Miskolc Mathematical Notes

# EXISTENCE AND EXPONENTIAL DECAY OF A LOGARITHMIC WAVE EQUATION WITH DISTRIBUTED DELAY 

HAZAL YÜKSEKKAYA AND ERHAN PIŞKIN<br>Received 02 March, 2022


#### Abstract

In this article, we deal with a logarithmic wave equation with distributed delay. Firstly, we establish the well-posedness by utilizing the semigroup theory. Later, we obtain the global existence of solutions by using the well-depth method. Moreover, under appropriate assumptions on the weight of the distributed delay and that of strong damping, we get the exponential decay results.


2010 Mathematics Subject Classification: 35B40; 35L05; 35L15; 35L70.
Keywords: existence, exponential decay, logarithmic wave equation, distributed delay.

## 1. Introduction

In this paper, we deal with the following logarithmic wave equation with distributed delay:

$$
\begin{cases}u_{t t}-\Delta u-\mu_{1} \Delta u_{t}(x, t)-\int_{\tau_{1}}^{\tau_{2}} \mu_{2}(s) \Delta u_{t}(x, t-s) d s &  \tag{1.1}\\ =u|u|^{p-2} \ln |u|^{k}, & \text { in } \Omega \times(0, \infty), \\ u(x, t)=0, & \text { on } \partial \Omega \times(0, \infty), \\ u_{t}(x,-t)=f_{0}(x,-t), & 0<t \leq \tau_{2}, \\ u(x, 0)=u_{0}(x), u_{t}(x, 0)=u_{1}(x), & \text { in } \Omega,\end{cases}
$$

where $\Omega$ is a bounded and regular domain of $R^{n} . k, \mu_{1}$ are positive constants, the integral term denotes the distributed delay for $\tau_{1}<\tau_{2}$ and $\mu_{2}:\left[\tau_{1}, \tau_{2}\right] \rightarrow R$ is a bounded function and $u_{0}, u_{1}, f_{0}$ are the functions of the initial data to be specified later.

The study of the asymptotic behavior of wave equation is an old and large areas because it is important in the applications, for this reasons wave equation has been taking different forms and names according to the phenomena it describes and also the material using in the experiment. In this paper we will study the nonlinear wave equation (1.1) with time delay. Also, in the same equation, we add the logarithmic source term which seems in inflation cosmology, nuclear physics, geophysics and optics, for instance (see [3-5,7,12]). To give a problem describe a phenomena enough perfect, we must take a consideration the delay which appears in practical phenomena like physical, biological, economic and some of themes. Furthermore, delay term
influenced on the stability and instability of the studied system and many papers has been discussed the both situations, for example [8-10, 16].

During the past decades, many authors considered extensively on existence, nonexistence, stability and blow-up of solutions for the strongly damped wave equations with source term as follows:

$$
\begin{equation*}
u_{t t}-\Delta u-\omega \Delta u_{t}+\mu u_{t}=f(u) \tag{1.2}
\end{equation*}
$$

Firstly, Sattinger [28] studied the existence of local as well as global solutions for the equation (1.2) with $\omega=\mu=0$ by introducing the concepts of stable and unstable sets. In [13], Ikehata looked into the decay and blow-up of solutions for the equation (1.2) with linear damping that is $\omega=0$ and $\mu>0$. In [11], Gazzola and Squassina obtained the global existence and blow-up results for the equation (1.2) with both weak and strong damping $(\omega>0)$. In the case of logarithmic source term $f(u)=u \ln |u|^{k}$, Ma and Fang [20] obtained the existence and blow-up results for the equation (1.2) with $\omega=1, \mu=0$ and $k=2$. In [18], Lian and Xu established the global existence, energy decay and blow-up results in the case $\omega \geq 0$ and $\mu>-\omega \lambda_{1}$, here $\lambda_{1}$ is the first eigenvalue of the operator $-\Delta$ under homogeneous Dirichlet boundary conditions.

It is well known that, in the $n$-dimensional case, the equation:

$$
\begin{equation*}
u_{t t}-\Delta u+a_{0} u_{t}(x, t)+a u_{t}(x, t-\tau)=0 \tag{1.3}
\end{equation*}
$$

is exponentially stable without delay $\left(a=0, a_{0}>0\right)$, (see $[19,35]$ ). With delay term $(a>0)$, Nicaise and Pignotti [23] considered the equation (1.3) and established, under the condition that the weight of the feedback is larger than the weight of the delay $\left(a<a_{0}\right)$, that the energy of (1.3) is exponentially stable. If the delay term in the equation (1.3) is replaced by the distributed delay:

$$
\int_{\tau_{1}}^{\tau_{2}} a(s) u_{t}(x, t-s) d s
$$

exponential stability of solutions have been proved in Ref. [22] under the assumption:

$$
\int_{\tau_{1}}^{\tau_{2}} a(s) d s<a_{0}
$$

Without logarithmic nonlinearity $\left(u|u|^{p-2} \ln |u|^{k}\right)$, the equation (1.1) takes the following form:

$$
\begin{equation*}
u_{t t}-\Delta u-\mu_{1} \Delta u_{t}(x, t)-\int_{\tau_{1}}^{\tau_{2}} \mu_{2}(s) \Delta u_{t}(x, t-s) d s=0 \tag{1.4}
\end{equation*}
$$

Messaoudi et al. [21], established the well-posedness and obtained an exponential decay results under a suitable assumption on the weight of the damping and the weight of the delay of the equation (1.4). Furthermore, in [21], they extended the results obtained to the case of strong delay $\left(\mu_{2} \Delta u_{t}(x, t-\tau)\right)$ in same work. Some other researchers considered delayed hyperbolic-type equations (see [2, 14, 15, 25, 27,29-34]).

Motivated by previous works and in the presence of strong damping $\left(-\mu_{1} \Delta u_{t}(x, t)\right)$, distributed delay $\left(\int_{\tau_{1}}^{\tau_{2}} \mu_{2}(s) \Delta u_{t}(x, t-s) d s\right)$ and logarithmic $\left(u|u|^{p-2} \ln |u|^{k}\right)$ nonlinearity, we consider the well-posedness, global existence and exponential decay for the logarithmic wave equation (1.1) with strong damping and distributed delay.

The contents of this work is organized as follows: In Section 2, firstly, we obtain the well-posedness by utilizing the semigroup theory. Then, in Section 3, we establish the global existence results by the well-depth method. Finally, in Section 4, we get the exponential decay of solutions.

