)) > 1, \quad \text{when } \beta = \gamma, \quad (4.1)$$

hold and condition (3.3) and

$$\limsup_{t \rightarrow \infty} R^\beta(t_0, \delta(t)) > 0, \quad \text{when } \beta < \gamma, \quad (4.2)$$

hold. Then (1.1) is oscillatory.

Proof. Assume that (1.1) has a nonoscillatory solution $x(t)$. Without loss of generality, we assume that there exists a $t_1 \in [t_0, \infty)_{\mathbb{T}}$ such that $x(t) > 0$, $x(\tau(t)) > 0$, and $x(\delta(t))$ for $t \in [t_1, \infty)_{\mathbb{T}}$. According to Lemma 2, we have two possible cases for $z(t)$. Assume that $z(t)$ satisfies Lemma 2 (I). It follows that

$$\begin{aligned} z(t) &= z(t_2) + \int_{t_2}^t \frac{(r(s)(z^\Delta(s))^\gamma)^{1/\gamma}}{a^{1/\gamma}(s)} \Delta s \\ &\geq (r(t)(z^\Delta(t))^\gamma)^{1/\gamma} \int_{t_2}^t a^{-1/\gamma}(s) \Delta s \\ &=: \Psi(t)z^\Delta(t). \end{aligned} \quad (4.3)$$

In view of (3.5) and (4.3), and using the decreasing fact of $r(t)z^\Delta(t)$, we find

$$\begin{aligned} w(t) &=: r(t)z^\Delta(t) \\ &\geq Q(t)\Psi^\beta(\delta(t))(z^\Delta(\delta(t)))^\beta \\ &= Q(t)\Psi^\beta(\delta(t)) \left(r^{-\beta/\gamma}(\delta(t)) \right) (r(\delta(t))(z^\Delta(\delta(t)))^\gamma)^{\beta/\gamma} \\ &\geq Q(t)\Psi^\beta(\delta(t)) \left(r^{-\beta/\gamma}(\delta(t)) \right) (r(t)(z^\Delta(t))^\gamma)^{\beta/\gamma} \\ &= Q(t)\Psi^\beta(\delta(t)) \left(r^{-\beta/\gamma}(\delta(t)) \right) w^{\beta/\gamma}(t), \end{aligned}$$

hence

$$\begin{aligned} w^{1-\beta/\gamma}(t) &\geq Q(t)\psi^\beta(\tau(t))\left(r^{-\beta/\gamma}(\delta(t))\right) \\ &= Q(t)\left(\int_{t_2}^{\delta(t)} r^{-1/\gamma}(s)\Delta s\right)^\beta \\ &= R^\beta(t_2, \delta(t))Q(t). \end{aligned} \tag{4.4}$$

Taking limsup of both sides of (4.4) as $t \rightarrow \infty$. For $\beta = \gamma$, we get a contradiction to (4.1) and (4.2) when $\beta < \gamma$. If $z(t)$ satisfies Lemma 2 (II), then the proof is similar to that of Theorem 1. \square

Remark 2. Note that the obtained results in Theorem 3 are an improvement of the results in [18, 34] which guarantee that every solution of (1.1) is oscillatory.

Example 1. Let $\mathbb{T} = \mathbb{R}$. Consider the second order differential equation

$$\left(t^2 \left(\left(x(t) - \frac{1}{2}x(t/3)\right)'\right)^3\right) + \frac{\lambda}{t^2}x^3(t/2) = 0, \quad t \geq 1. \tag{4.5}$$

Here $\alpha = 1, \beta = 3, \gamma = 3, \lambda > 0$ is a constant $k = \lambda, r(t) = t^2, p(t) = 1/2, q(t) = 1/t^2, \tau(t) = t/3, \delta(t) = t/2$ and $h(t) = 3t/2$. It is clear that

$$\begin{aligned} R(t_0, t) &= \int_1^t s^{-2/3} ds \\ &= 3(\sqrt[3]{t} - 1), \quad R(t_0, t) \rightarrow \infty \text{ as } t \rightarrow \infty. \end{aligned}$$

