



## BEST PROXIMITY POINTS FOR GENERALIZED MULTIVALUED CONTRACTIONS IN METRIC SPACES

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*Abstract.* In the present paper, we prove a best proximity point theorem for multivalued non-self-contractive type mappings which is a generalization of recent best proximity point theorems and some famous fixed point theorems.

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### 1. INTRODUCTION

Let  $A, B$  be nonempty subsets of a metric space  $(X, d)$  and  $T : A \rightarrow B$  be a non-self-mapping. Clearly, the set of fixed points of  $T$  can be empty. Therefore, it is of primary importance to seek an element  $x$  that in some sense is closest to  $Tx$ . That is, if there is no solution to the fixed point equation  $Tx = x$ , one tries to determine an approximate solution  $x$  subject to the condition that the distance between  $x$  and  $Tx$  is minimal. A classical best approximation theorem was introduced by Fan [4]. It states that if  $A$  is a non-empty compact convex subset of a Hausdorff locally convex topological vector space  $X$  and  $T : A \rightarrow X$  is a continuous mapping, Then there exists  $x \in A$  such that  $d(x, Tx) = d(Tx, A)$ . Recently, there have been many subsequent extensions of Fan's theorem, see [7, 8, 12] and references therein. A point  $x \in A$  is called a best proximity point for  $T$  if distance of  $x$  to  $Tx$  is equal to the distance of  $A$  to  $B$ . In fact best proximity point theorems have been studied to find necessary conditions such that the minimization problem,

$$\min_{x \in A} d(x, Tx) \tag{1.1}$$

has at least one solution. Investigation of several variants of contractions for the existence of a best proximity point can be found in [2, 3, 5, 9–11, 13, 14].

In this article, we consider a classes of multivalued non-self-mapping which called  $(\phi, \theta)$  contractive mappings and we present some best proximity point theorems for these classes of non-self-mappings in metric spaces.

Let  $A$  and  $B$  be two nonempty subsets of a metric space. We will use the following notations:

$$\begin{aligned} d(A, B) &= \inf\{d(x, y) : x \in A, y \in B\}, \\ A_0 &= \{x \in A : d(x, y) = d(A, B) \text{ for some } y \in B\}, \\ B_0 &= \{y \in B : d(x, y) = d(A, B) \text{ for some } x \in A\}, \\ D(x, B) &= \inf\{d(x, y) : y \in B\}, \quad \forall x \in X, \\ H(A, B) &= \max\{\sup_{x \in A} D(x, B), \sup_{y \in B} D(y, A)\}. \end{aligned}$$

Let  $A$  and  $B$  be nonempty subsets of a metric space  $(X, d)$ . Assume that  $T : A \rightarrow 2^B$  is a multivalued non-self-mapping. A point  $x \in A$  is said to be a fixed point of  $T$  if  $x \in Tx$ . In case  $A \cap B = \emptyset$ , the multifunction  $T$  has not fixed point. Then  $D(x, Tx) > 0$  for all  $x \in A$ . Therefore, we can explore to find necessary conditions so that the minimization problem

$$\min_{x \in A} D(x, Tx) \tag{1.2}$$

has at least one solution. Since  $D(x, Tx) \geq d(A, B)$  for all  $x \in A$ , the optimal solution to the problem (1.2) is obtained in some points of  $A$  for which the value  $d(A, B)$  is attained. A point  $x \in A$  is called a best proximity point of a multivalued non-self-mapping  $T$ , if  $D(x, Tx) = d(A, B)$ . We note that if  $d(A, B) = 0$ , then we get a fixed point of  $T$ .

**Definition 1** ([11]). Let  $(A, B)$  be a pair of nonempty subsets of a metric space  $(X, d)$  with  $A_0 \neq \emptyset$ . Then the pair  $(A, B)$  is said to have the  $P$ -property iff

$$\begin{cases} d(x_1, y_1) = d(A, B) \\ d(x_2, y_2) = d(A, B) \end{cases} \Rightarrow d(x_1, x_2) = d(y_1, y_2),$$

where  $x_1, x_2 \in A$  and  $y_1, y_2 \in B$

**Definition 2** ([15]). Let  $(A, B)$  be a pair of nonempty subsets of a metric space  $(X, d)$  with  $A_0 \neq \emptyset$ . Then the pair  $(A, B)$  is said to have the weak  $P$ -property iff

$$\begin{cases} d(x_1, y_1) = d(A, B) \\ d(x_2, y_2) = d(A, B) \end{cases} \Rightarrow d(x_1, x_2) \leq d(y_1, y_2),$$

where  $x_1, x_2 \in A$  and  $y_1, y_2 \in B$ .

