



Miskolc Mathematical Notes
Vol. 2 (2001), No 1, pp. 11-29

HU e-ISSN 1787-2413
DOI: 10.18514/MMN.2001.32

On the block implicit LU algorithm for linear systems of equations

Elena Bodon

ON THE BLOCK IMPLICIT LU ALGORITHM FOR LINEAR SYSTEMS OF EQUATIONS

ELENA BODON
University of Bergamo
Piazza Rosate 2, I-24129 Bergamo, Italy
E-mail:emilio@unibg.it

[Received November 30, 2000]

Abstract. We theoretically describe different implementations of the block version of the implicit LU algorithm in the ABS class. We also consider the special block ABS algorithm proposed in [3], showing that it corresponds to a version of the block implicit LU algorithm, with blocksize equal to two, when the coefficient matrix is diagonally dominant. Numerical experiments show that the different block implementations have similar accuracy.

Mathematical Subject Classification: 65F05

Keywords: linear equations, ABS methods, implicit LU algorithm

1. Introduction

Define the linear system of equations

$$Ax = b, \quad (1.1)$$

where $A = (a_1, \dots, a_m)^T : a_i, x \in R^n, : b \in R^m, : m \leq n$.

The unscaled version of the ABS algorithm [2] for solving system (1.1) is given by the following procedure.

Algorithm (a)

Let $x_1 \in R^n$ be arbitrary, $H_1 \in R^{n \times n}$ arbitrary nonsingular.

(•) For $i = 1$ to m :

Compute the i -th component of the residual vector in x_i

$$\tau_i = a_i^T x_i - b^T e_i,$$

where e_i is the unit vector in R^n , and compute the vector

$$s_i = H_i a_i.$$

If $s_i = 0$ and $\tau_i = 0$, set $x_{i+1} = x_i, : H_{i+1} = H_i$ and go to (•).

If $s_i = 0$ and $\tau_i \neq 0$ stop, the system is incompatible.

Compute the search vector

$$p_i = H_i^T z_i, \quad (1.2)$$

where $z_i \in R^n$ is arbitrary save for the condition $a_i^T H_i^T z_i \neq 0$.

Update the approximation to the solution

$$x_{i+1} = x_i - \alpha_i p_i, \quad (1.3)$$

where the stepsize α_i is given by

$$\begin{aligned} \alpha_i &= \tau_i / \delta_i \\ \delta_i &= a_i^T p_i. \end{aligned}$$

If $i = m$ stop, x_{m+1} is a solution, otherwise update matrix H_i by

$$H_{i+1} = H_i - H_i a_i w_i^T H_i, \quad (1.4)$$

where $w_i \in R^n$ is arbitrary save for the condition $w_i^T H_i a_i = 1$.

We list some properties of algorithm (a) which will be used later (see [2] for the proofs and other properties):

- (P1) $H_i a_j = 0, j = 1, \dots, i-1$ (the vectors a_j span the null space of H_i).
- (P2) From (P1) we have: a_j is linearly independent of a_1, \dots, a_{j-1} if $H_i a_j$ is linearly independent of $H_i a_1, \dots, H_i a_{j-1}, i < j$.
- (P3) Define $A_i = (a_1, \dots, a_i), P_i = (p_1, \dots, p_i), Q_i = (H_1^T w_1, \dots, H_i^T w_i), S_i = (s_1, \dots, s_i)$; then the following relations hold: $A_i^T P_i = L_i, A_i^T Q_i = L_i, A_i^T H_1^T = L_i S_i^T$, where L_i, L_i' are lower triangular matrices.
- (P4) The arbitrary parameter H_1 is redundant, since algorithm (a) can be defined in terms of $\tilde{H}_1 = I, \tilde{z}_i = H_1^T z_i, \tilde{w}_i = H_1^T w_i$, where I is the unit matrix in $R^{n \times n}$.
- (P5) The arbitrary parameters z_i, w_i , are redundant, since the sequences (1.2) and (1.3) can be defined in terms of only one parameter z_i or w_i .
- (P6) The matrix H_{i+1} (1.4) can be updated in the form $H_{i+1} = H_1 - S_i Q_i^T$. From (P3) it holds that $H_{i+1} = H_1 - H_1 A_i L_i^{-T} Q_i^T$, and from (P4) and (P5) it holds that $H_{i+1} = I - A_i L_i'^{-T} P_i^T$.
- (P7) The solution of the system $A_i^T X = I_i$, where $X \in R^{n \times i}, I_i$ is the unit matrix in $R^{i \times i}$, given by algorithm (a) can be also written in the form $X = P_i L_i'^{-1}$.
- (P8) The representation of all solutions of the first i equations has the form

$$x' = x_{i+1} + H_{i+1}^T t \quad (1.5)$$

with $t \in R^n$ arbitrary.

2. The block ABS algorithm

The block ABS algorithm, due to Abaffy and Galántai [1] for the scaled ABS class, see also [2], and further developed in several papers by Galántai, is a block form of the ABS algorithm. The block unscaled version of algorithm (a) is given by the following procedure.

Assume for simplicity that A is full rank. Let m_1, m_2, \dots, m_j be positive integers such that $m_1 + m_2 + \dots + m_j = m$. Set $A_k = (a_{m_1+m_2+\dots+m_{k-1}+1}, \dots, a_{m_1+m_2+\dots+m_k})$, $b_k = (b^T e_{m_1+m_2+\dots+m_{k-1}+1}, \dots, b^T e_{m_1+m_2+\dots+m_k})$, A_k^T is the k -th block of m_k rows of A , b_k is the k -th block of m_k components of b .

Let $x_1 \in R^n$ be arbitrary, and $H_1 \in R^{n \times n}$ arbitrary nonsingular.

For $k = 1$ to j :

Compute the matrix $P_k \in R^{n \times m_k}$ by

$$P_k = H_k^T Z_k ,$$

where $Z_k \in R^{n \times m_k}$ is arbitrary full rank save for the condition $A_k^T H_k^T Z_k$ nonsingular.

Update the approximation to the solution by

$$x_{k+1} = x_k - P_k d_k , \quad (2.1)$$

where d_k is the unique solution of the nonsingular system

$$A_k^T P_k d_k = r_k , \quad (2.2)$$

and $r_k = A_k^T x_k - b_k$ is the k -th block of m_k components of the residual in x_k .

If $k = j$ stop, x_{j+1} solves system (1.1), otherwise update matrix H_k by

$$H_{k+1} = H_k - H_k A_k W_k^T H_k ,$$

where $W_k \in R^{n \times m_k}$ is arbitrary full rank save for the condition

$$W_k^T H_k A_k = I_{m_k} . \quad (2.3)$$

The properties of block algorithm, similar to properties of algorithm (a), are given in [2].

If A is rank deficient, from property (P1), the linear dependent rows of A can be deleted from system (1.1) when solving system (2.3).

The choice $Z_k = W_k$ verifies the nonsingularity condition for the matrix $A_k^T H_k^T Z_k$ and implies $d_k = r_k$ in (2.2).

If $m_k = 1, : k = 1, \dots, j$ ($j = m$), we obtain algorithm (a), while if $m = n$ and $m_k = m_1 = m$ ($j = 1$) and if $H_1 = I$, we obtain the explicit computation of A^{-1} in (2.3) and if $Z_1 = W_1$, the solution (2.1) is computed by $x_2 = x_1 - A^{-1} r_1$.

3. Alternative formulations of the block ABS algorithm

We reformulate the block ABS algorithm for a general matrix A in the case $Z_k = W_k$, $k = 1, \dots, j$.

Algorithm (b1)

Give $x_1, H_1, m_1, m_2, \dots, m_j$ as above.

(•) For $k = 1$ to j :

Compute

$$S_k = H_k A_k, \quad (3.1)$$

$$r_k = A_k^T x_k - b_k. \quad (3.2)$$

If $S_k = 0$ and $r_k = 0$, set $x_{k+1} = x_k$, $H_{k+1} = H_k$ and go to (•).

If $S_k = 0$ and $r_k \neq 0$, stop, system (1.1) is incompatible, or if a column s_i of S_k and the corresponding element τ_i of r_k are such that $s_i = 0$, $\tau_i \neq 0$, stop, system (1.1) is incompatible.

If $S_k \neq 0$, apply algorithm (a) for finding the search vectors of the matrix $S_k^T \in R^{m_k \times n}$ deleting the linearly dependent rows if they exist (from property (P2) the corresponding rows in A are linearly dependent from the previous rows). Set $S_{\hat{k}} \in R^{n \times l_k}$ the matrix formed by the linearly independent columns of S_k , $l_k \leq m_k$. Determine the solution of the system

$$S_{\hat{k}}^T W_k = I_{l_k} \quad (3.3)$$

by algorithm (a), where $W_k \in R^{n \times l_k}$.

Compute the matrix $P_k \in R^{n \times l_k}$ by

$$P_k = H_k^T W_k. \quad (3.4)$$

Update the approximation to the solution by

$$x_{k+1} = x_k - P_k r_{\hat{k}}, \quad (3.5)$$

where $r_{\hat{k}}$ consists of the l_k components of r_k corresponding to the l_k rows of $S_{\hat{k}}^T$.

