Quasilinearization for fractional differential equations of Riemann-Liouville type

Zhenhai Liu, Rui Wang, and Jing Zhao
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ZHENHAI LIU, RUI WANG, AND JING ZHAO

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Abstract. In this paper, we deal with the quasilinearization for Riemann-Liouville fractional differential equations with two point boundary condition. By establishing a new comparison principle we get a monotone sequence which converges quadratically to the unique solution of the fractional differential equations.

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1. INTRODUCTION

Recently, the theory of fractional differential equations become a hot topic in many fields. It is known that many physical system can be represented more accurately through fractional derivative formulation. There are many fields of applications where we can use the fractional calculus as the mathematical model of systems and processes in the fields of physics, chemistry, aerodynamics, electrodynamics of complex medium, viscoelasticity, heat conduction, electricity mechanics, control theory, and so forth. For more details on the topics one can see for instance, [7–9, 11–13, 15, 16, 20] and the reference therein.

Many authors have studied fractional differential equations from two aspects, one is the theoretical aspects of the existence and uniqueness of solutions [1, 5, 6, 22, 23], the other is the development of analytic and numerical methods for finding solutions. The numerical-analytical technique based on successive approximations leads us the approximate solutions to differential equations. Now, it has been studied widely in the theory of integer differential equations, see for instance [17–19].

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It is well known that the method of quasilinearization \cite{10} offers an approach for obtaining approximate solutions to differential equations. This method not only applies to integer differential equations, but also applies to the fractional differential equations, which combining with the lower and upper solution method enables us to get a monotone sequence which converge quadratically to the solution of the differential equations\cite{2–4, 14, 21}.

In \cite{2, 4}, the authors studied the following Caputo fractional differential equations by using the quasilinearization method:

\begin{equation}
\begin{aligned}
&c D^q_{0+} x(t) = f(t, x(t)), \ t \in J = [t_0, T], \\
&x(t_0) = x_0,
\end{aligned}
\end{equation}

where \(0 < q \leq 1\), \(f \in C(J \times \mathbb{R}, \mathbb{R})\).

Later on, in \cite{3}, Vasundhara Devi and Radhika developed the quasilinearization method for the Caputo fractional impulsive differential systems as:

\begin{equation}
\begin{aligned}
&c D^q_{0+} x(t) = f(t, x(t))), \ t \neq t_k, \\
&x(t_k^+) = I_k (x(t_k)), \ k = 1, 2, \cdots n - 1, \\
&x(t_0) = x_0,
\end{aligned}
\end{equation}

where \(0 < q \leq 1\), \(f \in PC([t_0, T] \times \mathbb{R}, \mathbb{R})\), \(I_k : \mathbb{R} \to \mathbb{R}\). The comparison theorem they used is developed from differential equation.

Motivated by the works mentioned above, we investigate the following nonlinear two point boundary value problem for Riemann-Liouville fractional differential equations:

\begin{equation}
\begin{aligned}
&D^q_{0+} x(t) = f(t, x(t)), \ t \in (0, T], \\
&\tilde{x}(0) = g(\tilde{x}(T)),
\end{aligned}
\end{equation}

where \(J \in [0, T]\), \(\frac{1}{2} < q \leq 1\), \(f \in C(J \times \mathbb{R}, \mathbb{R})\), \(g \in C(\mathbb{R}, \mathbb{R})\) and \(\tilde{x}(0) = r^{1-q} x(t) \Big|_{t=0}, \tilde{x}(T) = r^{1-q} x(t) \Big|_{t=T}\). We develop a new comparison principle and the method of quasilinearization for Riemann-Liouville fractional differential equations.

Significant progresses have been made to the quasilinearization of the Caputo fractional differential equations \cite{2–4}. However, to our best knowledge, the quasilinearization for Riemann-Liouville fractional differential equations is still an untreated topics in the literature and this fact is the motivation of the present work. Our aim in this paper is to provide some suitable sufficient conditions for the existence and uniqueness of solutions and approximate results for Riemann-Liouville fractional differential equations.

This paper is organized as follows. In Section 2, we provide some definitions, lemmas and establish a new comparison principle by integral equations. In Section 3, The lower and upper solutions method and quasilinearization method are used to
construct a monotone sequence which converge uniformly and quadratically to the unique solution of (1.1).