Applying Theorem 3, we have

$$\limsup_{t \rightarrow \infty} \left[k \int_{h(t)}^t q(s)R^\beta(h(s), h(t))\Delta s \right] = \limsup_{t \rightarrow \infty} \left[\lambda \int_{3t/2}^t \frac{81(\sqrt[3]{s} - \sqrt[3]{t})^3}{2s^2} ds \right] > 1$$

and

$$\limsup_{t \rightarrow \infty} R^\beta(t_0, \delta(t)) = \limsup_{t \rightarrow \infty} \left(3(\sqrt[3]{3t/2} - 1) \right) > 1.$$

For suitable λ and large t , every solution of Eq. (4.5) is oscillatory.

Remark 3. Theorem 3.1 of [18] can be applied to (4.5) which yields that every solution of equation (4.5) is oscillatory when $\lambda > \frac{2}{27}$ or $\lim_{t \rightarrow \infty} x(t) = 0$.

Example 2. Let $\mathbb{T} = \mathbb{R}$. Consider the second order differential equation

$$\left(\left(x(t) - \frac{1}{2}x(\sqrt{t})\right)^3 \right)'' + \frac{m}{t^{5/4}}x(t/2) = 0, \quad t \geq 1. \tag{4.6}$$

Here $\alpha = 1$, $\beta = 1$, $\gamma = 3$, $k = m > 0$ where m is a constant, $r(t) = 1$, $p(t) = 1/2$, $q(t) = 1/t^{5/4}$, $\tau(t) = \sqrt{t}$, $\delta(t) = t^{5/4}$ and $h(t) = \sqrt{t}$. Taking $\varphi(t) = t$, by using Theorem 1, we have

$$\begin{aligned} & \limsup_{t \rightarrow \infty} \left[4mt^{3/4} + \int_1^t \left(\frac{m}{\sqrt[4]{s}} - \frac{9}{16 \left(\frac{1}{4}s^{1/4}\right)^3 (\sqrt[4]{s}-1)^{-2}} \right) ds \right] \\ &= \limsup_{t \rightarrow \infty} \left[4mt^{3/4} + \frac{4}{3} \left(m \left(t^{3/4} - 1 \right) - 36 \left(\sqrt[4]{t} - 1 \right)^3 \right) \right]. \end{aligned}$$

Hence, (4.6) oscillates for $m > 9$.
According to (3.2), we have

$$\limsup_{t \rightarrow \infty} \left[k \int_{h(t)}^t q(s) R^\beta(h(s), h(t)) ds \right] = \limsup_{t \rightarrow \infty} \left[2m \int_{\sqrt{t}}^t \frac{\sqrt{t} - \sqrt{s}}{s^{5/4}} ds \right] \rightarrow \infty.$$

Therefore, every solution of (4.5) is oscillatory when $m > 9$.

Remark 4. It should be noted that, for $\mathbb{T} = \mathbb{R}$ and $\alpha = 1$, Theorem 1 improves the conditions of Theorem 2.1 of [13] and guarantees that every solution of (1.1) is oscillatory unlike in [13, 33, 34].

Example 3. Let $\mathbb{T} = \mathbb{Z}$. Consider the second order difference equation

$$\Delta \left(\Delta \left(x(t) - \frac{1}{2} x^{1/3}(t-3) \right)^3 \right) + 8(x-7) = 0, \quad t \geq 1. \quad (4.7)$$

