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# On common fixed point theorems for $(\psi, \phi)$ -generalized $f$ -weakly contractive mappings

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## ON COMMON FIXED POINT THEOREMS FOR $(\psi, \varphi)$ -GENERALIZED $f$ -WEAKLY CONTRACTIVE MAPPINGS

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**Abstract.** In this paper, we present some common fixed point theorems for  $(\psi, \varphi)$ -generalized  $f$ -weakly contractive mappings in metric and ordered metric spaces. Our results extend, generalize and improve some well-known results in the literature. Also, we give an example to illustrate our results.

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### 1. INTRODUCTION AND PRELIMINARIES

The first important result on fixed points for contractive type mapping was the much celebrated Banach's contraction principle by Banach [2] in 1922. After this, Kannan [9, 10] proved the following result:

**Theorem 1.** *Let  $(X, d)$  be a complete metric space. If  $T : X \rightarrow X$  satisfies*

$$d(Tx, Ty) \leq k[d(x, Tx) + d(y, Ty)],$$

*where  $0 < k < \frac{1}{2}$  and  $x, y \in X$ , then  $T$  has a unique fixed point.*

A similar type of contractive condition has been studied by Chatterjee [5] and he proved the following result:

**Theorem 2.** *Let  $(X, d)$  be a complete metric space. If  $T : X \rightarrow X$  satisfies a  $C$ -contraction given as follows:*

$$d(Tx, Ty) \leq k[d(x, Ty) + d(y, Tx)],$$

*where  $0 < k < \frac{1}{2}$  and  $x, y \in X$ , then  $T$  has a unique fixed point.*

Alber and Guerre-Delabriere [1] introduced the definition of weak  $\Phi$ -contraction.

**Definition 1.** A self mapping  $T$  on a metric space  $X$  is called weak  $\Phi$ -contraction if there exists a function  $\Phi : [0, +\infty) \rightarrow [0, +\infty)$  such that for each  $x, y \in X$ ,

$$d(Tx, Ty) \leq d(x, y) - \Phi(d(x, y)).$$

The notion of  $\Phi$ -contraction and weak  $\Phi$ -contraction has been studied by many authors, see [3, 12, 15, 17, 19]. In recent years, many results related to fixed point theorems in partially ordered metric spaces are given, for more details see [8, 12–16].

Choudhury in [6] introduced a generalization of  $C$ -contraction given by the following definition.

**Definition 2** ([6]). Let  $(X, d)$  be a metric space. A mapping  $T : X \rightarrow X$  is said to be weakly  $C$ -contractive (or a weak  $C$ -contraction) if for all  $x, y \in X$ ,

$$d(Tx, Ty) \leq \frac{1}{2}(d(x, Ty) + d(y, Tx)) - \varphi(d(x, Ty), d(y, Tx)),$$

where  $\varphi : [0, +\infty) \rightarrow [0, +\infty)$  is a continuous function such that  $\varphi(x, y) = 0$  if and only  $x = y = 0$ .

In [6] the author proves that if  $X$  is complete then every weak  $C$ -contraction has a unique fixed point. Recently, Harjani et al, [8] presented this last result in the context of ordered metric spaces.

Chandok [4] introduced the following definition : A map  $T : X \rightarrow X$  is generalized  $f$ -weakly contractive if for each  $x, y \in X$ ,

$$d(Tx, Ty) \leq \frac{1}{2}(d(fx, Ty) + d(fy, Tx)) - \varphi(d(fx, Ty), d(fy, Tx)),$$

where  $\varphi : [0, +\infty) \rightarrow [0, +\infty) \rightarrow [0, +\infty)$  is a continuous function such that  $\varphi(x, y) = 0$  if and only  $x = y = 0$ .

If  $f = I_X$ , the identity mapping, then generalized  $f$ -weakly contractive mapping is weakly  $C$ -contractive.

Khan et al. [11] introduced the concept of altering distance function as follows:

**Definition 3** (altering distance function, [11]). The function  $\psi : [0, +\infty) \rightarrow [0, +\infty)$  is called an altering distance function if the following properties are satisfied:

- (1)  $\psi$  is continuous and non-decreasing.
- (2)  $\psi(t) = 0$  if and only if  $t = 0$ .