If $l_k < m_k$, compute $\tau_i = a_i^T x_{k+1} - b^T e_i$ for the $m_k - l_k$ indices i corresponding to the linearly dependent rows of S_k^T . If $\tau_i \neq 0$ for at least one index i , stop, the system is incompatible.

If $k = j$, stop, x_{j+1} is a solution of system (1.1), otherwise update matrix H_k by

$$H_{k+1} = H_k - S_{\hat{k}} P_k^T. \quad (3.6)$$

If $m_k = 2$, $k = 1, \dots, j$, $j = m/2$, we obtain the following algorithm, also proposed by a different derivation in [3]. Suppose m even, if m is odd, the last step for $k = m/2 + 1$ corresponds to the last step of algorithm (a). Set $A_k = (a_{k1}, a_{k2})$, $b_k = (b_{k1}, b_{k2})$.

Algorithm (b2)

Let x_1, H_1 as above.

(•) For $k = 1$ to $m/2$:

Compute the vectors $S_k = (s_{k1}, s_{k2})$

$$\begin{aligned} s_{k1} &= H_k a_{k1} , \\ s_{k2} &= H_k a_{k2} . \end{aligned} \quad (3.7)$$

Compute the residuals $r_k = (\tau_{k1}, \tau_{k2})$

$$\begin{aligned} \tau_{k1} &= a_{k1}^T x_k - b_{k1} , \\ \tau_{k2} &= a_{k2}^T x_k - b_{k2} . \end{aligned} \quad (3.8)$$

If $s_{k1} = 0$, $s_{k2} = 0$, $\tau_{k1} = 0$, $\tau_{k2} = 0$, set $x_{k+1} = x_k$, $H_{k+1} = H_k$ and go to (•).

If $s_{k1} = 0$ and $\tau_{k1} \neq 0$, or $s_{k2} = 0$ and $\tau_{k2} \neq 0$, stop, the system is incompatible.

If $s_{k1} \neq 0$ and $s_{k2} = 0$, $\tau_{k2} = 0$, set $k_i = k_1$ and go to (••).

If $s_{k2} \neq 0$ and $s_{k1} = 0$, $\tau_{k1} = 0$, set $k_i = k_2$ and go to (••).

If $s_{k1} \neq 0$ and $s_{k2} \neq 0$, verify if s_{k1}, s_{k2} are linearly independent (for example applying algorithm (a) to the matrix $(s_{k1}, s_{k2})^T$).

If s_{k1}, s_{k2} are linearly independent, choose $W_k = (w_{k1}, w_{k2})$, $W_k \in R^{n \times 2}$ satisfying system $S_k^T W_k = I_2$

$$\begin{aligned} s_{k1}^T w_{k1} &= 1, & s_{k1}^T w_{k2} &= 0 , \\ s_{k2}^T w_{k1} &= 0, & s_{k2}^T w_{k2} &= 1 . \end{aligned} \quad (3.9)$$

Update the approximation to the solution by

$$x_{k+1} = x_k - H_k^T (\tau_{k1} w_{k1} + \tau_{k2} w_{k2}) . \quad (3.10)$$

If $k = m/2$, stop, $x_{\frac{m}{2}+1}$ is a solution of system (1.1), otherwise update matrix H_k by

$$H_{k+1} = H_k - s_{k1} w_{k1}^T H_k - s_{k2} w_{k2}^T H_k \quad (3.11)$$

and go to (•).

(*) If s_{k2} is linearly dependent from s_{k1} , set $k_i = k_2$ (row k_2 in A is linearly dependent from the previous rows).

(••) Choose $w_{k_i} \in R^n$ such that

$$s_{k_i}^T w_{k_i} = 1 .$$

Update the approximation to the solution by

$$x_{k+1} = x_k - \tau_{k_i} H_k^T w_{k_i} .$$

If it is case (*), compute $\tau_{k_2} = a_{k_2}^T x_{k+1} - b_{k_2}$ and if $\tau_{k_2} \neq 0$, stop, the system is incompatible. If $k = m/2$, stop, $x_{\frac{m}{2}+1}$ is a solution of system (1.1), otherwise update matrix H_k by

$$H_{k+1} = H_k - s_{k_i} w_{k_i}^T H_k$$

and go to (•).

We consider two equivalent forms of the block ABS algorithm (b1), other particular cases of block forms can be found in [2].

The first versions of the algorithm (b1) constructs at every step k , the same approximate solution x_k and the same matrices S_k, H_k avoiding the explicit computation of W_k . Rewrite (3.5) as $x_{k+1} = x_k - H_k^T W_k r_k$. Then by multiplying (3.3) by r_k we have $S_k^T W_k r_k = r_k$. Set $t_k = W_k r_k$, then instead of (3.3) we can solve $S_k^T t_k = r_k$ and compute $x_{k+1} = x_k - H_k^T t_k$. Rewrite (3.6) as $H_{k+1} = (I - S_k W_k^T) H_k$. Denote by \tilde{H}_k the matrix obtained after m_k iterations of algorithm (a) applied to system $S_k^T t_k = r_k$. From (3.3) it holds that $\text{Null}(I - S_k W_k^T) = \text{Null}(\tilde{H}_k)$, hence from properties (P4),(P5),(P6),(P7) we can write \tilde{H}_k as $\tilde{H}_k = I - S_k W_k^T$. Then the update of H_k in (3.6) is given by $H_{k+1} = \tilde{H}_k H_k$. The first alternative formulation of algorithm (b1) is given by the following procedure.

Algorithm (c)

Let $x_1, H_1, m_1, m_2, \dots, m_j$ as above.

(•) For $k = 1$ to j :

Compute

$$S_k = H_k A_k , \tag{3.12}$$

$$r_k = A_k^T x_k - b_k . \tag{3.13}$$

If $S_k = 0$ and $r_k = 0$ set $x_{k+1} = x_k, H_{k+1} = H_k$ and go to (•).

If $S_k = 0$ and $r_k \neq 0$, stop, the system is incompatible.

If $S_k \neq 0$, solve by algorithm (a) the system

$$S_k^T t_k = r_k . \tag{3.14}$$

Update the approximation to the solution by

$$x_{k+1} = x_k - H_k^T t_k . \tag{3.15}$$

If S_k is not full rank and at a step i system (3.14) is incompatible, then the corresponding equation i in system (1.1) is incompatible from the previous equations.

If $k = j$, stop, x_{j+1} is a solution of system (1.1), otherwise update matrix H_k by

$$H_{k+1} = \tilde{H}_k H_k, \quad (3.16)$$

where \tilde{H}_k is the matrix (1.4) obtained after m_k steps of algorithm (a) applied to system (3.14).

The second version of algorithm (b1) is a modification of algorithm (c). It avoids the computation of the update H_{k+1} (a matrix-matrix product) but performs transformations on the matrix A .

Define $\bar{S}_k = H_k \bar{A}_k$ where \bar{A}_k is the transpose of the matrix formed by the last $m_{k+1} + \dots + m_j$ rows of A (i.e. the last $j - k$ blocks of A), $\bar{r}_k = \bar{A}_k^T x_k - \bar{b}_k$ where \bar{b}_k is the vector formed by the last $m_{k+1} + \dots + m_j$ components of b , and observe that $S_k = H_k A_k = \tilde{H}_{k-1} H_{k-1} A_k = \tilde{H}_{k-1} H_{k-1} (\bar{A}_{k-1})_{m_k} = \tilde{H}_{k-1} (\bar{S}_{k-1})_{m_k}$, $r_k = A_k^T x_k - b_k = A_k^T x_{k-1} - b_k - A_k^T H_{k-1}^T t_{k-1} = (\bar{A}_{k-1}^T)_{m_k} x_{k-1} - (\bar{b}_{k-1})_{m_k} - (\bar{A}_{k-1}^T)_{m_k} H_{k-1}^T t_{k-1} = (\bar{r}_{k-1})_{m_k} - (\bar{S}_{k-1}^T)_{m_k} t_{k-1}$, where $(\bar{A}_{k-1})_{m_k}$ is the submatrix formed by the first m_k columns of \bar{A}_{k-1} , $(\bar{S}_{k-1})_{m_k}$ is the submatrix formed by the first m_k columns of \bar{S}_{k-1} and $(\bar{r}_{k-1})_{m_k}$ is the vector formed by the first m_k components of \bar{r}_{k-1} . Then algorithm (c) becomes

Algorithm (d)

Let $x_1, H_1, m_1, m_2, \dots, m_j$ as above.

Set $\bar{S}_1 = H_1 A$, $\bar{r}_1 = Ax_1 - b$

(•) For $k = 1$ to j :

Set \bar{S}_k and \bar{r}_k partitioned as follows:

$\bar{S}_k = (S_k, \bar{S}_k)$, S_k with dimension $(n \times m_k)$, \bar{S}_k with dimension $(n \times (m_{k+1} + \dots + m_j))$

$\bar{r}_k = (r_k, \bar{r}_k)$, r_k with dimension m_k , \bar{r}_k with dimension $m_{k+1} + \dots + m_j$

If $S_k = 0$ and $r_k = 0$, set $\bar{S}_k = \bar{S}_k$, $\bar{r}_k = \bar{r}_k$, $t_k = 0$, $\tilde{H}_k = I$ and go to (•).