## 2. WELL-POSEDNESS

As usual, the notation $\|.\|_{p}$ denotes $L^{p}$ norm and $(.,$.$) is the L^{2}$ inner product. In particular, we write $\|$.$\| instead of \|.\|_{2}$ (see [1,26], for details). Similar to the [23], we introduce the new variable

$$
z(x, \rho, s, t)=u_{t}(x, t-\rho s), \text { in } \Omega \times(0,1) \times\left(\tau_{1}, \tau_{2}\right) \times(0, \infty)
$$

Hence, we get

$$
s z_{t}(x, \rho, s, t)+z_{\rho}(x, \rho, s, t)=0 \text { in } \Omega \times(0,1) \times\left(\tau_{1}, \tau_{2}\right) \times(0, \infty) .
$$

Therefore, the problem (1.1) becomes the form:

$$
\begin{cases}u_{t t}-\Delta u-\mu_{1} \Delta u_{t}(x, t)-\int_{\tau_{1}}^{\tau_{2}} \mu_{2}(s) \Delta z(x, 1, s, t) d s &  \tag{2.1}\\ \quad=u|u|^{p-2} \ln |u|^{k}, & \text { in } \Omega \times(0,+\infty) \\ s z_{t}(x, \rho, s, t)+z_{\rho}(x, \rho, s, t)=0, & \text { in } \Omega \times(0,1) \times\left(\tau_{1}, \tau_{2}\right) \times(0,+\infty) \\ u(x, t)=0, & \text { on } \partial \Omega \times(0, \infty) \\ u(x, 0)=u_{0}(x), u_{t}(x, 0)=u_{1}(x), & \text { in } \Omega \\ z(x, \rho, s, 0)=f_{0}(x,-\rho s), & \text { in } \Omega \times(0,1) \times\left(\tau_{1}, \tau_{2}\right) .\end{cases}
$$

We establish the local existence utilizing the semigroup theory [17,24]. Let $v=u_{t}$ and denote by
$\Phi=(u, v, z)^{T}, \Phi(0)=\Phi_{0}=\left(u_{0}, u_{1}, f_{0}(\cdot, \rho s)\right)^{T}$ and $J(\Phi)=\left(0, u|u|^{p-2} \ln |u|^{k}, 0\right)^{T}$.
Hence, (2.1) can be written as an initial-value problem:

$$
\left\{\begin{array}{cl}
\partial_{t} \Phi+\mathcal{A} \Phi & =J(\Phi),  \tag{2.2}\\
\Phi(0) & =\Phi_{0},
\end{array}\right.
$$

where the linear operator $\mathcal{A}: D(\mathcal{A}) \longrightarrow \mathcal{H}$ is defined by

$$
\mathcal{A} \Phi=\left(\begin{array}{c}
-v \\
-\Delta u-\mu_{1} \Delta v-\int_{\tau_{1}}^{\tau_{2}} \mu_{2}(s) \Delta z(x, 1, s, t) d s \\
\frac{1}{s} z_{\rho}
\end{array}\right),
$$

where $D(\mathcal{A})$ and $\mathcal{H}$ are introduced below.
The setting space of $\Phi$ is the Hilbert space

$$
\mathcal{H}=H_{0}^{1}(\Omega) \times L^{2}(\Omega) \times L^{2}\left((0,1) \times\left(\tau_{1}, \tau_{2}\right) ; H_{0}^{1}(\Omega)\right),
$$

equipped with the inner product

$$
\langle\Phi, \widetilde{\Phi}\rangle_{\mathcal{H}}=\int_{\Omega}(\nabla u \nabla \widetilde{u}+v \widetilde{v}) d x+\int_{\Omega} \int_{\tau_{1}}^{\tau_{2}} s\left|\mu_{2}(s)\right| \int_{0}^{1} \nabla z \nabla \widetilde{z} d \rho d s d x
$$

for all $\Phi=(u, v, z)^{T}$ and $\widetilde{\Phi}=(\widetilde{u}, \widetilde{v}, \widetilde{z})^{T}$ in $\mathcal{H}$. The domain of $\mathcal{A}$ is

$$
D(\mathcal{A})=\left\{\begin{array}{c}
\Phi \in \mathcal{H}:\left(u+\mu_{1} v+\left(\int_{\tau_{1}}^{\tau_{2}} \mu_{2}(s) z\right)\right) \in H^{2}(\Omega), \\
z, z_{\rho} \in L^{2}\left((0,1) \times\left(\tau_{1}, \tau_{2}\right) ; H_{0}^{1}(\Omega)\right), z(\cdot, 0, \cdot)=v
\end{array}\right\}
$$

Now, we obtain the local existence and uniqueness of solutions as follows:
Theorem 1. Suppose that $\mu_{1}>\int_{\tau_{1}}^{\tau_{2}} \mu_{2}(s) d s$ and

$$
\left\{\begin{array}{cl}
p>2 & \text { if } n=1,2  \tag{2.3}\\
2<p<\frac{2(n-1)}{n-2} & \text { if } n \geq 3
\end{array}\right.
$$

Then, for any $\Phi_{0} \in \mathcal{H}$, problem (2.2) has a unique weak solution

$$
\Phi \in C([0, T) ; \mathcal{H})
$$

Furthermore, if $\Phi_{0} \in D(\mathcal{A})$, the solution of (2.2) satisfies

$$
\Phi \in C^{1}([0, T), \mathcal{H}) \cap C([0, T), D(\mathcal{A}))
$$

Proof. We will utilize the Hille-Yoside theorem [6, 17]. For this aim, we indicate that $\mathcal{A}$ is monotone. Thus, for all $\Phi \in D(\mathcal{A})$, we obtain

$$
\begin{align*}
\langle\mathcal{A} \Phi, \Phi\rangle_{\mathcal{H}}= & -\int_{\Omega} \nabla v \nabla u d x \\
& -\int_{\Omega} v\left[\Delta u+\mu_{1} \Delta v+\int_{\tau_{1}}^{\tau_{2}} \mu_{2}(s) \Delta z(x, 1, s, t) d s\right] d x \\
& +\int_{\Omega} \int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| \int_{0}^{1} \nabla z \nabla z_{\rho} d \rho d s d x  \tag{2.4}\\
= & \mu_{1} \int_{\Omega}|\nabla v|^{2} d x+\int_{\Omega} \nabla v\left(\int_{\tau_{1}}^{\tau_{2}} \mu_{2}(s) \nabla z(x, 1, s, t) d s\right) d x \\
& +\frac{1}{2} \int_{\Omega} \int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right||\nabla z(x, 1, s, t)|^{2} d s d x \\
& -\frac{1}{2} \int_{\Omega} \int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right||\nabla v|^{2} d s d x
\end{align*}
$$

By using the Young's inequality, the estimate (2.4) becomes the form:

$$
\begin{aligned}
\langle\mathcal{A} \Phi, \Phi\rangle_{\mathcal{H}} & \geq \mu_{1} \int_{\Omega}|\nabla v|^{2} d x-\frac{\left|\mu_{2}\right|}{2} \int_{\Omega} \int_{\tau_{1}}^{\tau_{2}}|\nabla v|^{2} d s d x-\frac{\left|\mu_{2}\right|}{2} \int_{\Omega} \int_{\tau_{1}}^{\tau_{2}}|\nabla v|^{2} d s d x \\
& =\left(\mu_{1}-\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}\right|(s) d s\right) \int_{\Omega}|\nabla v|^{2} d x \geq 0
\end{aligned}
$$

Therefore, $\mathcal{A}$ is a monotone operator.