Following the above definitions, we introduce the following:

**Definition 4.** A map  $T : X \rightarrow X$  is called  $(\psi, \varphi)$ -generalized  $f$ -weakly contractive if for each  $x, y \in X$ ,

$$\psi(d(Tx, Ty)) \leq \psi\left(\frac{1}{2}[d(fx, Ty) + d(fy, Tx)]\right) - \varphi(d(fx, Ty), d(fy, Tx)),$$

where

- (1)  $\psi : [0, +\infty) \rightarrow [0, +\infty)$  is an altering distance function.
- (2)  $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$  is a continuous function with  $\varphi(t, s) = 0$  if and only if  $t = s = 0$ .

If  $\psi(t) = t$ , then  $(\psi, \varphi)$ -generalized  $f$ -weakly contractive mapping is generalized  $f$ -weakly contractive.

The aim of this paper is to study some common fixed point theorems for  $(\psi, \varphi)$ -generalized  $f$ -weakly contractive in metric and ordered metric spaces.

## 2. MAIN RESULTS

First, we state the following known definition:

**Definition 5.** Let  $X$  a non-empty set. A point  $x \in X$  is a coincidence point (common fixed point) of  $f : X \rightarrow X$  and  $T : X \rightarrow X$  if  $fx = Tx$  ( $x = fx = Tx$ ). The pair  $\{f, T\}$  is called commuting if  $Tfx = fTx$  for all  $x \in X$ .

We start with a common fixed point theorem for  $(\psi, \varphi)$ -generalized  $f$ -weakly contractive mappings in complete metric spaces.

**Theorem 3.** Let  $(X, d)$  be a metric space. Let  $f, T : X \rightarrow X$  satisfy  $T(X) \subset f(X)$ ,  $(f(X), d)$  is complete and

$$\psi(d(Tx, Ty)) \leq \psi\left(\frac{1}{2}[d(fx, Ty) + d(fy, Tx)]\right) - \varphi(d(fx, Ty), d(fy, Tx)), \quad (2.1)$$

for all  $x, y \in X$ , where

- (1)  $\psi : [0, +\infty) \rightarrow [0, +\infty)$  is an altering distance function,
- (2)  $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$  is a continuous function with  $\varphi(t, s) = 0$  if and only if  $t = s = 0$ , then  $T$  and  $f$  have a coincidence point in  $X$ . Further, if  $T$  and  $f$  commute at their coincidence points, then  $T$  and  $f$  have a common fixed point.

*Proof.* Let  $x_0 \in X$ . Since  $T(X) \subset f(X)$ , we can choose  $x_1 \in X$ , so that  $fx_1 = Tx_0$ . Since  $Tx_1 \in f(X)$ , there exists  $x_2 \in X$  such that  $fx_2 = Tx_1$ . By induction, we construct a sequence  $\{x_n\}$  in  $X$  such that  $fx_{n+1} = Tx_n$ , for every  $n \in \mathbb{N}$ . By inequality (2.1), we have

$$\begin{aligned} \psi(d(Tx_{n+1}, Tx_n)) &\leq \psi\left(\frac{1}{2}[d(fx_{n+1}, Tx_n) + d(fx_n, Tx_{n+1})]\right) \\ &\quad - \varphi(d(fx_{n+1}, Tx_n), d(fx_n, Tx_{n+1})) \\ &= \psi\left(\frac{1}{2}d(Tx_{n-1}, Tx_{n+1})\right) - \varphi(0, d(Tx_{n-1}, Tx_{n+1})) \\ &\leq \psi\left(\frac{1}{2}d(Tx_{n-1}, Tx_{n+1})\right) \\ &\leq \psi\left(\frac{1}{2}[d(Tx_{n-1}, Tx_n) + d(Tx_n, Tx_{n+1})]\right). \end{aligned} \quad (2.2)$$

Since  $\psi$  is a non-decreasing function, we get that

$$d(Tx_n, Tx_{n+1}) \leq d(Tx_{n-1}, Tx_n) \quad \text{for any } n \in \mathbb{N}^*. \quad (2.3)$$

Thus,  $\{d(Tx_n, Tx_{n+1})\}$  is a monotone non-increasing sequence of non-negative real numbers and hence is convergent. Hence there is  $r \geq 0$  such that

$$\lim_{n \rightarrow +\infty} d(Tx_n, Tx_{n+1}) = r.$$

Using a triangular inequality, we have

$$d(Tx_{n+1}, Tx_n) \leq \frac{1}{2}d(Tx_{n-1}, Tx_{n+1}) \leq \frac{1}{2}[d(Tx_{n-1}, Tx_n) + d(Tx_n, Tx_{n+1})].$$