2. Preliminaries

In this section, we introduce some notations, definitions and preliminary facts which are used throughout this paper.

Let \( C_{1-\alpha}(J, R) = \{ x \in C(0, T] : t^{1-\alpha}x(t) \in C[0, T] \} \) with the norm \( \| x \|_{C_{1-\alpha}} = \max_{t \in J} |t^{1-\alpha}x(t)| \). Obviously, the space \( C_{1-\alpha}(J, R) \) is a Banach space. The following definitions can be found from \([8, 16]\):

**Definition 1.** The integral

\[
I_{0+}^\alpha f(t) = \frac{1}{\Gamma(\alpha)} \int_0^t \frac{f(s)}{(t-s)^{1-\alpha}} ds, \quad \alpha > 0,
\]

is called Riemann-Liouville fractional integral of order \( \alpha \), where \( \Gamma \) is the gamma function.

**Definition 2.** For a function \( f(t) \), the Riemann-Liouville derivative of order \( \alpha \) can be written as

\[
D_{0+}^\alpha f(t) = \left( \frac{d}{dt} \right)^n (I_{0+}^{n-\alpha} f(t)) = \frac{1}{\Gamma(n-\alpha)} \frac{d^n}{dt^n} \int_0^t (t-s)^{n-\alpha-1} f(s) ds,
\]

where \( n-1 < \alpha \leq n \).

**Lemma 1** ([8]). Let \( n-1 < \alpha \leq n \) and let \( f_{n-\alpha}(t) = I_{0+}^{n-\alpha} f(t) \) be the fractional integral of order \( n-\alpha \). If \( f(t) \in L(0, T) \) and \( f_{n-\alpha}(t) \in AC^n[0, T] \), then we have the following equality

\[
I_{0+}^\alpha D_{0+}^\alpha f(t) = f(t) - \sum_{i=1}^n \frac{f_{n-\alpha}^{(n-i)}(0)}{\Gamma(\alpha-i+1)} t^{\alpha-i}.
\]

**Lemma 2.** Let \( \sigma \in C_{1-q}(J, R) \). \( x \in C_{1-q}(J, R) \) is a solution of the following linear initial value problem:

\[
\begin{aligned}
D_{0+}^q \ddot{x}(t) &= M \dot{x}(t) + \sigma(t), & t \in (0, T], 0 < q \leq 1, \\
\dot{x}(0) &= N \dot{x}(T) + r, & r \in R,
\end{aligned}
\]

if and only if \( x(t) \) is a solution of the following integral equation:

\[
x(t) = (N \dot{x}(T) + r)t^{q-1} + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} (\sigma(s) + M x(s)) ds,
\]

where \( M, N \) are constants.
Proof. Assume \( x(t) \) satisfies (2.1). From the first equation of (2.1) and Lemma 1, we have
\[
x(t) = \left[ t^{1-q}x(t)\right]_{t=0}^{t} + \frac{I_0^q}{\Gamma(q)}(\sigma(t) + Mx(t)) \\
= (N\bar{x}(T) + r)t^{q-1} + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1}(\sigma(s) + Mx(s))ds.
\]
Conversely, assume that \( x(t) \) satisfies (2.2). It is easy to check that \( x(t) \in C_{1-q}(J, R) \).
Applying the operator \( D_0^q \) to both sides of (2.2), we have
\[
D_0^q x(t) = Mx(t) + \sigma(t).
\]
In addition, by simple calculation, we conclude \( \bar{x}(0) = t^{1-q}x(t)|_{t=0} = N\bar{x}(T) + r \).

Lemma 3. Assume that \( M, N \geq 0 \) are constants and the following inequality holds
\[
N + \frac{MT^q\Gamma(q)}{\Gamma(2q)} < 1, \tag{2.3}
\]
then (1.1) has a unique solution.