Here $\alpha = 1/3$, $\beta = 1$, $\gamma = 3$, $k = 1$, $r(t) = 1$, $p(t) = 1/2$, $q(t) = 8$, $\tau(t) = t-3$, $\delta(t) = t-7$ and $h(t) = t-4$. Taking $\varphi(t) = t$, by using Corollary 1, we have

$$\begin{aligned} & \limsup_{t \rightarrow \infty} \left[\sum_{s=1}^t \left(kq(s)\varphi(s) - \frac{\gamma^\gamma}{\beta^\gamma(\gamma+1)^{\gamma+1}} \frac{r(\delta(s))(\Delta\varphi(s))^{\gamma+1}}{(\Delta\delta(s))^\gamma \varphi^\gamma(s) K^\gamma(\delta(\sigma(s)))} \right) \right] \\ &= \limsup_{t \rightarrow \infty} \left[\sum_{s=1}^t \left(8s - \frac{9}{16s^3(s-6)^{-2}} \right) \right] \rightarrow \infty. \end{aligned}$$

Also, condition (3.2) implies that

$$\limsup_{t \rightarrow \infty} \left[k \sum_{s=h(t)}^t q(s) R^{\beta/\alpha}(h(t), h(s)) ds \right] \rightarrow \infty,$$

which yields that (4.7) satisfies conditions (3.19) and (3.2). Therefore, every solution of (4.7) is oscillatory.

REFERENCES

- [1] R. P. Agarwal, M. Bohner, and T. Li, "Oscillatory behavior of second-order half-linear damped dynamic equations," *Applied Mathematics and Computation*, vol. 254, pp. 408–418, 2015, doi: <https://doi.org/10.1016/j.amc.2014.12.091>.
- [2] R. P. Agarwal, M. Bohner, T. Li, and C. Zhang, "Oscillation criteria for second-order dynamic equations on time scales," *Applied Mathematics Letters*, vol. 31, pp. 34–40, 2014, doi: [10.1016/j.aml.2014.01.002](https://doi.org/10.1016/j.aml.2014.01.002).
- [3] R. P. Agarwal, S. R. Grace, and D. O'Regan, *Oscillation theory for second order dynamic equations*. CRC Press, 2002.
- [4] R. P. Agarwal, D. O'Regan, and S. H. Saker, "Oscillation criteria for second-order nonlinear neutral delay dynamic equations," *Journal of Mathematical Analysis and Applications*, vol. 300, no. 1, pp. 203–217, 2004, doi: <https://doi.org/10.1016/j.jmaa.2004.06.041>.
- [5] R. Arul and V. S. Shobha, "Improvement results for oscillatory behavior of second order neutral differential equations with nonpositive neutral term," *Journal of Advances in Mathematics and Computer Science*, pp. 1–7, 2016, doi: [10.9734/BJMCS/2016/20641](https://doi.org/10.9734/BJMCS/2016/20641).
- [6] M. Bohner, T. S. Hassan, and T. Li, "Fite–Hille–Wintner-type oscillation criteria for second-order half-linear dynamic equations with deviating arguments," *Indagationes Mathematicae*, vol. 29, no. 2, pp. 548–560, 2018, doi: <https://doi.org/10.1016/j.indag.2017.10.006>.
- [7] M. Bohner and T. Li, "Oscillation of second-order p -Laplace dynamic equations with a non-positive neutral coefficient," *Applied Mathematics Letters*, vol. 37, pp. 72–76, 2014, doi: [10.1016/j.aml.2014.05.012](https://doi.org/10.1016/j.aml.2014.05.012).