Letting  $n \rightarrow +\infty$ , we get

$$r \leq \frac{1}{2} \lim_{n \rightarrow +\infty} d(Tx_{n-1}, Tx_{n+1}) \leq \frac{1}{2}r + \frac{1}{2}r,$$

that is  $\lim_{n \rightarrow +\infty} d(Tx_{n-1}, Tx_{n+1}) = 2r$ . Using the continuity of  $\psi$  and  $\varphi$ , and inequality (2.2), we have, letting  $n \rightarrow +\infty$

$$\psi(r) \leq \psi(r) - \varphi(0, 2r),$$

and consequently,  $\varphi(0, 2r) \leq 0$ . Thus, by a property of  $\varphi$ ,  $r = 0$ , so

$$\lim_{n \rightarrow +\infty} d(Tx_{n+1}, Tx_n) = 0. \quad (2.4)$$

Now, we show that  $\{Tx_n\}$  is a Cauchy sequence. If otherwise, then there exists  $\varepsilon > 0$  for which we can find subsequences  $\{Tx_{m(k)}\}$  and  $\{Tx_{n(k)}\}$  of  $\{Tx_n\}$  with  $n(k) > m(k) > k$  such that for every  $k$ ,

$$d(Tx_{m(k)}, Tx_{n(k)}) \geq \varepsilon, \quad d(Tx_{m(k)}, Tx_{n(k)-1}) < \varepsilon. \quad (2.5)$$

By triangular inequality, we have from (2.5)

$$\begin{aligned} \varepsilon &\leq d(Tx_{m(k)}, Tx_{n(k)}) \\ &\leq d(Tx_{m(k)}, Tx_{n(k)-1}) + d(Tx_{n(k)-1}, Tx_{n(k)}) \\ &< \varepsilon + d(Tx_{n(k)-1}, Tx_{n(k)}). \end{aligned}$$

Using (2.4), we get

$$\lim_{k \rightarrow +\infty} d(Tx_{m(k)}, Tx_{n(k)}) = \lim_{k \rightarrow +\infty} d(Tx_{m(k)}, Tx_{n(k)-1}) = \varepsilon. \quad (2.6)$$

On the other hand,

$$\begin{aligned} d(Tx_{m(k)}, Tx_{n(k)-1}) &\leq d(Tx_{m(k)}, Tx_{m(k)-1}) + d(Tx_{m(k)-1}, Tx_{n(k)}) \\ &\quad + d(Tx_{n(k)}, Tx_{n(k)-1}), \end{aligned}$$

and

$$d(Tx_{m(k)-1}, Tx_{n(k)}) \leq d(Tx_{m(k)-1}, Tx_{m(k)}) + d(Tx_{m(k)}, Tx_{n(k)}).$$

Letting  $k \rightarrow +\infty$  in the two above inequalities, we have thanks to (2.4) and (2.6),

$$\lim_{k \rightarrow +\infty} d(Tx_{m(k)-1}, Tx_{n(k)}) = \varepsilon. \quad (2.7)$$

From (2.1), we have

$$\begin{aligned}
 \psi(\varepsilon) &\leq \psi(d(Tx_{m(k)}, Tx_{n(k)})) \\
 &\leq \psi\left(\frac{1}{2}[d(fx_{m(k)}, Tx_{n(k)}) + d(fx_{n(k)}, Tx_{m(k)})]\right) \\
 &\quad - \varphi(d(fx_{m(k)}, Tx_{n(k)}), d(fx_{n(k)}, Tx_{m(k)})) \\
 &= \psi\left(\frac{1}{2}[d(Tx_{m(k)-1}, Tx_{n(k)}) + d(Tx_{n(k)-1}, Tx_{m(k)})]\right) \\
 &\quad - \varphi(d(Tx_{m(k)-1}, Tx_{n(k)}), d(Tx_{n(k)-1}, Tx_{m(k)})).
 \end{aligned}$$

Taking  $k \rightarrow +\infty$ , using the continuity of  $\psi$  and  $\varphi$ , we obtain from (2.6), (2.7)

$$\psi(\varepsilon) \leq \psi(\varepsilon) - \varphi(\varepsilon, \varepsilon),$$

hence  $\varphi(\varepsilon, \varepsilon) = 0$ , so  $\varepsilon = 0$ , it is a contradiction. Thus  $\{Tx_n\}$  is a Cauchy sequence. Since  $fx_n = Tx_{n-1}$ , hence  $\{fx_n\}$  is a Cauchy sequence in  $(f(X), d)$ , which is complete. Thus there is  $z \in X$  such that