Proof. We firstly define an operator \( F : C_{1-q}(J, R) \to C_{1-q}(J, R) \) by
\[
(Fx)(t) = (N\bar{x}(T) + r)t^{q-1} + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1}(\sigma(s) + Mx(s))ds.
\]
It is easy to check that \( t^{1-q}(Fx)(t) \in C(J, R) \). Hence the operator \( F \) is well defined on \( C_{1-q}(J, R) \).
For any \( x, y \in C_{1-q}(J, R) \), we have
\[
\|Fx - Fy\|_{C_{1-q}} \\
= \max_{t \in J}|t^{1-q}[(Fx)(t) - (Fy)(t)]| \\
\leq \max_{t \in J}|N(\bar{x}(T) - \bar{y}(T))| + \max_{t \in J} \frac{t^{1-q}}{\Gamma(q)} \int_0^t (t-s)^{q-1}Ms^{q-1}s^{1-q}|x(s) - y(s)|ds \\
\leq N \|x - y\|_{C_{1-q}} + \max_{t \in J} \frac{MT^{1-q}}{\Gamma(q)} \int_0^t (t-s)^{q-1}s^{1-q}ds \|x - y\|_{C_{1-q}} \\
\leq \left( N + \frac{MT^q\Gamma(q)}{\Gamma(2q)} \right) \|x - y\|_{C_{1-q}}.
\]
According to (2.3) and the Banach fixed point theorem, (1.1) has a unique solution. \( \Box \)
Definition 3. A function \( \alpha_0 \in C_{1-q}(J, R) \) is called a lower solution of (1.1) if
\[
\begin{align*}
D_{0+}^{q} \alpha_0 & \leq \alpha_0(0)t^{q-1} + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} f(s, \alpha_0(s))ds, \\
\alpha_0(0) & \leq g(\alpha_0(T)).
\end{align*}
\]
Analogously, \( \beta_0 \in C_{1-q}(J, R) \) is called an upper solution of (1.1) if
\[
\begin{align*}
D_{0+}^{q} \beta_0 & \geq \beta_0(0)t^{q-1} + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} f(s, \beta_0(s))ds, \\
\beta_0(0) & \geq g(\beta_0(T)).
\end{align*}
\]
In what follows, we assume that \( \alpha_0(t) \leq \beta_0(t), \ t \in (0, T], \ \alpha_0(0) \leq \beta_0(0) \).

Let \( \alpha_0, \beta_0 \) = \{ x \in C_{1-q}(J, R) : \alpha_0(t) \leq x(t) \leq \beta_0(t), \ \forall t \in (0, T], \ \alpha_0(0) \leq \bar{x}(0) \leq \beta_0(0) \} \).

Lemma 4. Suppose that there are two constants \( M, N \geq 0 \) such that
\[
0 \leq f_x(t, \eta(t)) \leq M, \ 0 \leq g'(\eta(T)) \leq N, \ \forall \eta \in [\alpha_0, \beta_0].
\]
If (2.3) holds and \( p(t) \in C_{1-q}(J, R) \) satisfies
\[
\begin{align*}
p(t) & \leq \bar{p}(0)t^{q-1} + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} f_x(s, \eta(s))p(s)ds, \\
\bar{p}(0) & \leq g'(\bar{\eta}(T))\bar{p}(T),
\end{align*}
\]
then \( p(t) \leq 0 \) for all \( t \in (0, T] \) and \( \bar{p}(0) \leq 0 \).

Proof: Suppose that the inequality \( p(t) \leq 0, \ \forall t \in (0, T] \) is not true. So there exists at least a \( t_* \in (0, T] \) such that \( t_*^{1-q}p(t_*) > 0 \). Without loss of generality, we assume that \( t_*^{1-q}p(t_*) = \max\{ t^{1-q}p(t) : t \in (0, T] \} = \rho > 0 \).
Then we have that
\[
\begin{align*}
t_*^{1-q}p(t) & \leq \bar{p}(0) + \frac{t_*^{1-q}}{\Gamma(q)} \int_0^t (t-s)^{q-1} f_x(s, \eta(s))p(s)ds \\
& \leq g'(\bar{\eta}(T))\bar{p}(T) + \frac{t_*^{1-q}}{\Gamma(q)} \int_0^t (t-s)^{q-1} f_x(s, \eta(s))p(s)ds \\
& \leq N\rho + \frac{t_*^{1-q}}{\Gamma(q)} \int_0^t (t-s)^{q-1}s^{q-1} f_x(s, \eta(s))s^{1-q}p(s)ds.
\end{align*}
\]
Let \( t = t_* \), we have
\[
\rho \leq \left( N + \frac{MT^q \Gamma(q)}{\Gamma(2q)} \right) \rho.
\]
So
\[
N + \frac{MT^q \Gamma(q)}{\Gamma(2q)} \geq 1.
\]
Which contradicts (2.3). Hence \( p(t) \leq 0 \) for all \( t \in (0, T] \).
For \( t = 0 \), \( \tilde{p}(T) \leq 0 \), we have that
\[
\tilde{p}(0) \leq g'(\eta(T)) \tilde{p}(T) \leq 0.
\]