To indicate that $\mathcal{A}$ is maximal, we establish that for each:

$$
F=(f, g, h)^{T} \in \mathcal{H}
$$

there exists $V=(u, v, z)^{T} \in D(\mathcal{A})$ such that $(I+\mathcal{A}) V=F$. That is,

$$
\left\{\begin{align*}
u-v & =f  \tag{2.5}\\
v-\Delta u-\mu_{1} \Delta v-\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| \Delta z(x, 1, s, t) d s & =g \\
s z+z_{\rho} & =s h
\end{align*}\right.
$$

As $z(., 0,)=.u-f=v$, by the third equation of (2.5), we infer that

$$
\begin{equation*}
z(., \rho, .)=(u-f) e^{-\rho s}+s e^{-\rho s} \int_{0}^{\rho} h(., \gamma, s) e^{\gamma s} d \gamma \tag{2.6}
\end{equation*}
$$

By substituting (2.6) in the second equation of (2.5), we have

$$
u-k \Delta u=G
$$

where

$$
\begin{align*}
k=1 & +\mu_{1}+\int_{\tau_{1}}^{\tau_{2}} e^{-s}\left|\mu_{2}(s)\right| d s>0, \\
G=g & +f-\left(\mu_{1}+\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| e^{-s} d s\right) \Delta f  \tag{2.7}\\
& +s \int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| e^{-s} \int_{0}^{1} \Delta h(\gamma, x) e^{\gamma s} d \gamma d s \in H^{-1}(\Omega) \tag{2.8}
\end{align*}
$$

We define, over $H_{0}^{1}(\Omega)$, the bilinear and linear forms:

$$
B(u, w)=\int_{\Omega} u w d x+k \int_{\Omega} \nabla u \nabla w d x, L(w)=\langle G, w\rangle_{H^{-1} \times H_{0}^{1}} .
$$

We see that $B$ is coercive and continuous, and $L$ is continuous on $H_{0}^{1}(\Omega)$.
Then, Lax-Milgram theorem specifies that the equation

$$
\begin{equation*}
B(u, w)=L(w), \forall w \in H_{0}^{1}(\Omega), \tag{2.9}
\end{equation*}
$$

has a unique solution $u \in H_{0}^{1}(\Omega)$. Thus, $v=u-f \in H_{0}^{1}(\Omega)$.
As a result, by (2.6), we obtain

$$
z, z_{\rho} \in L^{2}\left(\Omega \times(0,1) \times\left(\tau_{1}, \tau_{2}\right)\right) \text { and } z(., 0, .)=v
$$

Replacing $\Delta f$ by $\Delta(u-v)$ and $s e^{-s} \int_{0}^{1} \Delta h(\gamma, x) e^{\gamma s} d \gamma$ by $\Delta z(x, 1, s)-e^{-s} \Delta v$ in the right-hand side of (2.9) and utilizing the Green's formula, we get
$\int_{\Omega} u v+\int_{\Omega} \nabla\left(u+\mu_{1} v+\int_{\tau_{1}}^{\tau_{2}} \mu_{2}(s) e^{-s} z(x, 1, s) d s\right) \nabla w=\int_{\Omega}(f+g) w, \forall w \in H_{0}^{1}(\Omega)$.
From the standard elliptic regularity theory [6], we have

$$
u+\mu_{1} v+\int_{\tau_{1}}^{\tau_{2}} \mu_{2}(s) e^{-s} z(., 1, s) d s \in H^{2}(\Omega)
$$

Hence,

$$
\Delta\left(u+\mu_{1} v+\int_{\tau_{1}}^{\tau_{2}} \mu_{2}(s) e^{-s} z(., 1, s) d s\right)=g+f-u \in L^{2}(\Omega)
$$

Thus,

$$
V=(u, v, z)^{T} \in D(\mathcal{A})
$$

As a result, $I+\mathcal{A}$ is surjective and then $\mathcal{A}$ is maximal.
Finally, we denote that $J: \mathcal{H} \longrightarrow \mathcal{H}$ is locally Lipschitz. Hence, if we set:

$$
f(s)=|s|^{p-2} s \ln |s|^{k},|s| \neq 0 \text { and } f(s)=0,|s|=0
$$

then

$$
f^{\prime}(s)=k[1+(p-1) \ln |s|]|s|^{p-2},|s| \neq 0 \text { and } f^{\prime}(s)=0,|s|=0
$$

Thus,

$$
\begin{aligned}
\|J(\Phi)-J(\widetilde{\Phi})\|_{\mathcal{H}}^{2} & =\left\|\left(0,|u|^{p-2} u \ln |u|^{k}-|\widetilde{u}|^{p-2} \widetilde{u} \ln |\widetilde{u}|^{k}, 0\right)\right\|_{\mathcal{H}}^{2} \\
& =\left\||u|^{p-2} u \ln |u|^{k}-|\widetilde{u}|^{p-2} \widetilde{u} \ln |\widetilde{u}|^{k}\right\|_{L^{2}}^{2} \\
& =\|f(u)-f(\widetilde{u})\|_{L^{2}}^{2}
\end{aligned}
$$

By the mean value theorem, we obtain, for some $\theta \in[0,1]$,

$$
\begin{aligned}
|f(u)-f(\widetilde{u})|= & \left|f^{\prime}(\theta u+(1-\theta) \widetilde{u})(u-\widetilde{u})\right| \\
= & k \mid[1+(p-1) \ln \mid \theta u+(1-\theta) \widetilde{u}]]|\theta u+(1-\theta) \widetilde{u}|^{p-2}(u-\widetilde{u}) \mid \\
\leq & k[1+(p-1)|\ln | \theta u+(1-\theta) \widetilde{u}| |]|\theta u+(1-\theta) \widetilde{u}|^{p-2}|u-\widetilde{u}| \\
= & k(p-1)|\ln | \theta u+(1-\theta) \widetilde{u}| ||\theta u+(1-\theta) \widetilde{u}|^{p-2}|u-\widetilde{u}| \\
& \quad+k|\theta u+(1-\theta) \widetilde{u}|^{p-2}|u-\widetilde{u}| .
\end{aligned}
$$

To control the logarithmic term

$$
\ln |\theta u+(1-\theta) \widetilde{u}||\theta u+(1-\theta) \widetilde{u}|^{p-2},
$$

seems in the last inequality we remind that, for any $\varepsilon>0$,

$$
\lim _{|s| \rightarrow+\infty} \frac{\ln |s|}{|s|^{\varepsilon}}=0
$$

Then, there exists $B>0$ such that

$$
\frac{\ln |s|}{|s|^{\varepsilon}}<1, \forall|s|>B
$$

Hence, whenever $|\theta u+(1-\theta) \widetilde{u}|>B$, we get

$$
\ln |\theta u+(1-\theta) \widetilde{u}| \leq|\theta u+(1-\theta) \widetilde{u}|^{\varepsilon}
$$

and

$$
\ln |\theta u+(1-\theta) \widetilde{u}||\theta u+(1-\theta) \widetilde{u}|^{p-2} \leq|\theta u+(1-\theta) \widetilde{u}|^{p-2+\varepsilon} .
$$