**Definition 3.** We say that  $\varphi : [0, \infty[ \rightarrow [0, \infty[$  is a (c)-comparison function if and only if the following conditions hold:

- (i)  $\varphi$  is a nondecreasing function,
- (ii) for any  $t > 0$ ,  $\sum_{n=0}^{\infty} \varphi^n(t)$  is a convergent series.

In what follows, we will denote:

$$\Theta = \{\theta : [0, +\infty)^4 \rightarrow [0, +\infty) : \\ \theta \text{ is continuous and } \theta(t_1, t_2, t_3, t_4) = 0 \Leftrightarrow t_1 t_2 t_3 t_4 = 0\}.$$

*Example 1.* The following functions belong to  $\Theta$  :

- (1)  $\theta(t_1, t_2, t_3, t_4) = L \min\{t_1, t_2, t_3, t_4\}, L > 0$
- (2)  $\theta(t_1, t_2, t_3, t_4) = t_1 t_2 t_3 t_4,$
- (3)  $\theta(t_1, t_2, t_3, t_4) = \ln(1 + t_1 t_2 t_3 t_4),$
- (4)  $\theta(t_1, t_2, t_3, t_4) = \exp(t_1 t_2 t_3 t_4) - 1.$

The notion of almost  $(\varphi, \theta)$ -contraction for single valued non-self mapping was introduced by Bessem Samet as follows.

**Definition 4** ([10]). A mapping  $T : A \rightarrow B$  is said to be an almost  $(\varphi, \theta)$ -contraction if and only if there exist  $\varphi \in \Phi$  and  $\theta \in \Theta$  such that, for all  $x, y \in A$ ,

$$d(Tx, Ty) \leq \varphi\left(d(x, y)\right) + \theta\left(d(y, Tx) - d(A, B), d(x, Ty) - d(A, B), d(x, Tx) - d(A, B), d(y, Ty) - d(A, B)\right)$$

He proved the following result.

**Theorem 1** ([10]). Let  $A$  and  $B$  be closed subsets of a complete metric space  $(X, d)$  such that  $A_0$  is nonempty. Suppose that  $T : A \rightarrow B$  satisfies the following conditions:

- (i)  $T$  is an almost  $(\varphi, \theta)$ -contraction,
- (ii)  $T(A_0) \subseteq B_0,$
- (iii) the pair  $(A, B)$  has the  $P$ -property.

Then, there exists a unique element  $x^* \in A$  such that

$$d(x^*, Tx^*) = d(A, B)$$

Moreover, for any fixed element  $x_0 \in A_0$ , any iterative sequence  $\{x_n\}$  satisfying

$$d(x_{n+1}, Tx_n) = d(A, B)$$

converges to  $x^*$ .

Now, in the following we defined the notion of  $(\varphi, \theta)$ - contraction for multivalued mappings.

**Definition 5.** A mapping  $T : A \rightarrow 2^B$  is said to be an almost  $(\varphi, \theta)$ -contraction if and only if there exist  $\varphi \in \Phi$  and  $\theta \in \Theta$  such that, for all  $x, y \in A$ ,

$$H(Tx, Ty) \leq \varphi\left(d(x, y)\right) + \theta\left(D(y, Tx) - d(A, B), D(x, Ty) - d(A, B), D(x, Tx) - d(A, B), D(y, Ty) - d(A, B)\right)$$

## 2. MAIN RESULTS

Our first main result is the following theorem.

**Theorem 2.** Let  $A$  and  $B$  be closed subsets of a complete metric space  $(X, d)$  such that  $A_0 \neq \emptyset$  and the pair  $(A, B)$  satisfies the weak P-property. Suppose that  $T : A \rightarrow 2^B$  be a multi-valued almost  $(\varphi, \theta)$ -contraction non-self mapping. If  $T(x)$  is bounded and closed in  $B$  for all  $x \in A$ , and  $T(x_0) \subseteq B_0$  for each  $x_0 \in A_0$ , then  $T$  has a best proximity point in  $A$ .