$$\lim_{n \rightarrow +\infty} fx_n = fz. \quad (2.8)$$

Moreover, (2.4) reads

$$\lim_{n \rightarrow +\infty} d(fx_n, fx_{n+1}) = 0. \quad (2.9)$$

By (2.1), we have

$$\begin{aligned}
 \psi(d(Tz, fx_{n+1})) &= \psi(d(Tz, Tx_n)) \\
 &\leq \psi\left(\frac{1}{2}[d(fz, Tx_n) + d(fx_n, Tz)]\right) - \varphi(d(fz, Tx_n), d(fx_n, Tz)) \\
 &= \psi\left(\frac{1}{2}[d(fz, fx_{n+1}) + d(fx_n, Tz)]\right) - \varphi(d(fz, fx_{n+1}), d(fx_n, Tz)),
 \end{aligned}$$

and letting  $n \rightarrow +\infty$ , using the continuity of  $\psi$  and  $\varphi$  and by (2.8), (2.9), we find

$$\psi(d(Tz, fz)) \leq \psi\left(\frac{1}{2}d(Tz, fz)\right) - \varphi(0, d(fz, Tz)) \leq \psi\left(\frac{1}{2}d(Tz, fz)\right).$$

Consequently,  $d(Tz, fz) \leq \frac{1}{2}d(Tz, fz)$ , that is,  $d(Tz, fz) = 0$ , i.e.  $Tz = fz$ , hence  $z$  is a coincidence point of  $T$  and  $f$ . Now suppose that  $T$  and  $f$  commute at  $z$ . Let  $w = Tz = fz$ . Then  $Tw = T(fz) = f(Tz) = fw$ . By inequality (2.1)

$$\begin{aligned}
 \psi(d(Tz, Tw)) &\leq \psi\left(\frac{1}{2}[d(fz, Tw) + d(fw, Tz)]\right) - \varphi(d(fz, Tw), d(fw, Tz)) \\
 &= \psi\left(\frac{1}{2}[d(Tz, Tw) + d(Tw, Tz)]\right) - \varphi(d(Tz, Tw), d(Tw, Tz)) \\
 &= \psi\left(\frac{1}{2}[d(Tz, Tw) + d(Tw, Tz)]\right) - \varphi(d(Tz, Tw), d(Tw, Tz)) \\
 &= \psi(d(Tz, Tw)) - \varphi(d(Tz, Tw), d(Tw, Tz)).
 \end{aligned}$$

This implies that  $d(Tz, Tw) = 0$ , by the property of  $\varphi$ . Therefore,  $Tw = fw = w$ . This completes the proof of Theorem 3.  $\square$

*Example 1.* Let  $X = [0, +\infty)$ . Let  $d$  be defined by  $d(x, y) = |x - y|$  for all  $x, y \in X$ . We set  $fx = \frac{x}{2}$  and  $Tx = \frac{x}{4}$  for all  $x \in X$ . It is clear that  $T(X) \subset f(X)$  and  $(f(X), d)$  is a complete metric space. Define  $\psi : [0, +\infty) \rightarrow [0, +\infty)$  and  $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$  by

$$\psi(t) = \frac{t}{2} \quad \text{and} \quad \varphi(t, s) = \frac{1}{16}(t + s).$$

It is obvious that  $\psi$  and  $\varphi$  satisfy the hypotheses of Theorem 3. We need to show that the inequality (2.1) holds for any  $x, y \in X$ . First, the left-hand side of (2.1) is

$$\psi(d(Tx, Ty)) = \frac{1}{8}|x - y|. \quad (2.10)$$

While, the right-hand side of (2.1) is

$$\begin{aligned} & \psi\left(\frac{1}{2}(d(fx, Ty) + d(fy, Tx))\right) - \varphi(d(fx, Ty), d(fy, Tx)) \\ &= \frac{1}{4}\left[\left|\frac{x}{2} - \frac{y}{4}\right| + \left|\frac{y}{2} - \frac{x}{4}\right|\right] - \frac{1}{16}\left[\left|\frac{x}{2} - \frac{y}{4}\right| + \left|\frac{y}{2} - \frac{x}{4}\right|\right] \\ &= \frac{3}{16}\left[\left|\frac{x}{2} - \frac{y}{4}\right| + \left|\frac{y}{2} - \frac{x}{4}\right|\right]. \end{aligned} \quad (2.11)$$

By symmetry of (2.10) and (2.11), and without loss of generality, we suppose that  $x \geq y$ . In particular, (2.10) reads

$$\psi(d(Tx, Ty)) = \frac{1}{8}(x - y).$$

We distinguish two cases:

- If  $2y \geq x$ . Here, we have from (2.11)

$$\begin{aligned} & \psi\left(\frac{1}{2}(d(fx, Ty) + d(fy, Tx))\right) - \varphi(d(fx, Ty), d(fy, Tx)) \\ &= \frac{3}{16}\left[\left|\frac{x}{2} - \frac{y}{4}\right| + \left|\frac{y}{2} - \frac{x}{4}\right|\right] = \frac{3}{16}\left[\left(\frac{x}{2} - \frac{y}{4}\right) + \left(\frac{y}{2} - \frac{x}{4}\right)\right] \\ &= \frac{3}{64}(x + y) \geq \frac{1}{8}(x - y) = \psi(d(Tx, Ty)). \end{aligned} \quad (2.12)$$

- If  $2y < x$ . Here, we have from (2.11)

$$\begin{aligned} & \psi\left(\frac{1}{2}(d(fx, Ty) + d(fy, Tx))\right) - \varphi(d(fx, Ty), d(fy, Tx)) \\ &= \frac{3}{16}\left[\left|\frac{x}{2} - \frac{y}{4}\right| + \left|\frac{y}{2} - \frac{x}{4}\right|\right] = \frac{3}{16}\left[\left(\frac{x}{2} - \frac{y}{4}\right) + \left(-\frac{y}{2} + \frac{x}{4}\right)\right] \\ &= \frac{9}{64}(x - y) \geq \frac{1}{8}(x - y) = \psi(d(Tx, Ty)). \end{aligned} \quad (2.13)$$

By (2.12) and (2.13), the inequality (2.1) is satisfied. Then by Theorem 3,  $T$  and  $f$  have a common fixed point, which is  $z = 0$ .

**Corollary 1.** *Let  $(X, d)$  be a complete metric space. If  $T : X \rightarrow X$  satisfies*

$$\psi(d(Tx, Ty)) \leq \psi\left(\frac{1}{2}[d(x, Ty) + d(y, Tx)]\right) - \varphi(d(x, Ty), d(y, Tx)), \quad (2.14)$$

for all  $x, y \in X$ , where

- (1)  $\psi : [0, +\infty) \rightarrow [0, +\infty)$  is an altering distance function,
- (2)  $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$  is a continuous function with  $\varphi(t, s) = 0$  if and only if  $t = s = 0$ , then  $T$  has a unique fixed point.

*Proof.* It follows by taking  $f = I_X$  in Theorem 3. The uniqueness of the fixed point follows by the following: suppose  $u$  and  $v$  are fixed points of  $T$ . By (2.14), we have

$$\begin{aligned} \psi(d(u, v)) &= \psi(d(Tu, Tv)) \\ &\leq \psi\left(\frac{1}{2}[d(u, Tv) + d(v, Tu)]\right) - \varphi(d(u, Tv), d(v, Tu)) \\ &= \psi\left(\frac{1}{2}[d(u, v) + d(v, u)]\right) - \varphi(d(u, v), d(v, u)) \\ &= \psi(d(u, v)) - \varphi(d(u, v), d(v, u)), \end{aligned}$$

which implies that  $\varphi(d(u, v), d(v, u)) = 0$ , and by a property of  $\varphi$ , we get  $u = v$ .  $\square$

**Corollary 2.** *Let  $(X, d)$  be a metric space. If  $T, f : X \rightarrow X$  are such that  $T(X) \subset f(X)$ ,  $(f(X), d)$  is complete and*

$$d(Tx, Ty) \leq \frac{1}{2}[d(fx, Ty) + d(fy, Tx)] - \varphi(d(fx, Ty), d(fy, Tx)), \quad (2.15)$$

for all  $x, y \in X$ , where  $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$  is a continuous function with  $\varphi(t, s) = 0$  if and only if  $t = s = 0$ , then  $T$  and  $f$  have a coincidence point in  $X$ . Further, if  $T$  and  $f$  commute at their coincidence points, then  $T$  and  $f$  have a common fixed point.

*Proof.* The proof follows by taking  $\psi(t) = t$  in Theorem 3.  $\square$

**Corollary 3.** *Let  $(X, d)$  be a complete metric space. If  $T : X \rightarrow X$  satisfies for all  $x, y \in X$*

$$d(Tx, Ty) \leq \frac{1}{2}[d(x, Ty) + d(y, Tx)] - \varphi(d(x, Ty), d(y, Tx)), \quad (2.16)$$

where  $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$  is a continuous function with  $\varphi(t, s) = 0$  if and only if  $t = s = 0$ , then  $T$  has a unique fixed point.