\[ \square \]

3. Quasilinearization

In this section, we use the method of quasilinearization to construct a monotone sequence which converge quadratically to the solution of fractional differential equations with two point boundary condition.

**Theorem 1.** Let \( \alpha_0, \beta_0 \) be a lower and upper solutions of (1.1), respectively. Assume that (2.3) holds and that

1. \( 0 \leq g'(\tilde{\eta}(T)) \leq N, 0 \leq g'(x) - g'(y) \leq L_1(x - y), \)
2. \( 0 \leq f_x(t, \eta(t)) \leq M, 0 \leq f_x(t, x) - f_x(t, y) \leq L_2(x - y), \) where \( L_1, L_2 \geq 0, \eta \in [\alpha_0, \beta_0] \) and \( \alpha_0 \leq y \leq x \leq \beta_0. \)
3. \( 1 - \Gamma(q)E_{q,q}(MT^q)N > 0. \)

Then there exist two monotone sequences \( \{\alpha_n\}, \{\beta_n\} \) both of which converge uniformly to the unique solution of (1.1) and the convergence is quadratic.

**Proof.** For any \( \eta \in [\alpha_0, \beta_0] \), consider the following linear fractional differential equation:
\[
\begin{align*}
\dot{x}(t) &= f(t, \eta(t)) + f_x(t, \eta(t))(x(t) - \eta(t)), \\
\dot{\eta}(0) &= g(\tilde{\eta}(T)) + g'(\tilde{\eta}(T))(\tilde{\eta}(T) - \tilde{\eta}(T)).
\end{align*}
\]

Obviously, by Lemma 3, the problem above has a unique solution which satisfies
\[
\begin{align*}
x(t) &= \tilde{x}(0)t^{q-1} + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1}[f(s, \eta(s)) + f_x(s, \eta(s))(x(s) - \eta(s))]ds, \\
\dot{\eta}(0) &= g(\tilde{\eta}(T)) + g'(\tilde{\eta}(T))(\tilde{\eta}(T) - \tilde{\eta}(T)).
\end{align*}
\]

Replacing \( \eta, x \) by \( \alpha_0, \alpha_1 \), respectively, we obtain
\[
\begin{align*}
\alpha_1(t) &= \tilde{\alpha}_1(0)t^{q-1} \\
&\quad + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1}[f(s, \alpha_0(s)) + f_x(s, \alpha_0(s))(\alpha_1(s) - \alpha_0(s))]ds, \\
\tilde{\alpha}_1(0) &= g(\tilde{\alpha}_0(T)) + g'(\tilde{\alpha}_0(T))(\tilde{\alpha}_1(T) - \tilde{\alpha}_0(T)).
\end{align*}
\]

Setting \( p(t) = \alpha_0(t) - \alpha_1(t) \), we obtain that
\[
p(t) = \alpha_0(t) - \alpha_1(t)
\]
\[
\leq \tilde{\alpha}_0(0)t^{q-1} + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} f(s, \alpha_0(s))ds - \tilde{\alpha}_1(0)t^{q-1}
\]
\[
- \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1}[f(s, \alpha_0(s)) + f_x(s, \alpha_0(s))(\alpha_1(s) - \alpha_0(s))]ds
\]

And we have that

\[
\tilde{p}(0) = \tilde{\alpha}_0(0) - \tilde{\alpha}_1(0).
\]

By Lemma 4, we know \( p(t) \leq 0 \) for all \( t \in (0, T] \) and \( \tilde{p}(0) \leq 0 \). So \( t^{1-q} \alpha_0(t) \leq t^{1-q} \alpha_1(t) \) for all \( t \in J \).