- [8] M. Bohner and T. Li, "Kamenev-type criteria for nonlinear damped dynamic equations," *Science China Mathematics*, vol. 58, pp. 1445–1452, 2015, doi: [10.1007/s11425-015-4974-8](https://doi.org/10.1007/s11425-015-4974-8).
- [9] M. Bohner and A. Peterson, *Dynamic equations on time scales: An introduction with applications*. Springer Science & Business Media, 2001.
- [10] M. Bohner and A. C. Peterson, *Advances in dynamic equations on time scales*. Springer Science & Business Media, 2002. doi: <http://dx.doi.org/10.1007/978-0-8176-8230-9>.
- [11] J. Džurina, S. R. Grace, I. Jadlovská, and T. Li, "Oscillation criteria for second-order Emden–Fowler delay differential equations with a sublinear neutral term," *Mathematische Nachrichten*, vol. 293, no. 5, pp. 910–922, 2020, doi: <https://doi.org/10.1002/mana.201800196>.
- [12] H. A. El-Morshedy, "Oscillation and nonoscillation criteria for half-linear second order difference equations," *Dynamic Systems and Applications*, vol. 15, no. 3/4, pp. 429–450, 2006.
- [13] S. R. Grace, "Oscillatory behavior of second-order nonlinear differential equations with a non-positive neutral term," *Mediterranean Journal of Mathematics*, vol. 14, no. 6, p. 229, 2017, doi: [10.1007/s00009-017-1026-3](https://doi.org/10.1007/s00009-017-1026-3).
- [14] S. R. Grace and J. R. Graef, "Oscillatory behavior of second order nonlinear difference equations with a nonlinear nonpositive neutral term," *Miskolc Mathematical Notes*, vol. 20, no. 2, pp. 899–910, 2019, doi: [10.18514/MMN.2019.2731](https://doi.org/10.18514/MMN.2019.2731).
- [15] S. R. Grace, I. Jadlovská, and A. Zafer, "Oscillatory behavior of n -th order nonlinear delay differential equations with a nonpositive neutral term," *Hacetatepe Journal of Mathematics and Statistics*, vol. 49, no. 2, pp. 766–776, 2020, doi: [10.15672/hujms.471023](https://doi.org/10.15672/hujms.471023).
- [16] S. R. Grace, S. Sun, L. Feng, and Y. Sui, "Oscillatory behavior of second order nonlinear difference equations with a non-positive neutral term," *Open J. Math. Sci.*, vol. 2, no. 1, pp. 240–252, 2018, doi: [10.30538/oms2018.0032](https://doi.org/10.30538/oms2018.0032).
- [17] B. Karpuz, "Sufficient conditions for the oscillation and asymptotic behaviour of higher-order dynamic equations of neutral type," *Applied Mathematics and Computation*, vol. 221, pp. 453–462, 2013, doi: <https://doi.org/10.1016/j.amc.2013.06.090>.