If $S_k = 0$ and $r_k \neq 0$, stop, the system is incompatible.

If $S_k \neq 0$, solve by algorithm (a) the system

$$S_k^T t_k = r_k. \quad (3.17)$$

If S_k is not full rank and at a step i system (3.17) is incompatible, then the corresponding equation i in system (1.1) is incompatible from the previous equations.

If $k < j$, compute

$$\bar{S}_{k+1} = \tilde{H}_k \bar{S}_k, \quad (3.18)$$

$$\bar{r}_{k+1} = \bar{r}_k - \bar{S}_k^T t_k, \quad (3.19)$$

where \tilde{H}_k is the matrix (1.4) obtained after m_k steps of algorithm (a) applied to system (3.17), and go to (•).

Estimate the solution by the following process:

Set $\bar{t}_j = t_j$, for $k = 1$ to $j - 1$ compute

$$\bar{t}_{j-k} = t_{j-k} + \tilde{H}_{j-k}^T \bar{t}_{j-k+1} , \quad (3.20)$$

$$x_{j+1} = x_1 - H_1^T \bar{t}_1 .$$

Algorithms (c) and (d) can be also derived from property (P8) if we consider at step k a solution of the k -th block and all the possible solutions given by formula (1.5), at step $k + 1$ the solutions of the $(k + 1)$ -th block satisfying relation (1.5).

The equivalent forms of algorithms (a), (b1), (b2), (c), (d) can differ in storage, overhead, computational timings, according to the type of ABS method, the type of representation of matrix H_i , and the type of implementation (sequential or parallel).

The block form of algorithm (b1) was tested in [4] on three algorithms of the ABS class: the implicit LU algorithm, the modified Huang algorithm, the implicit QR algorithm. The block form of algorithm (d) was tested in [5] on the implicit LU algorithm and on the modified Huang algorithm (using several representations of the matrix H_i) on parallel processor. In this paper we consider only the implicit LU method and a modification in [3] used in algorithm (b2).

4. The implicit LU algorithm and some of its block forms

The implicit LU algorithm corresponds to the parameter choices

$$H_1 = I, \quad z_i = e_i, \quad w_i = e_i / e_i^T H_i a_i .$$

It is well defined if A has nonsingular principal submatrices, otherwise column pivoting has to be performed. Matrix H_{i+1} has the structure

$$H_{i+1} = \begin{bmatrix} 0_{i \times i} & 0_{i \times (n-i)} \\ M_i & I_{n-i} \end{bmatrix} . \quad (4.1)$$

The first i rows are zero, the submatrix given by the last $n - i$ rows and columns is the identity matrix. The search vector p_{i+1} coincides with the $(i + 1)$ -th row of H_{i+1} , hence the matrix P_i in (P3) is unit upper triangular. The vector s_{i+1} has the first i components equal to zero. If $x_1 = 0$, only the first i components of x_{i+1} can be nonzero. Several tests on the implicit LU method can be found in [6].

The block generalization of the implicit LU method is obtained solving system (3.3), (3.9), (3.14), (3.17), of algorithms (b1), (b2), (c), (d), respectively, by the implicit LU method with zero starting point. Matrix H_{k+1} in (3.6), (3.11), (3.16) is equal to (1.4) after $m_1 + m_2 + \dots + m_k$ steps. Matrix W_k can have nonzeros only in m_k rows, which form the inverse of the $m_k \times m_k$ nonsingular submatrix of S_k^T

whose columns are chosen by the implicit LU method. Matrix P_k in (3.4), (3.10) has $n - (m_{k+1} + \dots + m_j)$ rows equal to zero and so x_{k+1} in (3.5), (3.10), (3.15). Matrix S_k in (3.1), (3.7), (3.12), (3.17) has $m_1 + \dots + m_{k-1}$ rows equal to zero and the partial solution t_k in (3.14), (3.17) can have only m_k components that are nonzero.

The methods tested in our experiments are listed below. For the block algorithms we have used a size n_b equal for all the blocks. The starting points are set to zero.

- Implicit LU - the method given above, where, for stability reasons, at every step i we take column j such that $\delta_j = \max(\delta_k = |e_k^T H_i a_i| : k = 1, \dots, n)$. From the structure of H_{i+1} (4.1), at every step i , the $n - i$ elements of a_i , not used to update the estimate solution (1.3), are overwritten by the elements of the last column of M_i , hence the storage required is the storage of A . Then the search vectors p_i (column i of H_i^T) are memorized in A and system (1.1) can be solved with different right hand-sides using the vectors $p_i, i = 1, \dots, n$ previously computed. The method requires $nm^2 - 2m^3/3$ multiplications for $m \leq n$ and $n^3/3$ for $m = n$.
- Block implicit LU (b) - the method given by algorithm (b1), where system (3.3) is solved by the implicit LU described above. For this method the $n_b \times n$ block A_k^T is overwritten by the $kn_b \times n_b$ nonzero submatrix of P_k and by the $n_b \times n - kn_b$ submatrix of S_k^T used to update H_k (3.6) and at step $k + i$ by a nonzero part of H_{k+i+1} , while for solving (3.3) we use a workspace of dimension $n_b \times n - (k - 1)n_b$. Thus the storage required is the storage of A plus $n_b \times n$. To solve (3.3) $(n - (k - 1)n_b)n_b^2 - 2n_b^3/3$ multiplications are needed for computing the search vectors and $2n_b^3/3$ for W_k . $(k - 1)n_b^3$ multiplications are needed for the product $H_k^T W_k$ in computing P_k (3.4), $(n - kn_b)kn_b^2$ for the product $S_k P_k^T$ in updating H_{k+1} (3.6), $(k - 1)n_b^2$ for r_k (3.2), kn_b^2 for x_{k+1} (3.5) and $(n - (k - 1)n_b)(k - 1)n_b^2$ for S_k (3.1). Hence the total cost for $m = n$ and n multiple of n_b is $n^3/3 + n^2n_b - nn_b^2/3 + O(n^2)$. The number of operations is an increasing function in n_b , minimum is $n^3/3$ for $n_b = 1$ (the algorithm corresponds to implicit LU) and maximum is n^3 for $n_b = n$ (the algorithm performs one step computing the inverse of A in (3.3)).
- Block implicit LU (c) - the method given by algorithm (c), where system (3.14) is solved by the implicit LU described above. For this method the $n_b \times n$ block A_k^T is overwritten by the $n_b \times n - (k - 1)n_b$ nonzero submatrix of S_k^T , then S_k is overwritten by the nonzero submatrix of \tilde{H}_k when solving system (3.14) and then \tilde{H}_k is overwritten with a nonzero part of H_{k+2} at next step $k + 1$ and by a nonzero part of H_{k+i+1} at step $k + i$. Hence the memory cost is the storage of A . The number of multiplications required is $(n - (k - 1)n_b)n_b^2 - 2n_b^3/3$ for solving system (3.14), $(k - 1)n_b^2$ for x_{k+1} in (3.15), $(k - 1)n_b^2$ for r_k in (3.13), $(n - (k - 1)n_b)(k - 1)n_b^2$ for computing S_k (3.12), $(k - 1)n_b^2(n - kn_b)$ for the product in H_{k+1} in (3.16). The total amount for $m = n$ and n multiple of n_b is $n^3/3 + O(n^2)$. Also in the case of blocks m_1, m_2, \dots, m_j with different size the total amount is $n^3/3 + O(n^2)$.
- Block implicit LU (d) - the method given by algorithm (d), where system (3.17)

is solved by the implicit LU described above. For this method the $(n - kn_b) \times (n - (k - 1)n_b)$ nonzero submatrix of \bar{S}_k is overwritten by the $(n - kn_b) \times (n - kn_b)$ nonzero submatrix of \bar{S}_{k+1} and the $n_b \times (n - (k - 1)n_b)$ nonzero submatrix of S_k^T is overwritten by the $n_b \times (n - kn_b)$ nonzero submatrix of \tilde{H}_k^T when solving system (3.17). Hence the memory is the storage of A . The number of multiplications required is $(n - (k - 1)n_b)n_b^2 - 2n_b^3/3$ for solving system (3.17), $(n - kn_b)n_b$ for computing r_{k+1} (3.19), $n_b(n - kn_b)^2$ for the product in \bar{S}_{k+1} (3.18) and $n^2/2$ for the process in estimating the solution x_{k+1} (3.20). The total amount for $m = n$ and n multiple of n_b is $n^3/3 + O(n^2)$ also for blocks m_1, m_2, \dots, m_j with different size.

Notice that the two versions of block implicit LU (c) and (d) have the same storage and overhead as implicit LU has.

5. The algorithm of Adib et al.

Here we call Algorithm [3] the method described by Adib et al. in [3]. We show that this method is algorithm (b2), where system (3.9) is solved applying twice the implicit LU.