Now replacing \( \eta, \alpha \) by \( \beta_0, \beta_1 \), we have that

\[
\tilde{\beta}_1(t) = \tilde{\beta}_1(0) + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} [f(s, \alpha_0(s)) + f_x(s, \alpha_0(s)) (\beta_1(s) - \beta_0(s))] ds,
\]

Similarly, we can get \( t^{1-q} \beta_1(t) \leq t^{1-q} \beta_0(t) \) for all \( t \in J \).

Next we set \( p(t) = \alpha_1(t) - \beta_1(t) \), we can obtain

\[
p(t) = \alpha_1(t) - \beta_1(t)
\]

\[
= \tilde{\alpha}_1(0) t^{q-1} + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} [f(s, \alpha_0(s)) + f_x(s, \alpha_0(s)) (\alpha_1(s) - \alpha_0(s))] ds.
\]

And we have that

\[
\tilde{p}(0) = \tilde{\alpha}_1(0) - \tilde{\beta}_1(0)
\]

By Lemma 4, we know \( p(t) \leq 0 \) for all \( t \in (0, T] \) and \( \tilde{p}(0) \leq 0 \). So \( t^{1-q} \alpha_0(t) \leq t^{1-q} \alpha_1(t) \) for all \( t \in J \).

Hence, we have \( t^{1-q} \alpha_0(t) \leq t^{1-q} \alpha_1(t) \leq t^{1-q} \beta_1(t) \leq t^{1-q} \beta_0(t) \) for all \( t \in J \).

Now suppose that

\[
t^{1-q} \alpha_0(t) \leq t^{1-q} \alpha_{k-1}(t) \leq t^{1-q} \alpha_k(t) \leq t^{1-q} \beta_k(t) \leq t^{1-q} \beta_{k-1}(t) \leq t^{1-q} \beta_0(t).
\]
To show $t^{1-q} \alpha_k(t) \leq t^{1-q} \alpha_{k+1}(t) \leq t^{1-q} \beta_{k+1}(t) \leq t^{1-q} \beta_k(t)$.

It’s easy to get that $\alpha_k(t)$ is the lower solution of (1.1) and $\alpha_{k+1}(t)$ satisfies

\[
\begin{align*}
\alpha_{k+1}(t) &= \alpha_{k+1}(0) t^{1-q} \\
&+ \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} \left[ f(s, \alpha_k(s)) + f_x(s, \alpha_k(s)) (\alpha_{k+1}(s) - \alpha_k(s)) \right] ds,
\end{align*}
\]

\[
\alpha_{k+1}(0) = g(\alpha_k(T)) + g'(\alpha_k(T)) (\alpha_{k+1}(T) - \alpha_k(T)).
\]

So using the above method we can obtain $t^{1-q} \alpha_k(t) \leq t^{1-q} \alpha_{k+1}(t)$.

Similarly, $\beta_k(t)$ is the upper solution of (1.1) and $\beta_{k+1}(t)$ satisfies

\[
\begin{align*}
\beta_{k+1}(t) &= \beta_{k+1}(0) t^{1-q} \\
&+ \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} \left[ f(s, \beta_k(s)) + f_x(s, \beta_k(s)) (\beta_{k+1}(s) - \beta_k(s)) \right] ds,
\end{align*}
\]

\[
\beta_{k+1}(0) = g(\beta_k(T)) + g'(\beta_k(T)) (\beta_{k+1}(T) - \beta_k(T)).
\]

Hence $t^{1-q} \beta_{k+1}(t) \leq t^{1-q} \beta_k(t)$.