Since $p>2$, then for some $A>0$ and $|\theta u+(1-\theta) \widetilde{u}| \leq B$, we obtain

$$
\ln |\theta u+(1-\theta) \widetilde{u}||\theta u+(1-\theta) \widetilde{u}|^{p-2} \leq A .
$$

Thus, we get

$$
\ln |\theta u+(1-\theta) \widetilde{u}||\theta u+(1-\theta) \widetilde{u}|^{p-2} \leq A+|\theta u+(1-\theta) \widetilde{u}|^{p-2+\varepsilon} .
$$

Then, we obtain the following estimation for

$$
\begin{align*}
& |f(u)-f(\widetilde{u})| \leq k(p-1)|\theta u+(1-\theta) \widetilde{u}|^{p-2+\varepsilon}|u-\widetilde{u}| \\
& \quad+k|\theta u+(1-\theta) \widetilde{u}|^{p-2}|u-\widetilde{u}|+k A(p-1)|u-\widetilde{u}| \\
& \leq k(p-1)(|u|+|\widetilde{u}|)^{p-2+\varepsilon}|u-\widetilde{u}|  \tag{2.10}\\
& \quad+k(|u|+|\widetilde{u}|)^{p-2}|u-\widetilde{u}|+k A(p-1)|u-\widetilde{u}| .
\end{align*}
$$

As $u, \widetilde{u} \in H_{0}^{1}(\Omega)$, by utilizing Hölder's inequality, (2.3) and the Sobolev embedding

$$
H_{0}^{1}(\Omega) \hookrightarrow L^{r}(\Omega), 1 \leq r \leq \frac{2 n}{n-2},
$$

to have

$$
\begin{aligned}
\int_{\Omega}[(|u|+ & \left.|\widetilde{u}|)^{p-2}|u-\widetilde{u}|\right]^{2} d x=\int_{\Omega}(|u|+|\widetilde{u}|)^{2(p-2)}|u-\widetilde{u}|^{2} d x \\
& \leq C\left(\int_{\Omega}(|u|+|\widetilde{u}|)^{2(p-1)} d x\right)^{\frac{p-2}{p-1}}\left(\int_{\Omega}|u-\widetilde{u}|^{2(p-1)} d x\right)^{\frac{1}{p-1}} \\
& \leq C\left[\|u\|_{L^{2(p-1)}(\Omega)}^{2(p-1)}+\|\widetilde{u}\|_{L^{2(p-1)}(\Omega)}^{2(p-1)}\right]^{\frac{p-2}{p-1}}\|u-\widetilde{u}\|_{L^{2(p-1)}(\Omega)}^{2} \\
& \leq C\left[\|u\|_{H_{0}^{1}(\Omega)}^{2(p-1)}+\|\widetilde{u}\|_{H_{0}^{1}(\Omega)}^{2(p-1)}\right]^{\frac{p-2}{p-1}}\|u-\widetilde{u}\|_{H_{0}^{1}(\Omega)}^{2}
\end{aligned}
$$

Similarly,

$$
\begin{aligned}
& \int_{\Omega}\left[(|u|+|\widetilde{u}|)^{p-2+\varepsilon}|u-\widetilde{u}|\right]^{2} d x=\int_{\Omega}(|u|+|\widetilde{u}|)^{2(p-2+\varepsilon)}|u-\widetilde{u}|^{2} d x \\
& \leq\left(\int_{\Omega}(|u|+|\widetilde{u}|)^{\frac{2(p-2+\varepsilon)(p-1)}{p-2}} d x\right)^{\frac{p-2}{p-1}}\left(\int_{\Omega}|u-\widetilde{u}|^{2(p-1)} d x\right)^{\frac{1}{p-1}} \\
& \leq\left(\int_{\Omega}(|u|+|\widetilde{u}|)^{2(p-1)+\frac{2 \varepsilon(p-1)}{p-2}} d x\right)^{\frac{p-2}{p-1}}\|u-\widetilde{u}\|_{L^{2(p-1)}(\Omega)}^{2}
\end{aligned}
$$

Since $p<\frac{2(n-1)}{n-2}$, by choosing $\varepsilon>0$ small enough, such that

$$
p^{*}=2(p-1)+\frac{2 \varepsilon(p-1)}{p-2} \leq \frac{2 n}{n-2}
$$

Thus, we get

$$
\begin{aligned}
\int_{\Omega}(|u|+|\widetilde{u}|)^{2(p-2+\varepsilon)}|u-\widetilde{u}|^{2} d x & \leq C\left[\|u\|_{L^{p^{*}}(\Omega)}^{p^{*}}+\|\widetilde{u}\|_{L^{p^{*}}(\Omega)}^{p^{*}}\right]^{\frac{p-2}{p-1}}\|u-\widetilde{u}\|_{L^{2(p-1)}(\Omega)}^{2} \\
& \leq C\left[\|u\|_{H_{0}^{1}(\Omega)}^{p^{*}}+\|\widetilde{u}\|_{H_{0}^{1}(\Omega)}^{p^{*}}\right]^{\frac{p-1}{p-1}}\|u-\widetilde{u}\|_{H_{0}^{1}(\Omega)}^{2} .
\end{aligned}
$$

Thus, by combining the last three estimations, we get

$$
\begin{aligned}
\|J(\Phi)-J(\widetilde{\Phi})\|_{\mathcal{H}^{2}}^{2} \leq & {\left[k^{2}(p-1)^{2} A^{2}\right]\|u-\widetilde{u}\|_{H_{0}^{1}(\Omega)}^{2} } \\
& +C\left[\left(\|u\|_{H_{0}^{1}(\Omega)}^{2(p-1)}+\|\widetilde{u}\|_{H_{0}^{1}(\Omega)}^{2(p-1)}\right)^{\frac{p-1}{p-1}}\right. \\
& \left.+\left(\|u\|_{H_{0}^{1}(\Omega)}^{p^{*}}+\|\widetilde{u}\|_{H_{0}^{1}(\Omega)}^{p^{*}}\right)^{\frac{p-1}{p-1}}\right]\|u-\widetilde{u}\|_{H_{0}^{1}(\Omega)}^{2} \\
\leq & C\left(\|u\|_{H_{0}^{1}(\Omega)},\|\widetilde{u}\|_{H_{0}^{1}(\Omega)}\right)\|u-\widetilde{u}\|_{H_{0}^{1}(\Omega)}^{2} .
\end{aligned}
$$

Hence, $J$ is locally Lipschitz. Then, as a consequence of the Theorem 1.2 page 184, Pazy [24] (see also a remark in the beginning of page 118, Komornik [17]), we complete the proof.