Using implicit LU in (3.9) the search vectors p_{k_1}, p_{k_2} of the matrix $(s_{k_1}, s_{k_2})^T$ are constructed choosing two columns j_1, j_2 such that

$$\begin{aligned} \delta_{j_1} &= \max(\delta_i = |s_{k_1(i)}| \quad i = 1, \dots, n), \\ \delta_{j_2} &= \max(\delta_i = |s_{k_2(i)} - (s_{k_2(j_1)}s_{k_1(i)})/\delta_{j_1}| \quad i = 1, \dots, n), \end{aligned} \quad (5.1)$$

hence

$$\begin{aligned} p_{k_1(j_1)} &= 1, & p_{k_1(i)} &= 0, & i &= 1, \dots, n \quad i \neq j_1 \\ p_{k_2(j_1)} &= -s_{k_1(j_2)}/\delta_{j_1}, & p_{k_2(j_2)} &= 1, & p_{k_2(i)} &= 0 \quad i = 1, \dots, n \quad i \neq j_1, j_2. \end{aligned}$$

The solutions w_{k_1}, w_{k_2} can be nonzeros only in the components j_1, j_2

$$\begin{aligned} w_{k_1(j_1)} &= 1/\delta_{j_1} + (s_{k_2(j_1)}/(\delta_{j_1}\delta_{j_2}))(s_{k_1(j_2)}/\delta_{j_1}), \\ w_{k_1(j_2)} &= -s_{k_2(j_1)}/(\delta_{j_1}\delta_{j_2}), \quad w_{k_1(i)} = 0, \quad i = 1, \dots, n \quad i \neq j_1, j_2 \end{aligned} \quad (5.2)$$

$$w_{k_2(j_1)} = -s_{k_1(j_2)}/(\delta_{j_1}\delta_{j_2}), \quad w_{k_2(j_2)} = 1/\delta_{j_2}, \quad w_{k_2(i)} = 0, \quad i = 1, \dots, n \quad i \neq j_1, j_2 \quad (5.3)$$

and from property (4.1) of the update, rows j_1, j_2 in H_{k+1} (3.11) become zero.

In the method proposed in [3], the parameters w_{k_1}, w_{k_2} correspond to the two solutions obtained solving by implicit LU the two following systems

$$\begin{cases} s_{k_2}^T w_{k_1} = 0 \\ s_{k_1}^T w_{k_1} = 1 \end{cases}, \quad (5.4)$$

$$\begin{cases} s_{k_1}^T w_{k_2} = 0 \\ s_{k_2}^T w_{k_2} = 1 \end{cases}. \quad (5.5)$$

The solution w_{k_2} of the second system (5.5) is equal to the solution (5.3) since the sequence of the rows $s_{k_1}^T, s_{k_2}^T$ is the same as in (3.9) and so the choice of the pivot indices j_1, j_2 is (5.1). The solution w_{k_1} of the first system (5.4) is not (5.2) since in (5.4) the first considered row is $s_{k_2}^T$, then the columns taken for the pivot can be different from j_1, j_2 . Set

$$\delta_{j_3} = \max(\delta_i = |s_{k_2(i)}| \quad i = 1, \dots, n),$$

$$\delta_{j_4} = \max(\delta_i = |s_{k_1(i)} - (s_{k_1(j_3)} s_{k_2(i)}) / \delta_{j_3}| \quad i = 1, \dots, n).$$

The search vectors of (5.4) are

$$p_{k_1(j_3)} = 1, \quad p_{k_1(i)} = 0, \quad i = 1, \dots, n \quad i \neq j_3$$

$$p_{k_2(j_3)} = -s_{k_2(j_4)} / \delta_{j_3}, \quad p_{k_2(j_4)} = 1, \quad p_{k_2(i)} = 0, \quad i = 1, \dots, n \quad i \neq j_3, j_4$$

and the solutions w_{k_1} can be nonzeros only in the components j_3, j_4

$$w_{k_1(j_3)} = -s_{k_2(j_4)} / (\delta_{j_3} \delta_{j_4}), \quad w_{k_1(j_4)} = 1 / \delta_{j_4}, \quad w_{k_1(i)} = 0, \quad i = 1, \dots, n \quad i \neq j_3, j_4. \quad (5.6)$$

Since $H_1 = I$, rows j_1, j_2, j_3, j_4 in (3.11) can be different from the unit vector, and the process leads to a dense matrix H_k . If j_1, j_2 coincide with j_3, j_4 , solution (5.6) is equal to (5.2), the step corresponds to a step of the block implicit LU algorithm and rows j_1, j_2 of H_{k+1} become zero. The indices j_1, j_2 can be equal to j_3, j_4 if matrix $(s_{k_1}, s_{k_2})^T$ has two dominant elements in two different columns, thus if A is diagonally dominant, algorithm [3] becomes the block implicit LU (b) algorithm with blocksize $n_b = 2$.

The special structure of H_k depends on the pivot indices j_1, j_2, j_3, j_4 . A zero row appears if (s_{k_1}, s_{k_2}) has rank 1 (iteration k is an implicit LU iteration). Also zero rows appear at a step k when the number of a set of rows taken from the first $2k$ is equal to the number of different indices of columns selected as pivot in those rows (in this case all rows with indices in the set become zero in H_{k+1}).

Algorithm [3] can be generalized for blocks greater than 2, but it becomes very expensive.

The code written for numerical experiments uses an $n \times n$ array to memorize H_k since generally it is not known how sparse the matrix can be. The code performs at every iteration a search to find the set of pivot indices, used at previous iterations, which can give zero rows in H_k . If this set exists, these rows are ignored in the multiplications and so the number of operations is reduced. Then the amount of operations may vary according to the values of the elements of A , the minimum being $n^3/3$ when at every step the indices j_1, j_2 coincide with j_3, j_4 , maximum is $3n^3/2$ when at every step the indices j_1, j_2 are different from j_3, j_4 and there are no zero rows in H_k .

The following table reports storage requirement and number of multiplications for the above algorithms (only higher order terms are considered).

	storage	overhead
implicit LU	n^2	$n^3/3$
algorithm [3]	$2n^2$	$\min n^3/3, \max 3n^3/2$
block implicit LU (b) $n_b = 2$	n^2	$n^3/3$
block implicit LU (c) $n_b = 2$	n^2	$n^3/3$
block implicit LU (d) $n_b = 2$	n^2	$n^3/3$
block implicit LU (b)	$n^2 + n_b n$	$n^3/3 + n^2 n_b - n n_b^2/3$
block implicit LU (c)	n^2	$n^3/3$
block implicit LU (d)	n^2	$n^3/3$

6. Numerical testing and results

Codes for testing the above algorithms were written in Fortran 77, run in single precision and tested on square matrices with dimension $n = 100, n = 200$, using the same size n_b for all blocks, with values $n_b = 2, 5, 10, 20, 50$. The following families of problems were considered.

(M1) Matrices with random integer elements, solution vector x^* with random integer elements and right hand-side b computed exactly by $b = Ax^*$.

(M2) Ill conditioned matrices with random integer elements having two or more rows and/or columns equal save for an element a_{ij} set equal to $a_{ij} + 2^{-k}$, k integer, solution vector x^* with random integer elements and the component i (or j) equal to 2^k so that the right hand-side $b = Ax^*$ has integer elements.

(M3) Ill conditioned matrices formed by a product of a random matrix of family (M1) and an ill conditioned and small dimensioned matrix with integer elements taken from [7] (matrices of Wilson, Rutishauser, Morris, Pascal, Tanabe etc.). The solution vector x^* has random integer elements and b is computed by $b = Ax^*$.

(M4) A set of matrices listed in [3] and [8] having not all integer entries but exactly represented in the machine, the solution vector x^* having all components equal to 1.

The performance of the algorithms was measured by the relative error in the solution and in the residual with Euclidean norm defined respectively by $\|x - x^*\|/\|x^*\|$, $\|Ax - b\|/\|b\|$. Some of the results are reported in Tables 1, 2, 3, 4. Tables 5, 6 give a comparison of the algorithms on 200 problems. The elements u_{ij}/v_{ij} have the following meaning: u_{ij} indicates how many times the algorithm in row i has a smaller relative error than the algorithm in column j , v_{ij} how many times the relative error is equal (only the first two digits are considered). We find that all the algorithms have similar performance on most problems. The block implicit LU (b) seems to have the worst performance for great values of blocksize n_b , probably due to the computation of the inverse of a not small dimensioned matrix in (3.3). The original nonblock version gives generally the best performance.

Acknowledgement: This work is partly supported by MURST 1999 Programma di Cofinanziamento.