To show $t^{1-q} \alpha_{k+1}(t) \leq t^{1-q} \beta_{k+1}(t)$, we set $p(t) = \alpha_{k+1}(t) - \beta_{k+1}(t)$.

\[
p(t) = \alpha_{k+1}(t) - \beta_{k+1}(t) = \alpha_{k+1}(0) t^{1-q}
\]

\[
+ \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} \left[ f(s, \alpha_k(s)) + f_x(s, \alpha_k(s)) (\alpha_{k+1}(s) - \alpha_k(s)) \right] ds - \beta_{k+1}(0) t^{1-q}
\]

\[
- \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} \left[ f(s, \beta_k(s)) + f_x(s, \beta_k(s)) (\beta_{k+1}(s) - \beta_k(s)) \right] ds
\]

\[
\leq \tilde{p}(0) t^{1-q} + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} \left[ f_x(s, \alpha_k(s)) p(s) \right] ds.
\]

Then we have that

\[
\tilde{p}(0) = \alpha_{k+1}(0) - \beta_{k+1}(0)
\]

\[
= g(\alpha_k(T)) - g(\beta_k(T)) + g'(\alpha_k(T)) [\alpha_{k+1}(T) - \alpha_k(T)] - (\beta_{k+1}(T) - \beta_k(T)]
\]

\[
\leq g'(\alpha_k(T)) \tilde{p}(T).
\]

By Lemma 4, we know $t^{1-q} \alpha_{k+1}(t) \leq t^{1-q} \beta_{k+1}(t)$.

By induction, we easily get $\{t^{1-q} \alpha_n\}, \{t^{1-q} \beta_n\}$ which satisfy the relation

\[
t^{1-q} \alpha_0 \leq t^{1-q} \alpha_1 \leq \cdots \leq t^{1-q} \alpha_n \leq \cdots \leq t^{1-q} \beta_n \leq \cdots \leq t^{1-q} \beta_1 \leq t^{1-q} \beta_0.
\]

Obviously, the sequences $\{t^{1-q} \alpha_n\}, \{t^{1-q} \beta_n\}$ are uniformly bounded and equicontinuous. Hence by the Ascoli-Arzela Theorem that the sequences $\{t^{1-q} \alpha_n\}, \{t^{1-q} \beta_n\}$ converge uniformly on $J$ with

\[
\lim_{n \to \infty} t^{1-q} \alpha_n = t^{1-q} \alpha, \quad \lim_{n \to \infty} t^{1-q} \beta_n = t^{1-q} \beta.
\]
Then we can easily show that $\alpha$ and $\beta$ are the solutions of (1.1) in $[\alpha_0, \beta_0]$.

To prove quadratic convergence of $\{t^{1-q} \alpha_n\}, \{t^{1-q} \beta_n\}$ to the solution, we consider

$$p_{k+1} = x - \alpha_{k+1}, \quad r_{k+1} = \beta_{k+1} - x.$$  

We can obtain

$$p_{k+1}(0) = \tilde{x}(0) - \alpha_{k+1}(0)$$

$$= g(\tilde{\alpha}_k(T)) - g(\tilde{\alpha}_k(T)) - g'(\tilde{\alpha}_k(T))(\alpha_{k+1}(T) - \tilde{\alpha}_k(T))$$

$$= g'(\tilde{\theta}(T)) \tilde{p}_k(T) - g'(\tilde{\alpha}_k(T))(\tilde{p}_k(T) - p_{k+1}(T))$$

$$\leq L_1 |\tilde{\theta}(T) - \alpha_k(T)| \tilde{p}_k(T) + g'(\tilde{\alpha}_k(T)) p_{k+1}(T)$$

$$\leq L_1 \| p_k(t) \|_{C_{1-q}}^2 + N \| p_{k+1}(t) \|_{C_{1-q}}.$$  

Then we have that

$$p_{k+1}(t) = x(t) - \alpha_{k+1}(t)$$

$$= p_{k+1}(0)t^{q-1} + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} [f(s, x(s)) - f(s, \alpha_k(s))$$

$$- f_x(s, \alpha_k(s))(\alpha_{k+1}(s) - \alpha_k(s))] ds$$

$$= p_{k+1}(0)t^{q-1} + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} [f_x(s, \alpha_k(s)) p_k(s) - f_x(s, \alpha_k(s)) p_{k+1}(s)$$

$$+ f_x(s, \alpha_k(s)) p_{k+1}(s)) ds$$

$$\leq p_{k+1}(0)t^{q-1} + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} [L_2 \rho(s) - \alpha_k(s)] p_k(s) + M p_{k+1}(s)] ds$$

$$\leq p_{k+1}(0)t^{q-1} + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} [L_2 \rho(s) - \alpha_k(s)] p_k(s) + M p_{k+1}(s)] ds$$

$$\leq p_{k+1}(0)t^{q-1} + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} (L_2 s^{2q-2} \| p_k(t) \|_{C_{1-q}}^2 + M p_{k+1}(s)) ds.$$  