*Proof.* It follows by taking  $f = Id_X$  in Corollary 2. The uniqueness of the fixed point follows from Corollary 1.  $\square$



- Remark 1.*
- Corollary 1 corresponds to Corollary 2.1 of Shatanawi [18].
  - Corollary 2 corresponds to Theorem 1 of Chandok [4].
  - Corollary 3 corresponds to Theorem 2.1 of Choudhury [6].

Now, we extend Theorem 3 and we prove a common fixed point theorem for  $f$ -non-decreasing generalized nonlinear contraction mappings in the context of ordered metric spaces.

**Definition 6** ([7]). Suppose  $(X, \leq)$  is a partially ordered set and  $T, f : X \rightarrow X$ .  $T$  is said to be monotone  $f$ -nondecreasing if for all  $x, y \in X$ ,

$$fx \leq fy \quad \text{implies} \quad Tx \leq Ty. \quad (2.17)$$

If  $f = I_X$  in Definition 6, then  $T$  is monotone non-decreasing.

**Theorem 4.** Let  $(X, \leq)$  be a partially ordered set and suppose that there exists a metric  $d$  on  $X$  such that  $(X, d)$  is a complete metric space. Let  $f$  and  $T$  are self-mappings of  $X$  such that  $T(X) \subset f(X)$ ,  $f(X)$  is closed and  $T$  is  $f$ -non-decreasing mapping. Suppose that  $f$  and  $T$  satisfy for all  $x, y \in X$ , for which  $f(x) \leq f(y)$

$$\psi(d(Tx, Ty)) \leq \psi\left(\frac{1}{2}[d(fx, Ty) + d(fy, Tx)]\right) - \varphi(d(fx, Ty), d(fy, Tx)) \quad (2.18)$$

where

- (1)  $\psi : [0, +\infty) \rightarrow [0, +\infty)$  is an altering distance function,
- (2)  $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$  is a continuous function with  $\varphi(x, y) = 0$  if and only if  $x = y = 0$ .

Also, suppose that if  $\{f(x_n)\} \subset X$  is a non-decreasing sequence with  $f(x_n) \rightarrow f(z)$  in  $f(X)$ , then  $f(x_n) \leq f(z)$  and  $f(z) \leq f(f(z))$  for every  $n$ .

If there exists  $x_0 \in X$  with  $fx_0 \leq Tx_0$ , then  $T$  and  $f$  have a coincidence point. Further, if  $T$  and  $f$  commute at their coincidence points, then  $T$  and  $f$  have a common fixed point.

*Proof.* Let  $x_0 \in X$  such that  $fx_0 \leq Tx_0$ . Since  $T(X) \subset f(X)$ , we can choose  $x_1 \in X$ , so that  $fx_1 = Tx_0$ . Since  $Tx_1 \in f(X)$ , there exists  $x_2 \in X$  such that  $fx_2 = Tx_1$ . By induction, we construct a sequence  $\{x_n\}$  in  $X$  such that

$$fx_{n+1} = Tx_n.$$

Since  $fx_0 \leq Tx_0$ ,  $Tx_0 = fx_1$ , so  $fx_0 \leq fx_1$ .  $T$  is  $f$ -non-decreasing mapping, we get  $Tx_0 \leq Tx_1$ . Similarly  $fx_1 \leq fx_2$ ,  $Tx_1 \leq Tx_2$ , hence  $fx_2 \leq fx_3$ . Continuing, we obtain

$$fx_0 \leq fx_1 \leq fx_2 \leq \dots \leq fx_n \leq fx_{n+1} \leq \dots$$

If for some  $n$ ,  $Tx_{n+1} = Tx_n$ , then  $Tx_{n+1} = fx_{n+1}$ , i.e.  $T$  and  $f$  have a coincidence point  $x_{n+1}$ , and so we have the result. For the rest, assume that  $d(Tx_n, Tx_{n+1}) > 0$

for all  $n \in \mathbb{N}$ . By (2.18), we have

$$\begin{aligned}
 \psi(d(Tx_n, Tx_{n+1})) &\leq \psi\left(\frac{1}{2}[d(fx_{n+1}, Tx_n) + d(fx_n, Tx_{n+1})]\right) \\
 &\quad - \varphi(d(fx_{n+1}, Tx_n), d(fx_n, Tx_{n+1})) \\
 &= \psi\left(\frac{1}{2}d(Tx_{n-1}, Tx_{n+1})\right) - \varphi(0, d(Tx_{n-1}, Tx_{n+1})) \\
 &\leq \psi\left(\frac{1}{2}d(Tx_{n-1}, Tx_{n+1})\right) \\
 &\leq \psi\left(\frac{1}{2}d(Tx_{n-1}, Tx_n) + \frac{1}{2}d(Tx_n, Tx_{n+1})\right).
 \end{aligned}$$