REFERENCES

- [1] ABAFFY, J. and GALÁNTAI A.: *Conjugate direction methods for linear and nonlinear systems of algebraic equations*, Colloq. Math. Soc. János Bolyai **50**, (1986), 481-502.
- [2] ABAFFY J. and SPEDICATO E.: *ABS Projection Algorithms: Mathematical Techniques For Linear And Nonlinear Algebraic Equations*, Ellis Horwood, Chichester, 1989.
- [3] ADIB M. and MAHDAVI-AMIRI N.: *A new ABS-based approach for solving linear systems with a rank two update of the Abaffian*. Unpublished manuscript
- [4] BERTOCCHI M. and SPEDICATO E.: *ABS Block Algorithms for Dense Linear Systems in a Vector Processor Environment*, Technical Note, University of Bergamo, 1988.
- [5] BODON E.: *Numerical Results of the ABS Algorithms for Linear Systems of Equations*, Report DMSIA N.9, University of Bergamo, 1993.
- [6] NICOLAI S. and SPEDICATO E.: *A bibliography of the ABS methods*, Optimization Methods and Software, **8**, (1997), 171-183.
- [7] SPEDICATO E. and VESPUCCI M.T.: *Variations on the Gram-Schmidt and the Huang algorithms for linear systems: a numerical study*, Applications of Mathematics, **2**, (1993), 81-100.
- [8] MIRNIA K.: *Iterative Refinement In ABS Methods*, Report DMSIA 32/96, University of Bergamo, 1996.

Table 1 - Test matrices (M1)

Method	dimension n=100		Dimension n=200	
	Solution error	Residual error	Solution error	Residual error
impl.LU	.24E-05	.44E-06	.39E-05	.85E-06
algorithm[3]	.37E-05	.71E-06	.73E-05	.12E-05
block impl.LU (b) $n_b = 2$.59E-05	.61E-06	.14E-04	.12E-05
block impl.LU (c) $n_b = 2$.30E-05	.49E-06	.12E-04	.11E-05
block impl.LU (d) $n_b = 2$.34E-05	.10E-05	.82E-05	.25E-05
block impl.LU (b) $n_b = 5$.33E-05	.54E-06	.14E-04	.11E-05
block impl.LU (c) $n_b = 5$.54E-05	.57E-06	.13E-04	.13E-05
block impl.LU (d) $n_b = 5$.80E-05	.86E-06	.14E-04	.22E-05
block impl.LU (b) $n_b = 10$.39E-05	.71E-06	.10E-04	.14E-05
block impl.LU (c) $n_b = 10$.55E-05	.66E-06	.25E-04	.12E-05
block impl.LU (d) $n_b = 10$.33E-05	.11E-05	.69E-05	.26E-05
block impl.LU (b) $n_b = 20$.60E-05	.13E-05	.21E-04	.29E-05
block impl.LU (c) $n_b = 20$.48E-05	.78E-06	.10E-04	.14E-05
block impl.LU (d) $n_b = 20$.85E-05	.74E-06	.93E-05	.19E-05
block impl.LU (b) $n_b = 50$.16E-04	.39E-05	.16E-04	.42E-05
block impl.LU (c) $n_b = 50$.96E-05	.82E-06	.20E-04	.14E-05
block impl.LU (d) $n_b = 50$.96E-05	.82E-06	.28E-04	.15E-05
impl.LU	.26E-05	.60E-06	.62E-05	.94E-06
algorithm[3]	.35E-05	.76E-06	.84E-05	.13E-05
block impl.LU (b) $n_b = 2$.40E-05	.63E-06	.15E-04	.12E-05
block impl.LU (c) $n_b = 2$.47E-05	.57E-06	.98E-05	.12E-05
block impl.LU (d) $n_b = 2$.55E-05	.92E-06	.85E-05	.21E-05
block impl.LU (b) $n_b = 5$.13E-04	.71E-06	.81E-05	.12E-05
block impl.LU (c) $n_b = 5$.11E-04	.59E-06	.68E-05	.11E-05
block impl.LU (d) $n_b = 5$.95E-05	.10E-05	.14E-04	.30E-05
block impl.LU (b) $n_b = 10$.24E-05	.76E-06	.73E-05	.14E-05
block impl.LU (c) $n_b = 10$.53E-05	.62E-06	.99E-05	.11E-05
block impl.LU (d) $n_b = 10$.78E-05	.74E-06	.84E-05	.19E-05
block impl.LU (b) $n_b = 20$.98E-05	.15E-05	.85E-05	.18E-05
block impl.LU (c) $n_b = 20$.25E-05	.59E-06	.99E-05	.13E-05
block impl.LU (d) $n_b = 20$.60E-05	.88E-06	.42E-05	.16E-05
block impl.LU (b) $n_b = 50$.11E-04	.75E-05	.22E-04	.58E-05
block impl.LU (c) $n_b = 50$.19E-04	.86E-06	.46E-05	.15E-05
block impl.LU (d) $n_b = 50$.19E-04	.86E-06	.10E-04	.16E-05
impl.LU	.50E-05	.56E-06	.46E-05	.96E-06
algorithm[3]	.46E-05	.71E-06	.13E-03	.11E-05
block impl.LU (b) $n_b = 2$.18E-04	.56E-06	.60E-04	.11E-05
block impl.LU (c) $n_b = 2$.12E-04	.66E-06	.12E-03	.12E-05
block impl.LU (d) $n_b = 2$.84E-05	.95E-06	.86E-04	.20E-05
block impl.LU (b) $n_b = 5$.45E-05	.64E-06	.13E-03	.11E-05
block impl.LU (c) $n_b = 5$.17E-04	.63E-06	.11E-03	.12E-05
block impl.LU (d) $n_b = 5$.52E-05	.93E-06	.50E-04	.26E-05
block impl.LU (b) $n_b = 10$.54E-05	.80E-06	.15E-03	.16E-05
block impl.LU (c) $n_b = 10$.45E-05	.55E-06	.10E-03	.12E-05
block impl.LU (d) $n_b = 10$.55E-05	.67E-06	.13E-03	.17E-05
block impl.LU (b) $n_b = 20$.55E-05	.21E-05	.23E-04	.28E-05
block impl.LU (c) $n_b = 20$.15E-04	.62E-06	.10E-03	.13E-05
block impl.LU (d) $n_b = 20$.61E-05	.75E-06	.61E-04	.15E-05
block impl.LU (b) $n_b = 50$.19E-04	.52E-05	.19E-03	.37E-04
block impl.LU (c) $n_b = 50$.19E-04	.64E-06	.77E-04	.12E-05
block impl.LU (d) $n_b = 50$.19E-04	.64E-06	.33E-04	.14E-05
impl.LU	.50E-05	.41E-06	.21E-04	.84E-06
algorithm[3]	.13E-04	.69E-06	.92E-05	.94E-06
block impl.LU (b) $n_b = 2$.13E-04	.57E-06	.16E-04	.96E-06
block impl.LU (c) $n_b = 2$.18E-04	.57E-06	.18E-04	.95E-06
block impl.LU (d) $n_b = 2$.51E-05	.82E-06	.10E-04	.17E-05
block impl.LU (b) $n_b = 5$.71E-05	.60E-06	.11E-04	.10E-05
block impl.LU (c) $n_b = 5$.31E-05	.49E-06	.14E-04	.96E-06
block impl.LU (d) $n_b = 5$.63E-05	.82E-06	.26E-04	.16E-05
block impl.LU (b) $n_b = 10$.97E-05	.79E-06	.98E-05	.11E-05
block impl.LU (c) $n_b = 10$.53E-05	.50E-06	.71E-05	.99E-06
block impl.LU (d) $n_b = 10$.98E-05	.79E-06	.13E-04	.19E-05
block impl.LU (b) $n_b = 20$.46E-05	.13E-05	.87E-05	.24E-05
block impl.LU (c) $n_b = 20$.67E-05	.61E-06	.70E-05	.12E-05
block impl.LU (d) $n_b = 20$.17E-04	.50E-06	.21E-04	.17E-05
block impl.LU (b) $n_b = 50$.20E-04	.12E-04	.53E-04	.97E-05
block impl.LU (c) $n_b = 50$.15E-04	.62E-06	.25E-04	.13E-05
block impl.LU (d) $n_b = 50$.15E-04	.62E-06	.31E-04	.13E-05

Table 2 - Test matrices (M2)