*Proof.* Select  $x_0 \in A_0$  and  $y_0 \in Tx_0 \subseteq B_0$ . By the definition of the set  $B_0$ , we can find an element  $x_1$  in  $A_0$  such that  $d(x_1, y_0) = d(A, B)$ . If  $y_0 \in Tx_1$ , then  $d(A, B) \leq D(x_1, Tx_1) \leq d(x_1, y_0) = d(A, B)$ , therefore  $D(x_1, Tx_1) = d(A, B)$  and  $x_1$  is a best proximity point of  $T$ . If  $y_0 \notin Tx_1$  and  $q > 1$  be given. Then

$$0 < d(y_0, Tx_1) \leq H(Tx_0, Tx_1) < qH(Tx_0, Tx_1).$$

Hence, there exists  $y_1 \in Tx_1$  such that

$$0 < d(y_0, y_1) < qH(Tx_0, Tx_1) \leq q\varphi\left(d(x_0, x_1)\right) + q\theta\left(D(x_1, Tx_0) - d(A, B), D(x_0, Tx_1) - d(A, B), D(x_0, Tx_0) - d(A, B), D(x_1, Tx_1) - d(A, B)\right)$$

Since  $D(x_1, Tx_0) = d(A, B)$ , we have

$$\begin{aligned} 0 < d(y_0, y_1) &< q\varphi\left(d(x_0, x_1)\right) + q\theta\left(0, D(x_0, Tx_1) - d(A, B), D(x_0, Tx_0) - d(A, B), D(x_1, Tx_1) - d(A, B)\right) \\ &= q\varphi\left(d(x_0, x_1)\right). \end{aligned} \quad (2.1)$$

On the other hand since  $y_1 \in Tx_1 \subseteq B_0$ , there exists  $x_2 \in A_0$  such that  $d(x_2, y_1) = d(A, B)$ . By using the weak P-property of  $(A, B)$  we obtain  $d(x_2, x_1) \leq d(y_0, y_1)$ . Now, put  $t_0 = d(x_0, x_1)$ , then  $t_0 > 0$  and by (2.1) we have  $d(x_1, x_2) < q\varphi(t_0)$ . Since

$\varphi$  is strictly increasing,  $\varphi\left(d(x_1, x_2)\right) < \varphi\left(q\varphi(t_0)\right)$ . Set  $q_1 = \frac{\varphi\left(q\varphi(t_0)\right)}{\varphi\left(d(x_1, x_2)\right)} > 1$ . If

$y_1 \in Tx_2$  then  $x_2$  is a best proximity point of  $T$ . suppose that  $y_1 \notin Tx_2$ , then

$$0 < d(y_1, Tx_2) \leq H(Tx_1, Tx_2) < q_1H(Tx_1, Tx_2).$$

Therefore, there exists  $y_2 \in Tx_2$  such that

$$\begin{aligned} 0 < d(y_2, y_1) &< q_1 H(Tx_2, Tx_1) \\ &\leq q_1 \varphi(d(x_1, x_2)) + q_1 \theta(D(x_2, Tx_1) - d(A, B), D(x_1, Tx_2) \\ &\quad - d(A, B), D(x_1, Tx_1) - d(A, B), D(x_2, Tx_2) - d(A, B)) \end{aligned}$$

Since  $D(x_2, Tx_1) = d(A, B)$ , we have

$$\begin{aligned} 0 < d(y_2, y_1) &< q_1 \varphi(d(x_1, x_2)) + q_1 \theta(0, D(x_1, Tx_2) - d(A, B), D(x_1, Tx_1) \\ &\quad - d(A, B), D(x_2, Tx_2) - d(A, B)) \\ &= q_1 \varphi(d(x_1, x_2)) = \varphi(q\varphi(t_0)). \end{aligned} \tag{2.2}$$

Again, since  $y_2 \in Tx_2 \subseteq B_0$ , there exist  $x_3 \in A_0$  such that  $d(x_3, y_2) = d(A, B)$ . By using the weak P-property of  $(A, B)$  we obtain  $d(x_3, x_2) \leq d(y_2, y_1)$ . Since  $\varphi$  is strictly increasing by using (2.2) we have  $\varphi(d(x_3, x_2)) < \varphi^2(q\varphi(t_0))$ . Set