## 3. Global existence

In this section, we establish that the solution of (2.1) is uniformly bounded and global in time. The energy functional for the problem (2.1) is,

$$
\begin{align*}
E(t)= & \frac{1}{2}\left\|u_{t}\right\|^{2}+\frac{1}{2}\|\nabla u\|^{2}+\frac{k}{p^{2}}\|u\|_{p}^{p}-\frac{1}{p} \int_{\Omega}|u|^{p} \ln |u|^{k} d x \\
& +\frac{1}{2} \int_{\Omega} \int_{0}^{1} \int_{\tau_{1}}^{\tau_{2}} s\left|\mu_{2}(s)\right||\nabla z(x, \rho, s, t)|^{2} d s d \rho d x \tag{3.1}
\end{align*}
$$

The following lemma indicates that the energy functional is nonincreasing:
Lemma 1. The energy $E(t)$ satisfies, along the solution $(u, z)$ of $(2.1)$, the estimate

$$
\begin{equation*}
E^{\prime}(t) \leq-\left[\mu_{1}-\left(\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| d s\right)\right] \int_{\Omega}\left|\nabla u_{t}\right|^{2} d x<0 . \tag{3.2}
\end{equation*}
$$

Proof. Multiply the first equation in (2.1) by $u_{t}$ and integrate over $\Omega$ and the second equation in (2.1) by $-\left|\mu_{2}\right| \Delta z$ and integrate over $\Omega \times(0,1) \times\left(\tau_{1}, \tau_{2}\right)$, sum up, we obtain

$$
\begin{gathered}
\frac{d}{d t}\left[\begin{array}{c}
\frac{1}{2}\left\|u_{t}\right\|^{2}+\frac{1}{2}\|\nabla u\|^{2}+\frac{k}{p^{2}}\|u\|_{p}^{p}-\frac{1}{p} \int_{\Omega}|u|^{p} \ln |u|^{k} d x \\
+\frac{1}{2} \int_{\Omega} \int_{0}^{1} \int_{\tau_{1}}^{\tau_{2}} s\left|\mu_{2}(s)\right||\nabla z(x, \rho, s, t)|^{2} d s d \rho d x
\end{array}\right] \\
=-\mu_{1} \int_{\Omega}\left|\nabla u_{t}\right|^{2} d x-\int_{\Omega} \nabla u_{t} \int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| \nabla z(x, 1, s, t) d s d x
\end{gathered}
$$

$$
\begin{equation*}
-\left|\mu_{2}(s)\right| \int_{\Omega} \int_{0}^{1} \int_{\tau_{1}}^{\tau_{2}} \nabla z \nabla z_{\rho}(x, \rho, s, t) d s d \rho d x \tag{3.3}
\end{equation*}
$$

Now, we handle the last two terms of the right-hand side for (3.3) as:

$$
\begin{aligned}
&-\left|\mu_{2}(s)\right| \int_{\Omega} \\
& \int_{0}^{1} \int_{\tau_{1}}^{\tau_{2}} \nabla z \nabla z_{\rho}(x, \rho, s, t) d s d \rho d x \\
&=-\frac{\left|\mu_{2}(s)\right|}{2} \int_{\Omega} \int_{0}^{1} \int_{\tau_{1}}^{\tau_{2}} \frac{\partial}{\partial \rho}\left[|\nabla z(x, \rho, s, t)|^{2}\right] d s d \rho d x \\
&= \frac{1}{2}\left(\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| d s\right) \int_{\Omega}\left|\nabla u_{t}\right|^{2} d x \\
& \quad-\frac{\left|\mu_{2}(s)\right|}{2} \int_{\Omega} \int_{\tau_{1}}^{\tau_{2}}|\nabla z(x, 1, s, t)|^{2} d s d x
\end{aligned}
$$

and

$$
\begin{aligned}
& -\int_{\Omega} \nabla u_{t} \int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| \nabla z(x, 1, s, t) d s d x \\
& \quad \leq \frac{1}{2}\left(\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| d s \int_{\Omega}\left|\nabla u_{t}\right|^{2} d x+\left|\mu_{2}(s)\right| \int_{\Omega} \int_{\tau_{1}}^{\tau_{2}}|\nabla z(x, 1, s, t)|^{2} d s d x\right)
\end{aligned}
$$

Thus, we obtain

$$
\begin{aligned}
\frac{d E(t)}{d t} \leq- & \mu_{1} \int_{\Omega}\left|\nabla u_{t}\right|^{2} d x+\frac{1}{2}\left(\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| d s\right) \int_{\Omega}\left|\nabla u_{t}\right|^{2} d x \\
& -\frac{\left|\mu_{2}(s)\right|}{2} \int_{\Omega} \int_{\tau_{1}}^{\tau_{2}}|\nabla z(x, 1, s, t)|^{2} d s d x \\
& +\frac{1}{2}\left(\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| d s \int_{\Omega}\left|\nabla u_{t}\right|^{2} d x+\left|\mu_{2}(s)\right| \int_{\Omega} \int_{\tau_{1}}^{\tau_{2}}|\nabla z(x, 1, s, t)|^{2} d s d x\right)
\end{aligned}
$$

Therefore, we get

$$
E^{\prime}(t) \leq-\left[\mu_{1}-\left(\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| d s\right)\right] \int_{\Omega}\left|\nabla u_{t}\right|^{2} d x \leq 0
$$

Firstly, we set

$$
\begin{align*}
I(t)= & \|\nabla u\|^{2}-\int_{\Omega}|u|^{p} \ln |u|^{k} d x \\
J(t)= & \frac{1}{2} \int_{\Omega}|\nabla u|^{2} d x+\frac{k}{p^{2}}\|u\|_{p}^{p}-\frac{1}{p} \int_{\Omega}|u|^{p} \ln |u|^{k} d x \\
& +\frac{1}{2} \int_{\Omega} \int_{0}^{1} \int_{\tau_{1}}^{\tau_{2}} s\left|\mu_{2}(s)\right||\nabla z(x, \rho, s, t)|^{2} d s d \rho d x . \tag{3.4}
\end{align*}
$$

Thus, we obtain

$$
E(t)=J(t)+\frac{1}{2}\left\|u_{t}\right\|^{2}
$$

Lemma 2. Assume that the initial data $u_{0}, u_{1} \in H_{0}^{1}(\Omega) \times L^{2}(\Omega)$ satisfying

$$
\begin{equation*}
I(0)>0 \text { and } \beta=k C_{p+l}\left(\frac{2 p E(0)}{p-2}\right)^{\frac{p-2+l}{2}}<1 \tag{3.5}
\end{equation*}
$$