Method	dimension n=100		Dimension n=200	
	Solution error	Residual error	Solution error	Residual error
impl.LU	.17E-01	.46E-06	.22E-04	.74E-06
algorithm[3]	.43E-01	.72E-06	.69E-04	.10E-05
block impl.LU (b) $n_b = 2$.18E-02	.61E-06	.24E-03	.11E-05
block impl.LU (c) $n_b = 2$.61E-02	.53E-06	.10E-03	.11E-05
block impl.LU (d) $n_b = 2$.32E-02	.72E-06	.16E-03	.21E-05
block impl.LU (b) $n_b = 5$.21E-01	.66E-06	.94E-04	.12E-05
block impl.LU (c) $n_b = 5$.81E-02	.55E-06	.15E-03	.10E-05
block impl.LU (d) $n_b = 5$.27E-04	.71E-06	.12E-03	.17E-05
block impl.LU (b) $n_b = 10$.84E-02	.14E-05	.14E-03	.12E-05
block impl.LU (c) $n_b = 10$.42E-01	.55E-06	.16E-03	.12E-05
block impl.LU (d) $n_b = 10$.19E-01	.12E-05	.16E-03	.14E-05
block impl.LU (b) $n_b = 20$.87E-02	.41E-05	.20E-03	.12E-04
block impl.LU (c) $n_b = 20$.25E-01	.71E-06	.51E-04	.12E-05
block impl.LU (d) $n_b = 20$.31E-02	.65E-06	.52E-04	.14E-05
block impl.LU (b) $n_b = 50$.11E-01	.27E-04	.21E-03	.24E-04
block impl.LU (c) $n_b = 50$.28E-01	.74E-06	.47E-04	.13E-05
block impl.LU (d) $n_b = 50$.28E-01	.74E-06	.55E-04	.15E-05
impl.LU	.32E-03	.52E-06	.79E-03	.86E-06
algorithm[3]	.17E-04	.61E-06	.60E-03	.13E-05
block impl.LU (b) $n_b = 2$.21E-04	.63E-06	.10E-02	.10E-05
block impl.LU (c) $n_b = 2$.25E-03	.63E-06	.24E-03	.99E-06
block impl.LU (d) $n_b = 2$.81E-03	.79E-06	.84E-04	.19E-05
block impl.LU (b) $n_b = 5$.23E-03	.84E-06	.52E-03	.11E-05
block impl.LU (c) $n_b = 5$.74E-03	.61E-06	.65E-03	.11E-05
block impl.LU (d) $n_b = 5$.88E-05	.65E-06	.22E-03	.19E-05
block impl.LU (b) $n_b = 10$.48E-03	.68E-05	.61E-03	.11E-05
block impl.LU (c) $n_b = 10$.43E-03	.56E-06	.31E-03	.11E-05
block impl.LU (d) $n_b = 10$.80E-03	.81E-06	.50E-03	.19E-05
block impl.LU (b) $n_b = 20$.31E-03	.60E-04	.22E-03	.15E-05
block impl.LU (c) $n_b = 20$.99E-04	.64E-06	.61E-03	.11E-05
block impl.LU (d) $n_b = 20$.48E-03	.72E-06	.40E-03	.17E-05
block impl.LU (b) $n_b = 50$.30E-03	.16E-03	.22E-03	.49E-05
block impl.LU (c) $n_b = 50$.86E-04	.54E-06	.44E-04	.14E-05
block impl.LU (d) $n_b = 50$.86E-04	.54E-06	.43E-04	.17E-05
impl.LU	.18E-03	.60E-06	.43E-04	.10E-05
algorithm[3]	.12E-02	.94E-06	.46E-03	.91E-06
block impl.LU (b) $n_b = 2$.41E-03	.80E-06	.87E-04	.11E-05
block impl.LU (c) $n_b = 2$.56E-03	.73E-06	.56E-03	.11E-05
block impl.LU (d) $n_b = 2$.32E-04	.14E-05	.13E-04	.28E-05
block impl.LU (b) $n_b = 5$.12E-02	.71E-05	.29E-03	.98E-06
block impl.LU (c) $n_b = 5$.13E-02	.68E-06	.14E-03	.11E-05
block impl.LU (d) $n_b = 5$.58E-03	.10E-05	.12E-03	.22E-05
block impl.LU (b) $n_b = 10$.36E-03	.69E-05	.25E-03	.12E-05
block impl.LU (c) $n_b = 10$.20E-02	.87E-06	.17E-03	.11E-05
block impl.LU (d) $n_b = 10$.94E-03	.78E-06	.42E-03	.19E-05
block impl.LU (b) $n_b = 20$.14E-02	.16E-04	.28E-03	.16E-05
block impl.LU (c) $n_b = 20$.76E-05	.67E-06	.48E-04	.12E-05
block impl.LU (d) $n_b = 20$.89E-03	.81E-06	.22E-03	.17E-05
block impl.LU (b) $n_b = 50$.98E-03	.39E-04	.18E-03	.76E-05
block impl.LU (c) $n_b = 50$.16E-02	.75E-06	.14E-03	.14E-05
block impl.LU (d) $n_b = 50$.16E-02	.75E-06	.13E-03	.15E-05
impl.LU	.94E-03	.48E-06	.16E-04	.87E-06
algorithm[3]	.11E-02	.54E-06	.61E-03	.90E-06
block impl.LU (b) $n_b = 2$.51E-03	.53E-06	.25E-03	.10E-05
block impl.LU (c) $n_b = 2$.40E-03	.53E-06	.18E-02	.11E-05
block impl.LU (d) $n_b = 2$.29E-03	.89E-06	.24E-03	.21E-05
block impl.LU (b) $n_b = 5$.10E-02	.56E-06	.31E-03	.11E-04
block impl.LU (c) $n_b = 5$.25E-02	.56E-06	.21E-03	.11E-05
block impl.LU (d) $n_b = 5$.49E-03	.71E-06	.78E-03	.18E-05
block impl.LU (b) $n_b = 10$.31E-03	.63E-06	.42E-03	.16E-04
block impl.LU (c) $n_b = 10$.18E-02	.58E-06	.37E-04	.11E-05
block impl.LU (d) $n_b = 10$.24E-03	.55E-06	.12E-03	.18E-05
block impl.LU (b) $n_b = 20$.13E-02	.93E-06	.18E-03	.14E-04
block impl.LU (c) $n_b = 20$.74E-03	.51E-06	.24E-03	.12E-05
block impl.LU (d) $n_b = 20$.59E-03	.71E-06	.41E-03	.19E-05
block impl.LU (b) $n_b = 50$.14E-02	.89E-04	.13E-02	.67E-04
block impl.LU (c) $n_b = 50$.14E-03	.68E-06	.39E-03	.14E-05
block impl.LU (d) $n_b = 50$.14E-03	.68E-06	.40E-03	.16E-05

Table 3 - Test matrices (M3)

Method	dimension n=100		Dimension n=200	
	Solution error	Residual error	Solution error	Residual error
impl.LU	.34E-02	.68E-06	.13E-02	.51E-06
algorithm[3]	.76E-02	.17E-05	.75E-03	.66E-06
block impl.LU (b) $n_b = 2$.22E-01	.37E-06	.10E-02	.93E-06
block impl.LU (c) $n_b = 2$.18E-01	.41E-06	.38E-02	.64E-06
block impl.LU (d) $n_b = 2$.44E-03	.25E-06	.10E-02	.61E-06
block impl.LU (b) $n_b = 5$.22E-01	.28E-05	.96E-03	.97E-06
block impl.LU (c) $n_b = 5$.85E-02	.51E-06	.45E-02	.45E-06
block impl.LU (d) $n_b = 5$.23E-02	.90E-06	.13E-02	.42E-06
block impl.LU (b) $n_b = 10$.89E-02	.43E-05	.63E-03	.45E-06
block impl.LU (c) $n_b = 10$.44E-02	.85E-06	.78E-03	.36E-06
block impl.LU (d) $n_b = 10$.29E-02	.48E-06	.15E-02	.48E-06
block impl.LU (b) $n_b = 20$.10E+00	.32E-04	.41E-02	.30E-05
block impl.LU (c) $n_b = 20$.73E-02	.85E-06	.66E-03	.46E-06
block impl.LU (d) $n_b = 20$.53E-02	.32E-06	.21E-02	.77E-06
block impl.LU (b) $n_b = 50$.22E+00	.52E-03	.48E-02	.14E-04
block impl.LU (c) $n_b = 50$.54E-03	.79E-06	.18E-02	.63E-06
block impl.LU (d) $n_b = 50$.54E-03	.79E-06	.18E-02	.64E-06
impl.LU	.36E-03	.39E-06	.51E-03	.20E-06
algorithm[3]	.33E-03	.20E-06	.91E-03	.59E-06
block impl.LU (b) $n_b = 2$.72E-03	.30E-06	.38E-03	.27E-06
block impl.LU (c) $n_b = 2$.20E-02	.54E-06	.34E-03	.31E-06
block impl.LU (d) $n_b = 2$.53E-04	.14E-06	.29E-03	.32E-06
block impl.LU (b) $n_b = 5$.95E-03	.37E-06	.37E-03	.39E-06
block impl.LU (c) $n_b = 5$.12E-02	.38E-06	.38E-03	.26E-06
block impl.LU (d) $n_b = 5$.41E-04	.11E-06	.24E-03	.22E-06
block impl.LU (b) $n_b = 10$.24E-02	.49E-06	.96E-03	.14E-05
block impl.LU (c) $n_b = 10$.14E-02	.51E-06	.30E-03	.41E-06
block impl.LU (d) $n_b = 10$.15E-03	.21E-06	.35E-03	.18E-06
block impl.LU (b) $n_b = 20$.66E-02	.19E-05	.39E-03	.79E-06
block impl.LU (c) $n_b = 20$.54E-03	.34E-06	.48E-03	.24E-06
block impl.LU (d) $n_b = 20$.20E-03	.48E-06	.24E-03	.17E-06
block impl.LU (b) $n_b = 50$.21E-01	.33E-05	.23E-02	.42E-05
block impl.LU (c) $n_b = 50$.11E-02	.30E-06	.78E-03	.74E-06
block impl.LU (d) $n_b = 50$.11E-02	.30E-06	.78E-03	.74E-06
impl.LU	.10E-02	.25E-06	.53E-02	.39E-06
algorithm[3]	.92E-03	.17E-06	.28E-02	.30E-06
block impl.LU (b) $n_b = 2$.46E-02	.24E-06	.22E-02	.80E-06
block impl.LU (c) $n_b = 2$.53E-03	.38E-06	.86E-02	.83E-06
block impl.LU (d) $n_b = 2$.46E-04	.19E-06	.15E-02	.18E-06
block impl.LU (b) $n_b = 5$.47E-02	.49E-06	.12E-01	.18E-05
block impl.LU (c) $n_b = 5$.31E-02	.30E-06	.47E-02	.54E-06
block impl.LU (d) $n_b = 5$.26E-03	.15E-06	.14E-02	.47E-06
block impl.LU (b) $n_b = 10$.37E-02	.69E-06	.98E-02	.25E-05
block impl.LU (c) $n_b = 10$.24E-02	.29E-06	.26E-02	.32E-06
block impl.LU (d) $n_b = 10$.12E-03	.16E-06	.20E-02	.32E-06
block impl.LU (b) $n_b = 20$.18E-02	.27E-05	.43E-01	.37E-05
block impl.LU (c) $n_b = 20$.39E-02	.23E-06	.19E-02	.36E-06
block impl.LU (d) $n_b = 20$.44E-03	.13E-06	.21E-02	.69E-06
block impl.LU (b) $n_b = 50$.47E+00	.29E-04	.22E+00	.29E-04
block impl.LU (c) $n_b = 50$.95E-02	.32E-06	.23E-02	.33E-06
block impl.LU (d) $n_b = 50$.95E-02	.32E-06	.23E-02	.33E-06
impl.LU	.21E-01	.23E-06	.82E-01	.37E-06
algorithm[3]	.13E-01	.27E-06	.56E-01	.15E-06
block impl.LU (b) $n_b = 2$.37E-02	.24E-06	.30E-01	.31E-06
block impl.LU (c) $n_b = 2$.72E-02	.25E-06	.25E-02	.25E-06
block impl.LU (d) $n_b = 2$.42E-03	.21E-06	.72E-01	.11E-06
block impl.LU (b) $n_b = 5$.16E+00	.15E-05	.72E-01	.28E-06
block impl.LU (c) $n_b = 5$.98E-02	.19E-06	.52E-01	.16E-06
block impl.LU (d) $n_b = 5$.11E-02	.12E-06	.43E-01	.16E-06
block impl.LU (b) $n_b = 10$.58E-01	.11E-05	.47E+00	.20E-05
block impl.LU (c) $n_b = 10$.55E-02	.17E-06	.94E-01	.20E-06
block impl.LU (d) $n_b = 10$.32E-02	.13E-06	.73E-01	.29E-06
block impl.LU (b) $n_b = 20$.42E+00	.64E-05	.26E+00	.22E-05
block impl.LU (c) $n_b = 20$.71E-02	.26E-06	.18E-01	.26E-06
block impl.LU (d) $n_b = 20$.79E-02	.26E-06	.32E-01	.17E-06
block impl.LU (b) $n_b = 50$.21E+01	.32E-04	.25E+00	.12E-04
block impl.LU (c) $n_b = 50$.11E-01	.27E-06	.98E-01	.33E-06
block impl.LU (d) $n_b = 50$.11E-01	.27E-06	.98E-01	.33E-06