It follows that, for any  $n \in \mathbb{N}^*$

$$d(Tx_n, Tx_{n+1}) \leq d(Tx_{n-1}, Tx_n).$$

Thus  $\{d(Tx_n, Tx_{n+1})\}$  is a monotone non-increasing sequence, hence it is convergent. Now, proceeding as in Theorem 3, we can prove that

$$\lim_{n \rightarrow +\infty} d(Tx_n, Tx_{n+1}) = 0. \quad (2.19)$$

Moreover,  $\{Tx_n\}$  is a Cauchy sequence. Since  $Tx_n = fx_{n+1}$  and  $f(X)$  is closed, so there exists  $z \in X$  such that

$$\lim_{n \rightarrow +\infty} fx_n = fz. \quad (2.20)$$

Having in mind  $\{fx_n\}$  is a non-decreasing sequence, so by (2.20) we have for every  $n \in \mathbb{N}$

$$fx_n \leq fz, \quad f(z) \leq f(fz). \quad (2.21)$$

Having  $fx_n \leq fz$ , so from inequality (2.18), we have

$$\begin{aligned}
 \psi(d(fx_{n+1}, Tz)) &= \psi(d(Tx_n, Tz)) \\
 &\leq \psi\left(\frac{1}{2}[d(fz, Tx_n) + d(fx_n, Tz)]\right) - \varphi(d(fz, Tx_n), d(fx_n, Tz)) \\
 &= \psi\left(\frac{1}{2}[d(fz, fx_{n+1}) + d(fx_n, Tz)]\right) - \varphi(d(fz, fx_{n+1}), d(fx_n, Tz)).
 \end{aligned}$$

Taking  $n \rightarrow +\infty$ , using the continuity of  $\psi$  and  $\varphi$ , we get from (2.19), (2.20)

$$\psi(d(Tz, fz)) \leq \psi\left(\frac{1}{2}d(fz, fz)\right) - \varphi(0, d(fz, Tz)),$$

that is,  $d(Tz, fz) = 0$ , hence  $Tz = fz$ , so  $z$  is a coincidence point of  $T$  and  $f$ .

Now suppose that  $T$  and  $f$  commute at  $z$ . Let  $w = Tz = fz$ . Then  $Tw = T(fz) = f(Tz) = fw$ . From (2.21), we have  $fz \leq f(fz) = fw$ , so the inequality (2.18) gives us

$$\psi(d(Tz, Tw)) \leq \psi\left(\frac{1}{2}[d(fz, Tw) + d(fw, Tz)]\right) - \varphi(d(fz, Tw), d(fw, Tz))$$

$$\begin{aligned}
&= \psi\left(\frac{1}{2}[d(Tz, Tw) + d(Tw, Tz)]\right) - \varphi(d(Tz, Tw), d(Tw, Tz)) \\
&= \psi\left(\frac{1}{2}[d(Tz, Tw) + d(Tw, Tz)]\right) - \varphi(d(Tz, Tw), d(Tw, Tz)) \\
&= \psi(d(Tz, Tw)) - \varphi(d(Tz, Tw), d(Tw, Tz)).
\end{aligned}$$

This implies that  $d(Tz, Tw) = 0$ , by the property of  $\varphi$ . Therefore,  $Tw = fw = w$ . This completes the proof of Theorem 4.  $\square$

**Corollary 4.** *Let  $(X, \leq)$  be a partially ordered set and suppose that there exists a metric  $d$  on  $X$  such that  $(X, d)$  is a complete metric space. Let  $f$  and  $T$  are self-mappings of  $X$  such that  $T(X) \subset f(X)$ ,  $f(X)$  is closed and  $T$  is  $f$ -non-decreasing mapping. Assume that  $f$  and  $T$  satisfy for all  $x, y \in X$ , for which  $f(x) \leq f(y)$*

$$d(Tx, Ty) \leq \frac{1}{2}[d(fx, Ty) + d(fy, Tx)] - \varphi(d(fx, Ty), d(fy, Tx)), \quad (2.22)$$

where  $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$  is a continuous function with  $\varphi(x, y) = 0$  if and only if  $x = y = 0$ .