Then, $I(t)>0$, for any $t \in[0, T]$.
Proof. Since $I(0)>0$, we infer from continuity that there exists $T^{*} \leq T$ such that $I(t) \geq 0$ for all $t \in\left[0, T^{*}\right]$. This implies that, for all $t \in\left[0, T^{*}\right]$,

$$
\begin{aligned}
J(t)= & \frac{p-2}{2 p}\|\nabla u\|^{2}+\frac{k}{p^{2}}\|u\|_{p}^{p}+\frac{1}{p} I(t) \\
& +\frac{1}{2} \int_{\Omega} \int_{0}^{1} \int_{\tau_{1}}^{\tau_{2}} s\left|\mu_{2}(s) \| \nabla z(x, \rho, s, t)\right|^{2} d s d \rho d x
\end{aligned}
$$

Thus, we get

$$
J(t) \geq \frac{p-2}{2 p}\|\nabla u\|^{2}
$$

Therefore,

$$
\begin{equation*}
\|\nabla u\|^{2} \leq \frac{2 p}{p-2} J(t) \leq \frac{2 p}{p-2} E(t) \leq \frac{2 p}{p-2} E(0) \tag{3.6}
\end{equation*}
$$

On the other hand, by using the fact that $\ln |u|<|u|^{l}$, we obtain

$$
\begin{equation*}
\int_{\Omega}|u|^{p} \ln |u| d x \leq \int_{\Omega}|u|^{p+l} d x \tag{3.7}
\end{equation*}
$$

where $l$ is chosen to be $0<l<\frac{2}{n-2}$, such that

$$
p+l<\frac{2 n-2}{n-2}+l<\frac{2 n}{n-2}
$$

Hence, the embedding $H_{0}^{1}(\Omega) \hookrightarrow L^{p+l}(\Omega)$, satisfies

$$
\begin{align*}
\int_{\Omega}|u|^{p} \ln |u| d x & \leq C_{p+l}\|\nabla u\|^{p+l} \\
& =C_{p+l}\|\nabla u\|^{2}\|\nabla u\|^{p-2+l}=C_{p+l}\|\nabla u\|^{2}\left(\|\nabla u\|^{2}\right)^{\frac{p-2+l}{2}} \\
& \leq C_{p+l}\left(\frac{2 p E(0)}{p-2}\right)^{\frac{p-2+l}{2}}\|\nabla u\|^{2} \tag{3.8}
\end{align*}
$$

where $C_{p+l}$ is the embedding constant.
As a result, from (3.4) and (3.5), we have

$$
\begin{equation*}
I(t)>\|\nabla u\|^{2}-\beta\|\nabla u\|^{2}>0, \forall t \in\left[0, T^{*}\right] \tag{3.9}
\end{equation*}
$$

Therefore, $T^{*}$ can be extended to $T$.

Theorem 2. Assume that the initial data $u_{0}, u_{1}$ satisfy the conditions of Lemma 2, then the solution of (2.1) is uniformly bounded and global in time.

Proof. It suffices to indicate that $\|\nabla u\|^{2}+\left\|u_{t}\right\|^{2}$ is bounded independently of $t$. We have,

$$
\begin{aligned}
E(0) \geq & E(t)=\frac{1}{2}\left\|u_{t}\right\|^{2}+J(t) \geq \frac{1}{2}\left\|u_{t}\right\|^{2}+\frac{k}{p^{2}}\|u\|_{p}^{p}+\frac{1}{p} I(t) \\
& \quad+\frac{1}{2} \int_{\Omega} \int_{0}^{1} \int_{\tau_{1}}^{\tau_{2}} s\left|\mu_{2}(s)\right| \|\left.\nabla z(x, \rho, s, t)\right|^{2} d s d \rho d x \\
\geq & \frac{1}{2}\left\|u_{t}\right\|^{2}+\frac{1}{p}(1-\beta)\|\nabla u\|^{2} .
\end{aligned}
$$

Therefore,

$$
\|\nabla u\|^{2}+\left\|u_{t}\right\|^{2} \leq C E(0)
$$

where $C$ is a positive constant depending only on $k, p$ and $C_{p+1}$.

## 4. EXPONENTIAL DECAY

In this section, we establish the exponential decay results. Firstly, we give the lemmas as follows:

Lemma 3. [21] The functional

$$
F_{1}(t)=\int_{\Omega} \int_{0}^{1} \int_{\tau_{1}}^{\tau_{2}} s e^{-s \rho}\left|\mu_{2}(s)\right||\nabla z(x, \rho, s, t)|^{2} d s d \rho d x,
$$

satisfies, along the solution of (2.1),

$$
\begin{align*}
F_{1}^{\prime}(t) \leq & \left(\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| d s\right) \int_{\Omega}\left|\nabla u_{t}\right|^{2} d x-\int_{\Omega} \int_{\tau_{1}}^{\tau_{2}} e^{-s}\left|\mu_{2}(s)\right||\nabla z(x, 1, s, t)|^{2} d s d x \\
& -\int_{\Omega} \int_{\tau_{1}}^{\tau_{2}} s\left|\mu_{2}(s)\right| \int_{0}^{1} e^{-s \rho}|\nabla z(x, \rho, s, t)|^{2} d \rho d s d x \tag{4.1}
\end{align*}
$$

Lemma 4. The functional

$$
F_{2}(t)=N E(t)+\varepsilon \int_{\Omega} u u_{t} d x+\frac{\varepsilon \mu_{1}}{2} \int_{\Omega}|\nabla u|^{2} d x
$$

satisfies, along the solution of (2.1),

$$
\begin{align*}
F_{2}^{\prime}(t) \leq- & \left\{N\left[\mu_{1}-\left(\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| d s\right)\right]-\varepsilon\right\} \int_{\Omega}\left|\nabla u_{t}\right|^{2} d x \\
& -\varepsilon(1-\beta-\delta)\|\nabla u\|^{2}+\varepsilon \frac{c_{*}}{4 \delta} \int_{\Omega} \int_{\tau_{1}}^{\tau_{2}}|\nabla z(x, 1, s, t)|^{2} d s d x \tag{4.2}
\end{align*}
$$

where $N, \alpha$ and $\varepsilon$ are positive constants.