Table 4 - Test matrices (M4)

Method	Dimension n=100		Dimension n=200	
	Solution error	Residual error	Solution error	Residual error
impl.LU	.69E-05	.11E-06	.19E-04	.12E-06
algorithm[3]	.64E-05	.97E-07	.26E-04	.19E-06
block impl.LU (b) $n_b = 2$.13E-04	.24E-06	.55E-04	.47E-06
block impl.LU (c) $n_b = 2$.13E-04	.16E-06	.52E-04	.27E-06
block impl.LU (d) $n_b = 2$.35E-05	.44E-06	.46E-05	.35E-06
block impl.LU (b) $n_b = 5$.12E-04	.10E-06	.44E-04	.33E-06
block impl.LU (c) $n_b = 5$.82E-05	.16E-06	.67E-04	.46E-06
block impl.LU (d) $n_b = 5$.29E-05	.35E-06	.50E-05	.87E-06
block impl.LU (b) $n_b = 10$.20E-04	.25E-06	.61E-04	.65E-06
block impl.LU (c) $n_b = 10$.18E-04	.65E-06	.92E-04	.12E-05
block impl.LU (d) $n_b = 10$.33E-05	.57E-07	.36E-05	.23E-06
block impl.LU (b) $n_b = 20$.14E-04	.26E-06	.12E-03	.11E-05
block impl.LU (c) $n_b = 20$.15E-04	.14E-06	.10E-03	.57E-06
block impl.LU (d) $n_b = 20$.40E-05	.49E-07	.78E-05	.13E-06
block impl.LU (b) $n_b = 50$.23E-04	.43E-06	.16E-03	.95E-06
block impl.LU (c) $n_b = 50$.13E-04	.21E-06	.46E-04	.85E-06
block impl.LU (d) $n_b = 50$.13E-04	.21E-06	.18E-04	.11E-06
impl.LU	.28E-04	.87E-07	.21E-04	.28E-06
algorithm[3]	.28E-04	.25E-06	.24E-04	.90E-07
block impl.LU (b) $n_b = 2$.38E-04	.36E-06	.62E-04	.31E-06
block impl.LU (c) $n_b = 2$.17E-04	.29E-06	.57E-04	.25E-06
block impl.LU (d) $n_b = 2$.42E-05	.49E-06	.65E-05	.42E-07
block impl.LU (b) $n_b = 5$.13E-04	.11E-06	.67E-04	.26E-06
block impl.LU (c) $n_b = 5$.22E-04	.28E-06	.12E-03	.73E-06
block impl.LU (d) $n_b = 5$.42E-05	.52E-06	.59E-05	.27E-06
block impl.LU (b) $n_b = 10$.32E-04	.12E-06	.98E-04	.40E-06
block impl.LU (c) $n_b = 10$.28E-04	.27E-06	.92E-04	.44E-06
block impl.LU (d) $n_b = 10$.50E-05	.35E-06	.88E-05	.12E-05
block impl.LU (b) $n_b = 20$.58E-04	.84E-06	.11E-03	.15E-05
block impl.LU (c) $n_b = 20$.16E-04	.49E-06	.73E-04	.72E-06
block impl.LU (d) $n_b = 20$.50E-05	.29E-06	.10E-04	.61E-06
block impl.LU (b) $n_b = 50$.23E-03	.28E-05	.97E-04	.41E-06
block impl.LU (c) $n_b = 50$.32E-04	.30E-06	.12E-03	.15E-05
block impl.LU (d) $n_b = 50$.32E-04	.30E-06	.18E-04	.17E-06
impl.LU	.68E-03	.29E-06	.37E-02	.35E-06
algorithm[3]	.37E-03	.13E-06	.14E-02	.11E-06
block impl.LU (b) $n_b = 2$.10E-02	.17E-06	.78E-02	.26E-06
block impl.LU (c) $n_b = 2$.83E-03	.21E-06	.72E-02	.23E-06
block impl.LU (d) $n_b = 2$.28E-03	.13E-06	.16E-02	.20E-06
block impl.LU (b) $n_b = 5$.59E-03	.15E-06	.58E-02	.22E-06
block impl.LU (c) $n_b = 5$.10E-02	.15E-06	.63E-02	.20E-06
block impl.LU (d) $n_b = 5$.33E-03	.19E-06	.22E-02	.26E-06
block impl.LU (b) $n_b = 10$.84E-03	.19E-06	.68E-02	.24E-06
block impl.LU (c) $n_b = 10$.87E-03	.20E-06	.54E-02	.23E-06
block impl.LU (d) $n_b = 10$.32E-03	.22E-06	.19E-02	.39E-06
block impl.LU (b) $n_b = 20$.13E-02	.50E-06	.64E-02	.23E-06
block impl.LU (c) $n_b = 20$.54E-03	.23E-06	.42E-02	.28E-06
block impl.LU (d) $n_b = 20$.32E-03	.22E-06	.15E-02	.22E-06
block impl.LU (b) $n_b = 50$.12E-01	.25E-05	.12E-01	.11E-05
block impl.LU (c) $n_b = 50$.65E-03	.29E-06	.41E-02	.48E-06
block impl.LU (d) $n_b = 50$.65E-03	.29E-06	.14E-02	.53E-06
impl.LU	.49E-03	.15E-06	.20E-02	.22E-06
algorithm[3]	.50E-03	.14E-06	.22E-02	.20E-06
block impl.LU (b) $n_b = 2$.10E-02	.18E-06	.37E-02	.26E-06
block impl.LU (c) $n_b = 2$.88E-03	.16E-06	.42E-02	.24E-06
block impl.LU (d) $n_b = 2$.15E-03	.19E-06	.48E-03	.22E-06
block impl.LU (b) $n_b = 5$.12E-02	.17E-06	.37E-02	.25E-06
block impl.LU (c) $n_b = 5$.13E-02	.18E-06	.34E-02	.25E-06
block impl.LU (d) $n_b = 5$.20E-03	.15E-06	.88E-03	.23E-06
block impl.LU (b) $n_b = 10$.14E-02	.19E-06	.57E-02	.28E-06
block impl.LU (c) $n_b = 10$.11E-02	.17E-06	.34E-02	.26E-06
block impl.LU (d) $n_b = 10$.49E-03	.15E-06	.11E-02	.23E-06
block impl.LU (b) $n_b = 20$.28E-01	.40E-05	.91E-01	.37E-05
block impl.LU (c) $n_b = 20$.87E-03	.21E-06	.35E-02	.26E-06
block impl.LU (d) $n_b = 20$.73E-03	.18E-06	.15E-02	.21E-06
block impl.LU (b) $n_b = 50$.32E+00	.45E-04	.55E+00	.29E-04
block impl.LU (c) $n_b = 50$.82E-03	.15E-06	.36E-02	.24E-06
block impl.LU (d) $n_b = 50$.82E-03	.15E-06	.25E-02	.23E-06