$q_2 = \frac{\varphi^2(q\varphi(t_0))}{\varphi(d(x_3, x_2))} > 1$ . If  $y_2 \in Tx_3$  then  $x_3$  is a best proximity point of  $T$ . Suppose that  $y_2 \notin Tx_3$  then we have,

$$0 < d(y_2, Tx_3) \leq H(Tx_2, Tx_3) < q_2 H(Tx_2, Tx_3).$$

Then there is  $y_3 \in Tx_3$  such that

$$\begin{aligned} 0 < d(y_3, y_2) &< q_2 H(Tx_3, Tx_2) \leq q_2 \varphi(d(x_3, x_2)) \\ &+ q_2 \theta(D(x_3, Tx_2) - d(A, B), d(x_2, Tx_3) - d(A, B), D(x_3, Tx_3) \\ &\quad - d(A, B), D(x_2, Tx_2) - d(A, B)) \end{aligned}$$

Since  $D(x_3, Tx_2) = d(A, B)$  we have

$$\begin{aligned} 0 < d(y_3, y_2) &< \varphi(d(x_3, x_2)) + q_2 \theta(0, d(x_2, Tx_3) - d(A, B), D(x_3, Tx_3) \\ &\quad - d(A, B), D(x_2, Tx_2) - d(A, B)) \\ &= q_2 \varphi(d(x_3, x_2)) = \varphi^2(q\varphi(t_0)) \end{aligned}$$

By continuing this process, for each  $n \in \mathbb{N}$ , we can find a sequences  $\{x_n\}$  and  $\{y_n\}$  in  $A_0$  and  $B_0$  respectively, such that,

(1)  $y_n \in Tx_n \subseteq B_0$ ,

(2)  $d(x_{n+1}, y_n) = d(A, B)$

$$(3) d(y_{n+1}, y_n) \leq \varphi^n(q\varphi(t_0)).$$

Since  $(A, B)$  satisfies the weak p-property, we conclude that

$$d(x_n, x_{n+1}) \leq d(y_{n-1}, y_n) \quad \forall n \in N$$

we now have

$$d(x_n, x_{n+1}) \leq d(y_{n-1}, y_n) \leq \varphi^{n-1}(q\varphi(t_0))$$

Let  $m > n$ . Then

$$d(x_n, x_m) \leq \sum_{i=n}^{m-1} d(x_i, x_{i+1}) \leq \sum_{i=n}^{m-1} \varphi^{i-1}(q\varphi(t_0))$$

and so  $\{x_n\}$  is a Cauchy sequence in  $A$ . Hence, there exists  $x^* \in A$  such that  $x_n \rightarrow x^*$ . Similarly, by using (3) we can show that the sequence  $\{y_n\}$  in  $B$  is Cauchy and hence is convergent. Suppose that  $y_n \rightarrow y^*$ . By the relation  $d(x_{n+1}, y_n) = d(A, B)$ , for all  $n \in N$ , we conclude that  $d(x^*, y^*) = d(A, B)$ . Now we show that  $y^* \in Tx^*$ . Since  $y_n \in Tx_n$ , we obtain

$$\begin{aligned} & \lim_{n \rightarrow \infty} D(y_n, Tx^*) \\ & \leq \lim_{n \rightarrow \infty} H(Tx_n, Tx^*) \\ & \leq \lim_{n \rightarrow \infty} \left[ \varphi(d(x_n, x^*)) + \theta(D(x^*, Tx_n) \right. \\ & \quad \left. - d(A, B), D(x_n, Tx^*) - d(A, B), D(x_n, Tx_n) - d(A, B), \right. \\ & \quad \left. D(x^*, Tx^*) - d(A, B)) \right] \\ & = 0 + \theta \left( \lim_{n \rightarrow \infty} d(x^*, y_n) - d(A, B), \lim_{n \rightarrow \infty} (D(x_n, Tx^*) \right. \\ & \quad \left. - d(A, B)), \lim_{n \rightarrow \infty} (D(x_n, Tx_n) - d(A, B)), D(x^*, Tx^*) - d(A, B) \right) \\ & = 0 + \theta \left( 0, \lim_{n \rightarrow \infty} (D(x_n, Tx^*) \right. \\ & \quad \left. - d(A, B)), \lim_{n \rightarrow \infty} (D(x_n, Tx_n) - d(A, B)), D(x^*, Tx^*) - d(A, B) \right) \\ & = 0. \end{aligned}$$