Proof. A direct differentiation, from the equations in (2.1), satisfies

$$
\begin{align*}
F_{2}^{\prime}(t) \leq-N & {\left[\mu_{1}-\left(\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| d s\right)\right] \int_{\Omega}\left|\nabla u_{t}\right|^{2} d x } \\
& +\varepsilon\left(\int_{\Omega}\left|u_{t}\right|^{2} d x-\int_{\Omega}|\nabla u|^{2} d x+\int_{\Omega}|u|^{p} \ln |u|^{k} d x\right) \\
& -\varepsilon \int_{\Omega} \int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| \nabla u \nabla z(x, 1, s, t) d s d x . \tag{4.3}
\end{align*}
$$

From the Young's inequality and the boundness property of $\mu_{2}(s)$, we get, for any $\delta>0$ and some $c_{*}>0$,

$$
\begin{align*}
-\int_{\Omega} \int_{\tau_{1}}^{\tau_{2}} & \left|\mu_{2}(s)\right| \nabla u \nabla z(x, 1, s, t) d s d x \\
& \leq \delta\|\nabla u\|^{2}+\frac{c_{*}}{4 \delta} \int_{\Omega} \int_{\tau_{1}}^{\tau_{2}}\left|\nabla_{z}(x, 1, s, t)\right|^{2} d s d x \tag{4.4}
\end{align*}
$$

Combining (3.7), (4.3) and (4.4), the result follows:
Theorem 3. Assume that (3.5) holds. Then, there exist two positive constants $c_{3}$ and $c_{4}$ such that

$$
E(t) \leq c_{3} e^{-c_{4} t} .
$$

Proof. By setting

$$
F_{3}(t)=F_{1}(t)+F_{2}(t) .
$$

It is easy to see, for $\varepsilon$ small enough, that

$$
\begin{equation*}
F_{3}(t) \sim E(t) \tag{4.5}
\end{equation*}
$$

From the (4.1) and (4.2), we get

$$
\begin{align*}
F_{3}^{\prime}(t) \leq & \left\{N\left[\mu_{1}-\left(\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| d s\right)\right]-\left(\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| d s\right)-\varepsilon\right\}\left\|\nabla u_{t}\right\|^{2} \\
& -\varepsilon(1-\beta-\delta)\|\nabla u\|^{2}-\left(e^{-s}\left|\mu_{2}(s)\right|-\varepsilon \frac{c_{*}}{4 \delta}\right) \int_{\Omega} \int_{\tau_{1}}^{\tau_{2}}|\nabla z(x, 1, s, t)|^{2} d s d x \\
& -\int_{\Omega} \int_{\tau_{1}}^{\tau_{2}} s\left|\mu_{2}(s)\right| \int_{0}^{1} e^{-s \rho}|\nabla z(x, \rho, s, t)|^{2} d \rho d s d x . \tag{4.6}
\end{align*}
$$

Since $\beta<1$, by choosing $\delta$ small enough, such that $\alpha=1-\beta-\delta>0$.
For some $\omega>0$, the embedding $H_{0}^{1}(\Omega) \hookrightarrow L^{p}(\Omega)$ satisfies

$$
\begin{aligned}
\|u\|_{p}^{p} & \leq C\|\nabla u\|_{2}^{p} \leq C\left(\|\nabla u\|^{2}\right)^{\frac{p-2}{2}}\|\nabla u\|^{2} \leq C(E(0))^{\frac{p-2}{2}}\|\nabla u\|^{2} \\
& \leq \omega\|\nabla u\|^{2},
\end{aligned}
$$

or

$$
-\frac{\varepsilon \alpha \omega^{-1}}{2}\|u\|_{p}^{p} \geq-\frac{\varepsilon \alpha}{2}\|\nabla u\|_{2}^{2}
$$

Therefore, (4.6) becomes the form

$$
\begin{align*}
F_{3}^{\prime}(t) & \leq-\left\{N\left[\mu_{1}-\left(\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| d s\right)\right]-\left(\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| d s\right)-\varepsilon\right\}\left\|\nabla u_{t}\right\|^{2} \\
& -\frac{\varepsilon \alpha}{2}\|\nabla u\|^{2}-\frac{\varepsilon \alpha \omega^{-1}}{2}\|u\|_{p}^{p}-\left(e^{-s}\left|\mu_{2}(s)\right|-\varepsilon \frac{c_{*}}{4 \delta}\right) \int_{\Omega} \int_{\tau_{1}}^{\tau_{2}}|\nabla z(x, 1, s, t)|^{2} d s d x \\
& -\int_{\Omega} \int_{\tau_{1}}^{\tau_{2}} s\left|\mu_{2}(s)\right| \int_{0}^{1} e^{-s \rho}|\nabla z(x, \rho, s, t)|^{2} d \rho d s d x \tag{4.7}
\end{align*}
$$

Whence $\delta$ is fixed, by choosing $N$ to be large enough, such that

$$
N\left[\mu_{1}-\left(\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| d s\right)\right]-\left(\int_{\tau_{1}}^{\tau_{2}}\left|\mu_{2}(s)\right| d s\right)-\varepsilon>0 \text { and } e^{-s}\left|\mu_{2}(s)\right|-\varepsilon \frac{c_{*}}{4 \delta}>0
$$

Hence, (4.7) takes the form, for some $C>0$,

$$
\begin{aligned}
F_{3}^{\prime}(t) \leq- & C\left[\left\|\nabla u_{t}\right\|^{2}+\|\nabla u\|^{2}+\|u\|_{p}^{p}\right. \\
& \left.+\int_{\Omega} \int_{0}^{1} \int_{\tau_{1}}^{\tau_{2}} s\left|\mu_{2}(s) \| \nabla z(x, \rho, s, t)\right|^{2} d s d \rho d x\right] \\
\leq- & C E(t)
\end{aligned}
$$

From the equivalence relation (4.5) and taking a simple integration over $(0, t)$, the result is established.

## Acknowledgement

The authors are grateful to DUBAP (ZGEF.20.009) for research funds.