Table 5 - Comparison of solution error

	n_b	imp. LU	algo- rithm [3]	Block implicit					
				LU(b)	LU(c)	LU(d)	LU(b)	LU(c)	LU(d)
				2	2	2	5	5	5
imp.LU			106/9	107/9	113/10	72/10	122/9	115/11	78/10
algorithm [3]		85/9		98/8	108/8	66/6	102/11	106/6	72/7
imp.LU(b)	2	84/9	94/8		92/14	54/12	99/12	92/14	62/10
imp.LU(c)	2	77/10	84/8	94/14		48/14	95/13	95/11	59/7
imp.LU(d)	2	118/10	128/6	134/12	138/14		135/12	127/9	99/10
imp.LU(b)	5	69/9	87/11	89/12	92/13	53/12		95/12	55/10
imp.LU(c)	5	74/11	88/6	94/14	94/11	64/9	93/12		61/11
imp.LU(d)	5	112/10	121/7	128/10	134/7	91/10	135/10	128/11	
imp.LU(b)	10	62/8	70/8	77/10	88/9	58/6	79/10	83/9	58/10
imp.LU(c)	10	73/11	89/9	99/7	105/9	66/9	97/10	90/11	68/10
imp.LU(d)	10	107/11	119/9	126/10	121/8	67/11	123/13	119/11	73/11
imp.LU(b)	20	50/7	58/5	57/8	63/10	43/9	59/8	61/6	42/8
imp.LU(c)	20	70/11	96/7	101/8	93/9	52/10	100/12	102/13	54/11
imp.LU(d)	20	96/12	107/7	105/8	118/7	64/7	119/10	110/9	67/12
imp.LU(b)	50	29/7	42/5	30/11	35/9	20/8	36/10	39/11	19/7
imp.LU(c)	50	79/11	94/8	88/10	96/10	61/7	98/12	89/14	62/10
imp.LU(d)	50	81/11	95/9	91/10	96/10	62/7	99/12	92/12	63/10

		Block implicit								
		LU(b)	LU(c)	LU(d)	LU(b)	LU(c)	LU(d)	LU(b)	LU(c)	LU(d)
		10	10	10	20	20	20	50	50	50
alg.[3]	n_b	130/8	116/11	82/11	143/7	119/11	92/12	164/7	110/11	108/11
		122/8	102/9	72/9	137/5	97/7	86/7	153/5	98/8	96/9
imp.LU(b)	2	113/10	94/7	64/10	135/8	91/8	87/8	159/11	102/10	99/10
imp.LU(c)	2	103/9	86/9	71/8	127/10	98/9	75/7	156/9	94/10	94/10
imp.LU(d)	2	136/6	125/9	122/11	148/9	138/10	129/7	172/8	132/7	131/7
imp.LU(b)	5	111/10	93/10	64/13	133/8	88/12	71/10	154/10	90/12	89/12
imp.LU(c)	5	108/9	99/11	70/11	133/6	85/13	81/9	150/11	97/14	96/12
imp.LU(d)	5	132/10	122/10	116/11	150/8	135/11	121/12	174/7	128/10	127/10
imp.LU(b)	10		79/14	65/8	126/9	80/11	72/9	151/8	82/10	81/10
imp.LU(c)	10	107/14		69/16	127/8	88/14	80/11	149/10	79/13	79/13
imp.LU(d)	10	127/8	115/16		140/8	115/15	112/15	166/6	117/15	117/15
imp.LU(b)	20	65/9	65/8	52/8		62/7	50/9	138/12	56/8	57/8
imp.LU(c)	20	109/11	98/14	70/15	131/7		65/16	161/6	88/13	87/13
imp.LU(d)	20	119/9	109/11	73/15	141/9	119/16		161/6	115/14	113/14
imp.LU(b)	50	41/8	41/10	28/6	50/12	33/6	33/6		32/10	31/10
imp.LU(c)	50	108/10	108/13	68/15	136/8	99/13	71/14	158/10		5/187
imp.LU(d)	50	109/10	108/13	68/15	135/8	100/13	73/14	159/10	8/187	

Table 6 - Comparison of residual error

		imp. LU	algo- rithm [3]	Block implicit					
				LU(b)	LU(c)	LU(d)	LU(b)	LU(c)	LU(d)
	n_b			2	2	2	5	5	5
imp.LU			136/10	149/14	138/16	146/8	162/9	133/10	144/11
algorithm [3]		54/10		99/12	83/13	131/10	125/8	84/16	127/8
imp.LU(b)	2	37/14	89/12		70/21	128/9	130/14	65/18	127/10
imp.LU(c)	2	46/16	104/13	109/21		139/9	137/13	85/18	138/12
imp.LU(d)	2	46/8	59/10	63/9	52/9		88/8	47/9	81/18
imp.LU(b)	5	29/9	67/8	56/14	50/13	104/8		44/15	98/11
imp.LU(c)	5	57/10	100/16	117/18	97/18	144/9	141/15		140/12
imp.LU(d)	5	45/11	65/8	63/10	50/12	101/18	91/11	48/12	
imp.LU(b)	10	12/6	30/9	21/7	15/8	65/11	31/12	13/10	57/11
imp.LU(c)	10	43/13	98/11	98/17	71/23	140/9	120/17	75/22	136/11
imp.LU(d)	10	47/10	70/8	68/10	46/9	110/18	96/9	48/9	97/20
imp.LU(b)	20	7/6	8/7	5/6	4/7	15/8	9/6	4/6	12/8
imp.LU(c)	20	38/12	83/9	78/15	66/13	139/11	121/12	57/15	135/12
imp.LU(d)	20	49/9	74/11	75/9	54/10	127/15	102/10	55/11	121/13
imp.LU(b)	50	4/6	6/6	1/7	2/6	1/7	2/8	4/6	0/6
imp.LU(c)	50	40/13	79/12	85/12	61/14	134/10	111/14	54/15	135/10
imp.LU(d)	50	42/13	80/12	87/12	63/13	135/10	113/14	56/14	136/11

	n_b	Block implicit								
		LU(b)	LU(c)	LU(d)	LU(b)	LU(c)	LU(d)	LU(b)	LU(c)	LU(d)
		10	10	10	20	20	20	50	50	50
imp.LU		182/6	144/13	143/10	187/6	150/12	142/9	190/6	147/13	145/13
alg. [3]		161/9	91/11	122/8	185/7	108/9	115/11	188/6	109/12	108/12
imp.LU(b)	2	172/7	85/17	122/10	189/6	107/15	116/9	192/7	103/12	101/12
imp.LU(c)	2	177/8	106/23	145/9	189/7	121/13	136/10	192/6	125/14	124/13
imp.LU(d)	2	124/11	51/9	72/18	177/8	50/11	58/15	192/7	56/10	55/10
imp.LU(b)	5	157/12	63/17	95/9	185/6	67/12	88/10	190/8	75/14	73/14
imp.LU(c)	5	177/10	103/22	143/9	190/6	128/15	134/11	190/6	131/15	130/14
imp.LU(d)	5	132/11	53/11	83/20	180/8	53/12	66/13	194/6	55/10	53/11
imp.LU(b)	10		19/14	56/7	175/7	26/12	48/7	190/7	31/10	30/9
imp.LU(c)	10	167/14		140/15	187/8	104/18	130/11	190/6	116/16	116/15
imp.LU(d)	10	137/7	45/15		182/8	61/10	71/14	192/6	61/12	59/13
imp.LU(b)	20	18/7	5/8	10/8		4/9	7/8	180/7	5/7	6/6
imp.LU(c)	20	162/12	78/18	129/10	187/9		115/13	192/6	101/13	101/12
imp.LU(d)	20	145/7	59/11	115/14	185/8	72/13		191/6	67/14	66/16
imp.LU(b)	50	3/7	4/6	2/6	13/7	2/6	3/6		1/7	0/7
imp.LU(c)	50	159/10	68/16	127/12	188/7	86/13	119/14	192/7		10/187
imp.LU(d)	50	161/9	69/15	128/13	188/6	87/12	118/16	193/7	3/187	