- [18] Q. Li, R. Wang, F. Chen, and T. Li, "Oscillation of second-order nonlinear delay differential equations with nonpositive neutral coefficients," *Advances in Difference Equations*, vol. 2015, no. 1, p. 35, 2015, doi: [10.1186/s13662-015-0377-y](https://doi.org/10.1186/s13662-015-0377-y).
- [19] T. Li, N. Pintus, and G. Viglialoro, "Properties of solutions to porous medium problems with different sources and boundary conditions," *Zeitschrift für angewandte Mathematik und Physik*, vol. 70, pp. 1–18, 2019, doi: [10.1007/s00033-019-1130-2](https://doi.org/10.1007/s00033-019-1130-2).
- [20] T. Li and Y. V. Rogovchenko, "Oscillation of second-order neutral differential equations," *Mathematische Nachrichten*, vol. 288, no. 10, pp. 1150–1162, 2015, doi: <https://doi.org/10.1002/mana.201300029>.
- [21] T. Li and Y. V. Rogovchenko, "On asymptotic behavior of solutions to higher-order sublinear Emden–Fowler delay differential equations," *Applied Mathematics Letters*, vol. 67, pp. 53–59, 2017, doi: <https://doi.org/10.1016/j.aml.2016.11.007>.
- [22] T. Li and Y. V. Rogovchenko, "Oscillation criteria for second-order superlinear Emden–Fowler neutral differential equations," *Monatshefte für Mathematik*, vol. 184, pp. 489–500, 2017, doi: [10.1007/s00605-017-1039-9](https://doi.org/10.1007/s00605-017-1039-9).
- [23] T. Li and Y. V. Rogovchenko, "On the asymptotic behavior of solutions to a class of third-order nonlinear neutral differential equations," *Applied Mathematics Letters*, vol. 105, pp. 1–7, 2020, doi: [10.1016/j.aml.2020.106293](https://doi.org/10.1016/j.aml.2020.106293).
- [24] T. Li and S. H. Saker, "A note on oscillation criteria for second-order neutral dynamic equations on isolated time scales," *Communications in Nonlinear Science and Numerical Simulation*, vol. 19, no. 12, pp. 4185–4188, 2014, doi: [10.1016/j.cnsns.2014.04.015](https://doi.org/10.1016/j.cnsns.2014.04.015).
- [25] T. Li and G. Viglialoro, "Boundedness for a nonlocal reaction chemotaxis model even in the attraction-dominated regime," *Differential Integral Equations*, vol. 34, pp. 316–336, 2021.
- [26] X. Lin, "Oscillation of solutions of neutral difference equations with a nonlinear neutral term," *Computers & Mathematics with Applications*, vol. 52, no. 3–4, pp. 439–448, 2006, doi: <https://doi.org/10.1016/j.camwa.2006.02.009>.
- [27] S. H. Saker, "Oscillation criteria of second-order half-linear delay difference equations," *Kyung-pook Mathematical Journal*, vol. 45, no. 4, pp. 579–594, 2005.
- [28] E. Thandapani, V. Balasubramanian, and J. R. Graef, "Oscillation criteria for second order neutral difference equations with negative neutral term," *International Journal of Pure and Applied Mathematics*, vol. 87, no. 2, pp. 283–292, 2013, doi: [10.12732/ijpam.v87i2.9](https://doi.org/10.12732/ijpam.v87i2.9).
- [29] E. Thandapani and K. Mahalingam, "Necessary and sufficient conditions for oscillation of second order neutral difference equations," *Tamkang Journal of Mathematics*, vol. 34, no. 2, pp. 137–146, 2003, doi: <https://doi.org/10.5556/j.tkm.34.2003.260>.
- [30] E. Thandapani, D. Seghar, and S. Pinelas, "Oscillation theorems for second order difference equations with negative neutral term," *Tamkang Journal of Mathematics*, vol. 46, no. 4, pp. 441–451, 2015, doi: [10.5556/j.tkm.46.2015.1827](https://doi.org/10.5556/j.tkm.46.2015.1827).
- [31] C. Zhang, R. P. Agarwal, M. Bohner, and T. Li, "Oscillation of second-order nonlinear neutral dynamic equations with noncanonical operators," *Bulletin of the Malaysian Mathematical Sciences Society*, vol. 38, no. 2, pp. 761–778, 2015, doi: [10.1007/s40840-014-0048-2](https://doi.org/10.1007/s40840-014-0048-2).
- [32] C. Zhang and T. Li, "Some oscillation results for second-order nonlinear delay dynamic equations," *Applied Mathematics Letters*, vol. 26, no. 12, pp. 1114–1119, 2013, doi: [10.1016/j.aml.2013.05.014](https://doi.org/10.1016/j.aml.2013.05.014).
- [33] M. Zhang, W. Chen, M. M. A. El-Sheikh, R. A. Sallam, A. M. Hassan, and T. Li, "Oscillation criteria for second-order nonlinear delay dynamic equations of neutral type," *Advances in Difference Equations*, vol. 2018, no. 1, pp. 1–9, 2018, doi: [10.1186/s13662-018-1474-5](https://doi.org/10.1186/s13662-018-1474-5).
- [34] M. Zhang, W. Chen, M. M. A. El-Sheikh, R. A. Sallam, A. M. Hassan, and T. Li, "New oscillation criteria for second-order nonlinear delay dynamic equations with nonpositive neutral coefficients on time scales," *Journal of Computational Analysis & Applications*, vol. 27, no. 1, 2019.

*Authors' addresses***Ahmed Mohamed Hassan**

(**Corresponding author**) Benha University, Department of Mathematics, Faculty of Science, Benha-Kalubia 13518, Egypt

E-mail address: ahmed.mohamed@fsc.bu.edu.eg

Samy Affan

Benha University, Department of Mathematics, Faculty of Science, Benha-Kalubia 13518, Egypt

E-mail address: samy.affan@fsc.bu.edu.eg