Also, suppose that if  $\{f(x_n)\} \subset X$  is a non-decreasing sequence with  $f(x_n) \rightarrow f(z)$  in  $f(X)$ , then  $f(x_n) \leq f(z)$  and  $f(z) \leq f(f(z))$  for every  $n$ .

If there exists  $x_0 \in X$  with  $fx_0 \leq Tx_0$ , then  $T$  and  $f$  have a coincidence point. Further, if  $T$  and  $f$  commute at their coincidence points, then  $T$  and  $f$  have a common fixed point.

*Proof.* It follows by taking  $\psi(t) = t$  in Theorem 4.  $\square$

**Corollary 5.** *Let  $(X, \leq)$  be a partially ordered set and suppose that there exists a metric  $d$  on  $X$  such that  $(X, d)$  is a complete metric space. Let  $T : X \rightarrow X$  be a monotone non-decreasing mapping. Suppose that  $T$  satisfies for all  $x, y \in X$ , for which  $x \leq y$ ,*

$$\psi(d(Tx, Ty)) \leq \psi\left(\frac{1}{2}[d(x, Ty) + d(y, Tx)]\right) - \varphi(d(x, Ty), d(y, Tx)), \quad (2.23)$$

where

- (1)  $\psi : [0, +\infty) \rightarrow [0, +\infty)$  is an altering distance function,
- (2)  $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$  is a continuous function with  $\varphi(x, y) = 0$  if and only if  $x = y = 0$ .

Also suppose either

- (i)  $\{x_n\} \subset X$  is a non-decreasing sequence with  $x_n \rightarrow z$ , then  $x_n \leq z$  for every  $n$ , or
- (ii)  $T$  is continuous.

If there exists  $x_0 \in X$  with  $x_0 \leq Tx_0$ , then  $T$  has a fixed point.

*Proof.* If (i) holds, then taking  $f = I_X$  in Theorem 4, we get the result.  
If (ii) holds, then proceeding as in Theorem 4 with  $f = I_X$ , we can prove that  $\{Tx_n\}$  is a Cauchy sequence and

$$z = \lim_{n \rightarrow +\infty} x_{n+1} = \lim Tx_n = T(\lim_{n \rightarrow +\infty} x_n) = Tz.$$

Hence the proof is completed.  $\square$

**Corollary 6.** *Let  $(X, \leq)$  be a partially ordered set and suppose that there exists a metric  $d$  on  $X$  such that  $(X, d)$  is a complete metric space. Let  $T : X \rightarrow X$  be a monotone non-decreasing mapping. Suppose that  $T$  satisfies for all  $x, y \in X$ , for which  $x \leq y$ ,*

$$d(Tx, Ty) \leq \frac{1}{2}[d(x, Ty) + d(y, Tx)] - \varphi(d(x, Ty), d(y, Tx)), \quad (2.24)$$

where  $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$  is a continuous function with  $\varphi(x, y) = 0$  if and only if  $x = y = 0$ .

Also, suppose either

- (i) *If  $\{x_n\} \subset X$  is a non-decreasing sequence with  $x_n \rightarrow z$ , then  $x_n \leq z$  for every  $n$ , or*
- (ii)  *$T$  is continuous.*

*If there exists  $x_0 \in X$  with  $x_0 \leq Tx_0$ , then  $T$  has a fixed point.*

*Proof.* It follows by taking  $\psi(t) = t$  in Corollary 5.  $\square$

**Remark 2.** Corollary 6 corresponds to Theorem 2.1 and Theorem 2.2 of Harjani et al. [8].

**Corollary 7.** *Let  $(X, \leq)$  be a partially ordered set and suppose that there exists a metric  $d$  on  $X$  such that  $(X, d)$  is a complete metric space. Let  $T : X \rightarrow X$  be a monotone non-decreasing mapping. Suppose that  $T$  satisfies for all  $x, y \in X$ , for which  $x \leq y$ ,*

$$d(Tx, Ty) \leq k[d(x, Ty) + d(y, Tx)], \quad (2.25)$$

where  $0 < k < \frac{1}{2}$ .

Also, suppose either

- (i) *If  $\{x_n\} \subset X$  is a non-decreasing sequence with  $x_n \rightarrow z$ , then  $x_n \leq z$  for every  $n$ , or*
- (ii)  *$T$  is continuous.*

*If there exists  $x_0 \in X$  with  $x_0 \leq Tx_0$ , then  $T$  has a fixed point.*

*Proof.* It follows by taking  $\varphi(t) = (\frac{1}{2} - k)t$  in Corollary 6.  $\square$

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