Then using the method of successive approximations we get that

$$p_{k+1}(t) \leq \Gamma(q) p_{k+1}(0)t^{q-1} E_{q,q}(Mt^q)$$  

$$+ L_2 \| p_k(t) \|_{C_{1-q}}^2 \int_0^t (t-s)^{q-1} s^{2q-2} E_{q,q}(M(t-s)^q) ds$$

$$\leq \Gamma(q) E_{q,q}(MT^q)p_{k+1}(0)t^{q-1}$$

$$+ L_2 \| p_k(t) \|_{C_{1-q}}^2 E_{q,q}(M(T)^q) \frac{\Gamma(q) \Gamma(2q-1)}{\Gamma(3q-1)} t^{3q-2}.$$  

$$t^{1-q} p_{k+1}(t) \leq \Gamma(q) p_{k+1}(0) E_{q,q}(MT^q)$$  

$$+ L_2 \| p_k(t) \|_{C_{1-q}}^2 E_{q,q}(M(T)^q) \frac{\Gamma(q) \Gamma(2q-1)}{\Gamma(3q-1)} t^{3q-2}.$$
\[ + L_2 \| p_k(t) \|_{C_{1-q}}^2 E_{q,q}(M(T)^q) \frac{\Gamma(q) \Gamma(2q-1)}{(3q - 1)} T^{2q-1} \]

\[ \leq (L_1 \| p_k(t) \|_{C_{1-q}}^2 + N \| p_{k+1}(t) \|_{C_{1-q}}) E_{q,q}(M(T)^q) \]

\[ + L_2 \| p_k(t) \|_{C_{1-q}}^2 E_{q,q}(M(T)^q) \frac{\Gamma(q) \Gamma(2q-1)}{(3q - 1)} T^{2q-1} \]

\[ = \left( L_1 \Gamma(q) + L_2 \frac{\Gamma(q) \Gamma(2q-1)}{(3q - 1)} T^{2q-1} \right) E_{q,q}(M(T)^q) \| p_k(t) \|_{C_{1-q}}^2 \]

\[ + \frac{1 - \Gamma(q) E_{q,q}(M(T)^q) N}{1 - \Gamma(q) E_{q,q}(M(T)^q) N} \]

where \( E_{q,q}(t) = \sum_{k=0}^{\infty} \frac{e^k}{T(qk+q)} \), \( E_{q,q}(t) = \sum_{k=0}^{\infty} \frac{e^k}{T(qk+q)} \).

\[ \| p_{k+1}(t) \|_{C_{1-q}} \leq \Omega \| p_k(t) \|_{C_{1-q}}^2 \]

Thus we have the estimate

\[ \| p_{k+1}(t) \|_{C_{1-q}} \leq \Omega \| p_k(t) \|_{C_{1-q}}^2 \]

where

\[ \Omega = \frac{L_1 \Gamma(q) + L_2 \frac{\Gamma(q) \Gamma(2q-1)}{(3q - 1)} T^{2q-1}}{1 - \Gamma(q) E_{q,q}(M(T)^q) N} \]

Similarly

\[ \| r_{k+1}(t) \|_{C_{1-q}} \leq \Omega \| r_k(t) \|_{C_{1-q}}^2 \]

\[ \square \]

REFERENCES


Authors’ addresses

**Zhenhai Liu**  
Guangxi Key Laboratory of Hybrid Computation and IC Design Analysis and College of Sciences, Guangxi University for Nationalities, Nanning, Guangxi 530006, P.R. China  
*E-mail address*: zhhliu@hotmail.com

**Rui Wang**  
College of Sciences, Guangxi University for Nationalities, Nanning, Guangxi 530006, P.R. China  
*E-mail address*: 278349201@qq.com

**Jing Zhao**  
College of Sciences, Guangxi University for Nationalities, Nanning, Guangxi 530006, P.R. China  
*E-mail address*: jingzhao1008126.com