Thus, we have

$$\lim_{n \rightarrow \infty} D(y_n, Tx^*) = 0.$$

Hence  $D(y^*, Tx^*) = 0$ . Since  $Tx^*$  is closed, We conclude that  $y^* \in Tx^*$ . Now we have,

$$d(A, B) \leq D(x^*, Tx^*) \leq d(x^*, y^*) = d(A, B),$$

which implies that  $D(x^*, Tx^*) = d(A, B)$ , that is  $x^* \in A$  is a best proximity point of  $T$ . This completes the proof of theorem.  $\square$

Taking  $\varphi(t) = \alpha t$  we have the following result which is an extension of theorem 2.1 in [1].

**Corollary 1.** *Let  $(A, B)$  be a pair of nonempty closed subsets of a complete metric space  $(X, d)$  such that  $A_0 \neq \emptyset$  and  $(A, B)$  satisfies the weak  $P$ -property. Let  $T : A \rightarrow 2^B$  be a multivalued non-self-mapping, for which there exist a constant  $\alpha \in [0, 1)$  and  $\theta \in \Theta$  such that for all  $x, y \in X$*

$$H(Tx, Ty) \leq \alpha d(x, y) + \theta \left( D(y, Tx) - d(A, B), D(x, Ty) - d(A, B), D(x, Tx) - d(A, B), D(y, Ty) - d(A, B) \right)$$

Suppose also that  $T(x)$  is bounded and closed in  $B$  for all  $x \in A$ , and  $T(x_0) \subseteq B_0$  for each  $x_0 \in A_0$ , then  $T$  has a best proximity point in  $A$ .

*Example 2.* Let  $X = \mathfrak{R}$  with the usual metric. Suppose  $A := \{0, 3, 6, 9\}$  and  $B := \{-1, 2, 5, 8\}$ . Then,  $A$  and  $B$  are nonempty and closed subsets of  $X$  and  $A_0 = A$  and  $B_0 = B$ . We note that,  $d(A, B) = 1$ . It is easy to show that the pair  $(A, B)$  has the weak  $P$ -property. Let  $T : A \rightarrow 2^B$  be a mapping defined by  $T0 = \{8\}$  and  $Tx = \{5, 8\}$ , if  $x \neq 0$ . Consider the functions  $\theta(t_1, t_2, t_3, t_4) = t_1 t_2 t_3 t_4$  and  $\varphi(t) = \frac{t}{2}$  for all  $t \geq 0$ . Then  $T$  is  $(\varphi, \theta)$ -multivalued contraction. Thus  $T$  has a best proximity point. Note that  $x = 6$  and  $x = 9$  are best proximity points of  $T$ . It is interesting to note that the non-self mapping  $T$  is not a non-self contraction.

Taking  $B = A$  in Theorem 2, we obtain the following result.

**Corollary 2.** *Let  $(X, d)$  be a complete metric space, and  $A$  be a nonempty and closed subset of  $X$ . Let  $T : A \rightarrow 2^A$  be an almost  $(\varphi, \theta)$ -contraction self-mapping. Then  $T$  has a fixed point  $x \in A$ .*

Taking  $\varphi(t) = \alpha t$  and  $\theta(t_1, t_2, t_3, t_4) = L \min\{t_1, t_2, t_3, t_4\}$ , we obtain from Corollary 2 the following result which is a generalization of Nadler fixed point theorem [6].

**Corollary 3.** *Let  $(X, d)$  be a complete metric space, and  $A$  be a nonempty closed subset of  $X$ . Let  $T : A \rightarrow 2^A$  be a mapping such that there exist  $\alpha \in [0, 1)$  and  $L > 0$  such that, for all  $x, y \in A$ ,*

$$H(Tx, Ty) \leq \alpha d(x, y) + L \min\{D(y, Tx), D(x, Ty), D(x, Tx), D(y, Ty)\}$$

Then  $T$  has a unique fixed point  $x \in A$ .

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