## References

[1] R. A. Adams and J. J. F. Fournier, "Sobolev spaces," 2003.
[2] S. Antontsev, J. Ferreira, E. Pişkin, H. Yüksekkaya, and M. Shahrouzi, "Blow up and asymptotic behavior of solutions for a $p(x)$-Laplacian equation with delay term and variable exponents," Electron. J. Differ. Equ., vol. 2021, p. 20, 2021, id/No 84.
[3] K. Bartkowski and P. Górka, "One-dimensional Klein-Gordon equation with logarithmic nonlinearities," J. Phys. A, Math. Theor., vol. 41, no. 35, p. 11, 2008, id/No 355201, doi: 10.1088/17518113/41/35/355201.
[4] I. Białynicki-Birula and J. Mycielski, "Wave equations with logarithmic nonlinearities," Bull. Acad. Pol. Sci. Cl, vol. 3, no. 23, pp. 461-466, 1975.
[5] I. Bialynicki-Birula and J. Mycielski, "Nonlinear wave mechanics," Annals of Physics, vol. 100, no. 1, pp. 62-93, 1976, doi: https://doi.org/10.1016/0003-4916(76)90057-9.
[6] H. Brezis, Functional analysis, Sobolev spaces and partial differential equations, ser. Universitext. New York, NY: Springer, 2011.
[7] T. Cazenave and A. Haraux, "Equations d'évolution avec non linearite logarithmique," vol. 2," doi: 10.5802/afst.543, 1980, pp. 21-51.
[8] R. Datko, M. P. Polis, and J. Lagnese, "An example on the effect of time delays in boundary feedback stabilization of wave equations," SIAM J. Control Optim., vol. 24, pp. 152-156, 1986, doi: 10.1137/0324007.
[9] R. Datko, "Representation of solutions and stability of linear differential-difference equations in a Banach space," J. Differ. Equations, vol. 29, pp. 105-160, 1978, doi: 10.1016/0022-0396(78)90043-8.
[10] R. Datko, "Not all feedback stabilized hyperbolic systems are robust with respect to small time delays in their feedbacks," SIAM J. Control Optim., vol. 26, no. 3, pp. 697-713, 1988, doi: 10.1137/0326040.
[11] F. Gazzola and M. Squassina, "Global solutions and finite time blow up for damped semilinear wave equations," vol. 23, no. 2, doi: 10.1016/j.anihpc.2005.02.007, 2006, pp. 185-207.
[12] P. Górka, "Logarithmic Klein-Gordon equation," Acta Phys. Pol. B, vol. 40, no. 1, pp. 59-66, 2009.
[13] R. Ikehata, "Some remarks on the wave equations with nonlinear damping and source terms," Nonlinear Anal., Theory Methods Appl., vol. 27, no. 10, pp. 1165-1175, 1996, doi: 10.1016/0362-546X(95)00119-G.
[14] M. Kafini, "On the decay of a nonlinear wave equation with delay," Ann. Univ. Ferrara, Sez. VII, Sci. Mat., vol. 67, no. 2, pp. 309-325, 2021, doi: 10.1007/s11565-021-00366-6.
[15] M. Kafini and S. Messaoudi, "Local existence and blow up of solutions to a logarithmic nonlinear wave equation with delay," Appl. Anal., vol. 99, no. 3, pp. 530-547, 2020, doi: 10.1080/00036811.2018.1504029.
[16] M. Kafini and S. A. Messaoudi, "A blow-up result in a nonlinear wave equation with delay," Mediterr. J. Math., vol. 13, no. 1, pp. 237-247, 2016, doi: 10.1007/s00009-014-0500-4.
[17] V. Komornik, Exact controllability and stabilization. The multiplier method. Chichester: Wiley; Paris: Masson, 1994.
[18] W. Lian and R. Xu, "Global well-posedness of nonlinear wave equation with weak and strong damping terms and logarithmic source term," Adv. Nonlinear Anal., vol. 9, pp. 613-632, 2020, doi: 10.1515/anona-2020-0016.
[19] K. Liu, "Locally distributed control and damping for the conservative systems," SIAM J. Control Optim., vol. 35, no. 5, pp. 1574-1590, 1997, doi: 10.1137/S0363012995284928.
[20] L. Ma and Z. B. Fang, "Energy decay estimates and infinite blow-up phenomena for a strongly damped semilinear wave equation with logarithmic nonlinear source," Math. Methods Appl. Sci., vol. 41, no. 7, pp. 2639-2653, 2018, doi: 10.1002/mma.4766.
[21] S. A. Messaoudi, A. Fareh, and N. Doudi, "Well posedness and exponential stability in a wave equation with a strong damping and a strong delay," J. Math. Phys., vol. 57, no. 11, pp. 111 501, 13, 2016, doi: 10.1063/1.4966551.
[22] S. Nicaise and C. Pignotti, "Stability and instability results of the wave equation with a delay term in the boundary or internal feedbacks," SIAM J. Control Optim., vol. 45, no. 5, pp. 1561-1585, 2006, doi: 10.1137/060648891.
[23] S. Nicaise and C. Pignotti, "Stabilization of the wave equation with boundary or internal distributed delay." Differ. Integral Equ., vol. 21, no. 9-10, pp. 935-958, 2008.
[24] A. Pazy, Semigroups of linear operators and applications to partial differential equations, ser. Appl. Math. Sci. Springer, Cham, 1983, vol. 44, doi: 10.1007/978-1-4612-5561-1.
[25] E. Pişkin, J. Ferreira, H. Yüksekkaya, and M. Shahrouzi, "Existence and asymptotic behavior for a logarithmic viscoelastic plate equation with distributed delay," International Journal of Nonlinear Analysis and Applications, vol. 13, no. 2, pp. 763-788, 2022, doi: 10.22075/ijnaa.2022.24639.2797.
[26] E. Pişkin and B. Okutmuştur, An introduction to Sobolev spaces. Singapore: Bentham Science Publishers, 2021. doi: 10.2174/97816810891331210101.
[27] E. Piskin and H. Yüksekkaya, "Nonexistence of global solutions of a delayed wave equation with variable-exponents," Miskolc Math. Notes, vol. 22, no. 2, pp. 841-859, 2021, doi: 10.18514/MMN.2021.3487.
[28] D. H. Sattinger, "On global solution of nonlinear hyperbolic equations," Arch. Ration. Mech. Anal., vol. 30, pp. 148-172, 1968, doi: 10.1007/BF00250942.
[29] H. Yüksekkaya and E. Pişkin, "Blow-up results for a visoelastic plate equation with distributed delay," Journal of Universal Mathematics, vol. 4, no. 2, pp. 128-139, 2021, doi: 10.33773/jum. 957748.
[30] H. Yüksekkaya and E. Pişkin, "Nonexistence of global solutions for a Kirchhoff-type visoelastic equation with distributed delay," Journal of Universal Mathematics, vol. 4, no. 2, pp. 271-282, 2021, doi: 10.33773/jum. 957741.
[31] H. Yüksekkaya and E. Pişkin, "Blow-up of solutions of a logarithmic viscoelastic plate equation with delay term," Journal of Mathematical Sciences \& Computational Mathematics, vol. 3, no. 2, pp. 167-182, 2022, doi: $10.15864 / \mathrm{jmscm} .3203$.
[32] H. Yüksekkaya and E. Pişkin, "Growth of solutions for a delayed kirchhoff-type viscoelastic equation," Journal of Mathematical Sciences \& Computational Mathematics, vol. 3, no. 2, pp. 234246, 2022, doi: 10.15864/jmscm. 3209.
[33] H. Yüksekkaya, E. Pişkin, S. M. Boulaaras, and B. B. Cherif, "Existence, decay, and blow-up of solutions for a higher-order Kirchhoff-type equation with delay term," J. Funct. Spaces, vol. 2021, p. 11, 2021, id/No 4414545, doi: 10.1155/2021/4414545.
[34] H. Yüksekkaya, E. Pişkin, S. M. Boulaaras, B. B. Cherif, and S. A. Zubair, "Existence, nonexistence, and stability of solutions for a delayed plate equation with the logarithmic source," $A d v$. Math. Phys., vol. 2021, p. 11, 2021, id/No 8561626, doi: 10.1155/2021/8561626.
[35] E. Zuazua, "Exponential decay for the semilinear wave equation with locally distributed damping," Commun. Partial Differ. Equations, vol. 15, no. 2, pp. 205-235, 1990, doi: 10.1080/03605309908820684.

## Authors' addresses

## Hazal Yüksekkaya

(Corresponding author) Dicle University, Department of Mathematics, Diyarbakir, Turkey
E-mail address: hazally.kaya@gmail.com

## Erhan Pişkin

Dicle University, Department of Mathematics, Diyarbakir, Turkey
E-mail address: episkin@dicle.edu.tr

